

DECtalk DTC01

Programmer Reference Manual

Prepared by Educational Services
of
Digital Equipment Corporation

1st Edition, December 1983
2nd Edition, June 1984
3rd Edition, March 1985

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This equipment generates and uses radio frequency energy and if not installed and used properly, that is, in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception. It has been type tested and found to comply with the limits for a Class B computing device in accordance with the specifications in Subpart J of Part 15 of FCC Rules, which are designed to provide reasonable protection against such interference in a residential installation. Compliance with the FCC Class B technical requirements is dependent upon the use of interconnecting cables specified in the User/Installation manual. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following methods.

- Reorient the receiving antenna.
- Relocate the computer with respect to the receiver.
- Move the computer away from the receiver.
- Plug the computer into a different outlet, so that computer and receiver are on different branch circuits.

If necessary, the user should consult the dealer or an experienced radio/television technician for additional suggestions. The user may find the booklet *How to Identify and Resolve Radio/TV Interference Problems*, prepared by the Federal Communications Commission, helpful. This booklet is available from the U.S. Government Printing Office, Washington, D.C. 20402, Stock No. D64-000-00345-00345-4.

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TELEPHONE COMPANY AND FCC REQUIREMENTS AND RESPONSIBILITIES

FCC regulations require that you provide your local telephone company business office with the following information before you connect DECTalk to the telephone network.

- The particular line(s) to which terminal equipment will be connected (by telephone number)
- The make, model number, and FCC registration number (label on bottom of unit)
- The ringer equivalence for the registered terminal equipment (label on bottom of unit)
- The type of jack needed (if not already installed)

Make: DECTalk

Model: DTC01-AA

FCC Registration: AO994Q-12463-0T-E

Ringer equivalence: 0.3B

Type of jack: USOC RJ11C or USOC RJXA1 for telephone line interference (See the *DECTalk DTC01 Installation Manual*.)

You must also notify the telephone company when you permanently disconnect terminal equipment from telephone line(s).

You may not connect terminal equipment to a party line or coin-operated telephone equipment.

If the telephone or telephone line is already equipped with a jack you should be able to plug in DECTalk without any additional telephone company charge. Otherwise, the telephone company will install a jack, which usually results in a one-time installation charge.

If terminal equipment damages the telephone network, the telephone company can, after notifying the customer, temporarily discontinue service. However, when prior notice is not practical, the telephone company can temporarily discontinue service immediately. In such cases, the telephone company shall:

- Promptly notify customers that service has been discontinued
- Give customers the opportunity to correct the situation
- Inform customers of their right to bring a complaint to the FCC according to Subpart E of Part 68 of FCC Telephone Equipment Rules.

The DECTalk DTC01 unit is classified as terminal equipment.

CANADIAN APPLICATION NOTICE

The Canadian Department of Communications label identifies certified equipment. This certification means that the equipment meets certain telecommunications network protective, operational, and safety requirements. The department does not guarantee the equipment will operate to the user's satisfaction.

Before you install this equipment, make sure it is permissible to be connected to the local telecommunications company's facilities. You must also install the equipment by using an approved connection method. In some cases, the company's inside wiring associated with single line individual service can be extended by a certified jack/plug/cord ensemble (telephone extension cord). Be aware that complying with the above conditions may not prevent degradation of service in some situations. Telecommunications company requirements do not allow you to connect their equipment to customer-provided jacks, except where specified by individual telecommunications company tariffs.

Only authorized Canadian maintenance facilities, designated by the supplier, should repair certified equipment. If you repair or alter certified equipment yourself, or if the equipment malfunctions, the telecommunications company has cause to ask you to disconnect the equipment.

You should ensure (for your own protection) that the electrical ground connections for the power utility, telephone lines, and internal metallic water pipe system, if present, are connected together. This precaution may be particularly important in rural areas.

CAUTION: *Do not try to make such connections yourself, but contact the appropriate electric inspection authority or electrician.*

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INTRODUCTION

This manual describes how to use DECtalk with a host computer. The text explains the escape sequences you can use with DECtalk.

Terminals display information from a computer on a screen or paper; they provide communication with computers through the sense of sight. DECtalk speaks information from a computer in an English-language voice; it provides communication with computers through the sense of hearing.

The *DECtalk DTC01 Owner's Manual* (EK-DTC01-OM) describes how to use DECtalk connected to a terminal. This manual describes how to use DECtalk connected to a host computer.

Chapter 1 describes how DECtalk can communicate with a host computer through computer application programs. The chapter also describes some guidelines for writing applications.

Chapter 2 describes the setup escape sequences that initialize and control the DECtalk environment.

Chapter 3 describes how to use voice commands, send phonemic text to DECtalk, and load the user dictionary.

Chapter 4 describes how DECtalk works when connected to a telephone network.

Chapter 5 describes the maintenance and debugging commands used to test DECtalk.

Chapter 6 provides a detailed application program written in C programming language. You can copy this program.

Chapter 7 provides a sample program written in BASiC-PLUS programming language. You can copy this program.

The appendices summarize the DECtalk escape sequences, the phonemic alphabet used, and the other available DECtalk documentation.

HOW DECtalk PROGRAMMING WORKS **1**

This chapter gives you an overview of DECtalk programming. The chapter has four major sections.

- "Communicating with DECtalk" describes the types of data DECtalk can receive and the operating modes DECtalk uses.
- "Escape Sequences and Control Characters" explains the basic format for entering commands with escape sequences. This section includes a table of the control characters that DECtalk recognizes.
- "DECtalk-Computer Communication" lists some special rules DECtalk follows when processing text. This section describes how escape sequences affect the flow of information between DECtalk, a local terminal, and a computer. The section also describes data synchronization.
- "Developing Your Application" provides some guidelines for writing application dialog and encoding your program.

COMMUNICATING WITH DECtalk

DECtalk is an intelligent peripheral device, so the following guidelines apply.

- You cannot program DECtalk directly. After the initial power-up operations, DECtalk is controlled through a terminal or host computer.
- DECtalk is easy to control, because the internal DECtalk processor is sophisticated enough to process complex operations with simple commands.
- You can select DECtalk's operating characteristics and have DECtalk answer questions (from the host computer) about its status. DECtalk can also inform the host computer of status changes. For example, DECtalk can tell the host computer if a connected telephone has rung.
- DECtalk memory can store some information. For example, DECtalk has an extensive built-in pronunciation dictionary. You can load a user-defined dictionary under computer control.

The following paragraphs describe how DECtalk sends and receives information from the host computer.

Types Of Data

DECtalk can receive two types of data through its communications connector, text and commands.

Text is data that DECtalk will speak. Text consists of English-language sentences, phonemically spelled text, or a combination of both.

Commands are instructions to perform an action. Commands are not spoken by DECtalk.

There are two ways to send commands – with escape sequences or with square brackets []. Some commands you can only send with escape sequences, and some commands you can send both ways.

Escape sequences start with an ESC character, followed by a string of ASCII characters. DECtalk interprets the string as a special command. This manual describes the escape sequence method of sending commands.

Square bracket [] commands let you include speech commands and phonemic text with text information, if MODE SQUARE is on.

The "Mode Selection" section in Chapter 2 describes MODE SQUARE. The *DECtalk DTC01 Owner's Manual* describes square bracket commands and syntax.

Appendix B summarizes both command methods. Figure 1-1 shows the relationship between terminal commands and host commands. This chapter provides more information on escape sequence conventions and format.

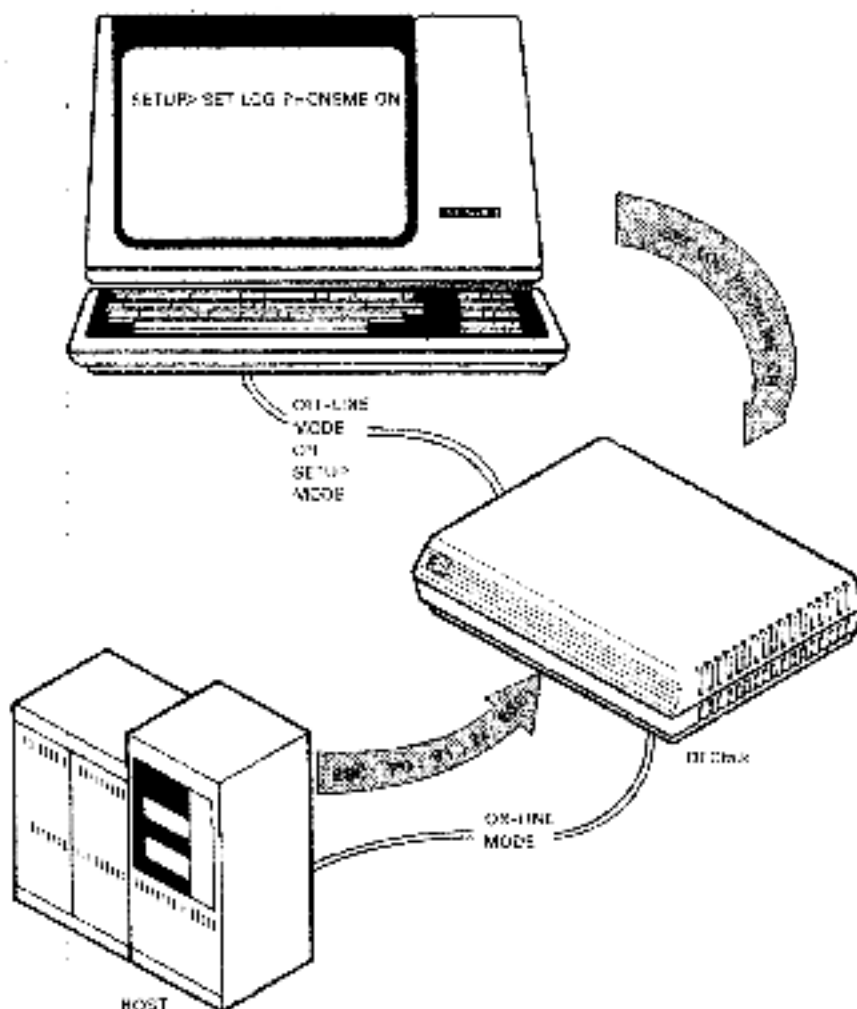


Figure 1-1 DECtalk, Terminal, and Host Communications

Operating Modes

DECTalk has three operating modes: setup, off-line, and on-line.

You use *setup* mode to select the operating parameters of DECTalk, such as communication line characteristics and phonemic representation.

You use *off-line* mode when DECTalk is connected to a terminal. The *DECTalk DTC01 Owner's Manual* describes off-line mode.

You use *on-line* mode when DECTalk is connected to a host computer. Commands must be sent as escape sequences from the host computer.

DECTalk powers up in on-line mode. When you connect DECTalk to a terminal for local use, you must switch DECTalk to off-line mode; press the **BREAK** key to enter setup mode, then select the off-line setting.

USING ESCAPE SEQUENCES AND CONTROL CHARACTERS

This section describes the general syntax of escape sequences, and how to use them with DECTalk.

Escape Sequences

In setup mode, you can enter commands directly to DECTalk through the terminal.

When DECTalk is on-line, you can enter most setup commands plus other on-line commands; however the commands come from the computer instead of the terminal. For example, you can only load the user-defined dictionary while on-line.

On-line and setup commands act the same, but they have different formats. For example, the user command

```
SETUP>SET LOG PHONEME ON
```

is sent from a computer as an escape sequence

```
ESC P 0 : 8 1 : 2 z ESC \
```

You can omit parameters with a value of 0 (ASCII). For example, you could send the above sequence as ESC P : 8 1 : 2 z ESC \. DECTalk does not send parameters with a value of 0 in its reply sequences.

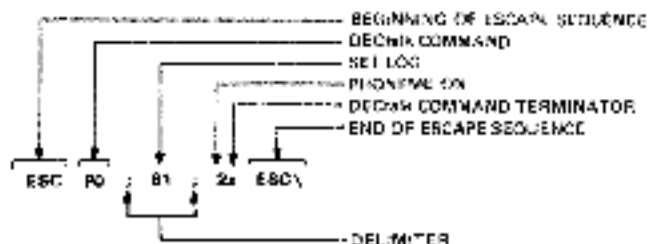
NOTE: Escape sequences in this manual are spaced for clarity only. Spaces are not part of the actual escape sequences.

DECtalk escape sequences have the following characteristics.

1. They begin with an ESC character.
2. The ESC character is followed by ASCII characters that define the command.
3. Every character in the command is important. You must enter the exact characters shown. For example, in the command above, the semicolons are part of the command. The letter z is lowercase; an uppercase Z has no meaning to DECtalk.
4. Programming standards require that you end some commands with a sequence terminator - ESC \. This manual includes ESC \ with all commands that require it.
5. Escape sequences only work on the DECtalk host line. This is different from most terminals, which can interpret typed escape sequences.

The ESC character plus the ASCII characters are like a compressed version of the off-line commands. Figure 1-2 shows the meaning of each part of a typical escape sequence.

DECtalk ignores invalid sequences and commands.



1-1. 780-10.02

Figure 1-2 Typical Escape Sequence Format

Escape Sequence Format

The following chapters describe the specific escape sequences used with DECTalk. This manual includes the following information with all escape sequences (Figure 1-3).

Mnemonic
ASCII characters
Parameters
Decimal value

NOTE: Since DECTalk suppresses parameters with a value of 0, DECTalk would send ESC P ; 31 ; P3 Z ESC \ for the sequence in Figure 1-3 (assuming P3 is not 0). If P3 is 0, DECTalk would send ESC P ; 31 ; z ESC \.

The *mnemonic* is a unique name (such as DT_INDEX) used to identify the escape sequence. Mnemonics do not have any direct programming significance; that is, DECTalk does not recognize a mnemonic name as a valid escape sequence. However, when you refer to escape sequences by mnemonic in program documentation and program variables, it simplifies editing and debugging.

The program examples in Chapter 6 use mnemonics for the appropriate escape sequences. The header file DECTLK.H in Chapter 6 defines all DECTalk command mnemonics.

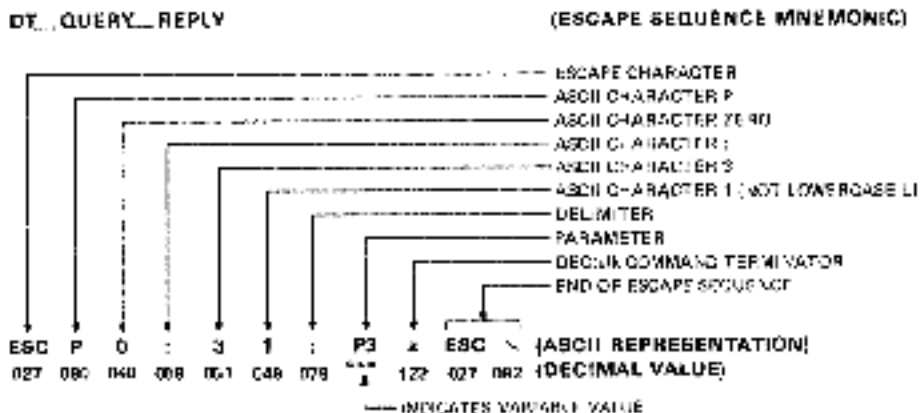


Figure 1-3 Escape Sequence Representations

The *ASCII characters* are the actual characters to use. The "Escape Sequences" section in this chapter gives an example of an escape sequence in ASCII format. The escape character is represented by ESC in all sequences. The numbers that appear are actual ASCII characters, not numeric values.

Parameters appear in escape sequences that can cause several DECTalk actions. These different actions depend on parameter values.

Parameters are represented in this manual by a capital P followed by a number or letter. Parameters are always sent to DECTalk as a decimal number, in ASCII format.

An empty parameter is treated like a parameter with a value of 0. The sequences ESC P ; z and ESC P 0 ; 0 z are identical. *DECTalk always sends a 0 parameter as an empty string.* However, the 0 parameters are always shown as explicit zeros in examples.

This manual lists possible parameter values in tables. There are two methods used to show parameter values.

1. Usually the ASCII character(s) appears (with the decimal value underneath as a check). Use the ASCII character(s) in the escape sequence.
2. Sometimes only a numeric value appears. You must convert the numeric value to a sequence of ASCII characters for the escape sequence.

The *decimal value* of each escape sequence character appears directly under the character, so you can verify the sequence characters. Parameters are marked with asterisks ("*"), indicating that the value is variable.

Chapter 2 provides complete tables of all ASCII characters and their decimal, octal, and hexadecimal equivalents.

Figure 1-3 shows all the parts of an escape sequence.

Control Characters

Some control characters (such as carriage return and backspace) have special meanings. Table 1-1 lists the control characters that DECTalk recognizes. DECTalk ignores any other control characters.

Table 1-1 Control Characters and Host Communications

Character	Mnemonic	Decimal Value	Function
Backspace	BS	008	See "Effect of Backspace (BS) Character" (Chapter 4).
Horizontal tab	HT	009	Same as a space.
Line feed	LF	010	Same as a space.
Vertical tab	VT	011	Clause terminator.
Form feed	FF	012	Same as a space.
Carriage return	CR	013	Same as a space.
Shift out	SO	014	Used in character set selection. See "Selecting Alternate Character Sets" (Chapter 2).
Shift in	SI	015	Used in character set selection. See "Selecting Alternate Character Sets" (Chapter 2).
Substitute	SUB	026	If a communication error occurs, DECtalk replaces the bad character with a SUB character. The SUB character acts as a clause terminator. See "DECtalk On-line Communication" (Chapter 1) for information on clause terminators.
Escape character	ESC	027	Introduces escape sequence.
Space	SP	032	Normal word terminator.

Control Character Logging

Version 2.0 of DECtalk firmware improves control character logging. Before version 2.0, some control characters were not correctly logged. In particular, the CTRL-K (clause flush) control character sequence (generated internally by DECtalk), was not logged unless DECtalk received text from the host in 5 seconds. If a heavily loaded system was slow to respond, DECtalk might not log the current event.

For example, suppose the host system stopped sending data in the middle of a phonemic text string or an escape sequence. DECtalk would execute a timeout, exit phonemic text mode (or ignore the escape sequence), and fail to log the event. The result was problems for the application developer in tracking control character logs.

NOTE: You should enable LOG_INHOST or LOG_RAWHOST to ensure the proper logging of all characters. See "Local Log Control (DT_LOG)" in Chapter 5 for more information on control character logging.

Effect of the Backspace (BS) Character

If DECtalk finds the backspace character in a word, DECtalk modifies the word according to the hierarchy of the characters involved, as follows.

1. letters and digits
2. punctuation
3. underline character

The BS character allows DECtalk to process text containing overstrikes and underlining.

Here are several examples of DECtalk's processing (spaced for clarity).

Input	Pronounced as
a BS _	a
_ BS a	a
a BS b	b
ab BS BS de	de
a BS "	a
a BS " BS _	a

DECTalk-COMPUTER COMMUNICATION

Programming DECTalk is similar to programming a smart terminal (such as a VT220). That is, DECTalk and the host computer must exchange information according to fixed rules.

DECTalk does not process text until reaching a valid clause boundary. Clause boundaries mark the end of phrases or sentences. DECTalk recognizes the following clause boundaries.

- A period, comma, exclamation point, or question mark is a valid boundary. If a period is used, DECTalk checks the characters after the period (because periods do not always mean the end of a sentence).
- A full buffer also acts as a boundary. If DECTalk's temporary buffer begins to approach its fill limit (at about 12 words), DECTalk begins speaking what is in the buffer and treats the last word as a clause boundary.
- A timeout is another boundary. If nothing is sent to DECTalk within 5 seconds and there is text in the buffer, then DECTalk speaks all text in the buffer as though a comma had been sent with the text.

Escape sequences represent (1) commands sent from the host to DECTalk, and (2) status replies sent from DECTalk to the host. All escape sequences begin with the ESC character; a sequence ends when the last character required for that sequence is sent. Do not use a carriage return or any other normal terminating character to terminate an escape sequence.

Figure 1-4 shows the data paths in DECTalk, as follows.

1. The DECTalk unit is in the center of the figure. The speech processor is part of the DECTalk unit, but is shown as a separate module.
2. Arrows show the direction of information flow. Notice that information flows from the terminal (or telephone) to the host, and from the host to the terminal (or telephone). However, information only goes to the speech processor from the host or terminal. Information from the speech processor is sent to the telephone or speaker.
3. Each DECTalk escape sequence affects the flow of information within particular data paths. The switches within the data paths represent the points at which the escape sequences act. For example, the DT_STOP escape sequence affects the data flow from the host to the speech processor.

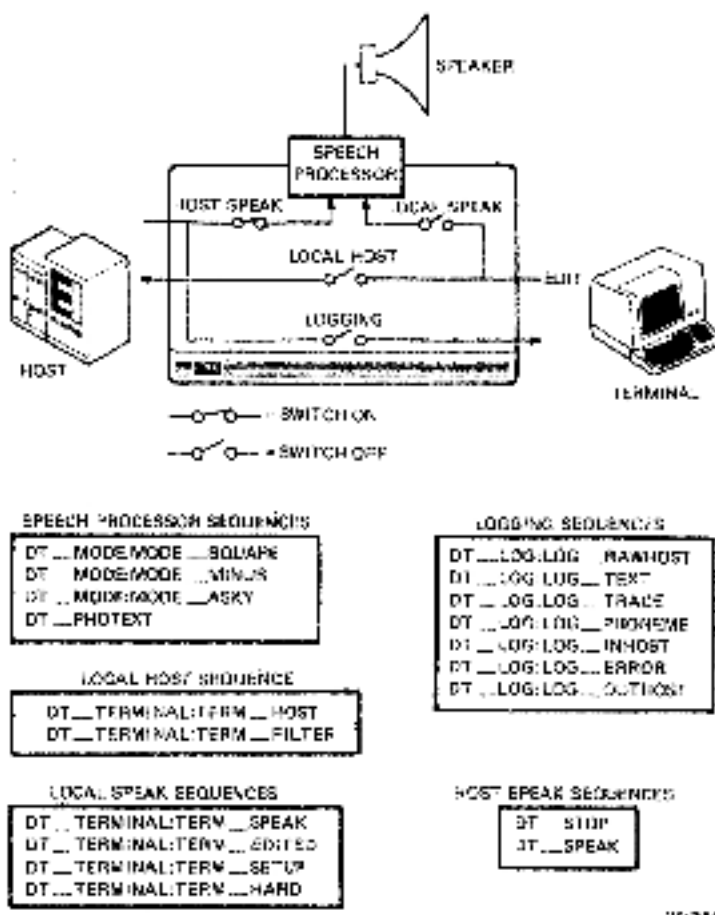


Figure 1-4 DECtalk-Computer Program Interaction

- Since there are a large number of commands and parameters, they are grouped in boxes under the diagram.
- Some commands have parameters (sometimes called arguments). Figure 1-4 shows commands and their parameters. The parameters (if any) appear after a colon (:) mark.

There are many ways to control and use DECtalk when connected to a host computer. The rest of this chapter and the sample program in Chapter 6 describe a general programming method for DECtalk. If you are writing a control program for DECtalk, remember that your application and needs may not match the descriptions that follow exactly.

DECTalk Setups

The controlling program first configures DECTalk to ensure that all parameters are set correctly. Use these steps in your program.

1. Programs may wish to send a "What are you?" sequence to make sure DECTalk is available. DECTalk replies with a code correctly identifying DECTalk.

The "Device Attribute Request" section in Chapter 5 describes "What are you?" sequences.

2. Send setup commands to configure DECTalk for host-DECTalk communication. The required setup commands vary from computer to computer and from application to application; however, here are some commands to consider.
 - a. Include any required communication command (such as 7-bit or 8-bit codes, and code interpretation. See "Selecting ASCII Character Sets" in Chapter 2.
 - b. Set MODE SQUARE on (if desired). This command ensures that phonemic code values are accepted. See "Mode Selection" in Chapter 2.
 - c. If you connect DECTalk to the public telephone network, select the correct telephone handling parameters. See Chapter 4 for these parameters.
3. You may have to set up the host computer (or DECTalk communication line) for DECTalk commands. You must set up the computer for single-character, unsolicited input, and operating system XON/XOFF processing.

Setting up computers is beyond the scope of this manual; however, Chapter 8 has examples of setting up certain Digital Equipment Corporation computers for DECTalk.

If your host computer cannot support single-character processing, you can use the DT_MASK escape sequence to permit line-at-a-time processing. See "Keypad Mask Command (DT_MASK)" in Chapter 5.

4. Other commands depend on the DECTalk environment, such as debugging commands or special text-to-speech commands.

Program Control

DECtalk is primarily a speech device; its internal code is directed towards producing artificial speech. DECtalk assumes the host computer will handle most of the necessary control operations (such as waiting for task completion and requests for status).

The host is responsible for control and coordination, but this is not a major task. The rest of this chapter describes areas you should consider when designing the DECtalk program application.

Data Synchronization

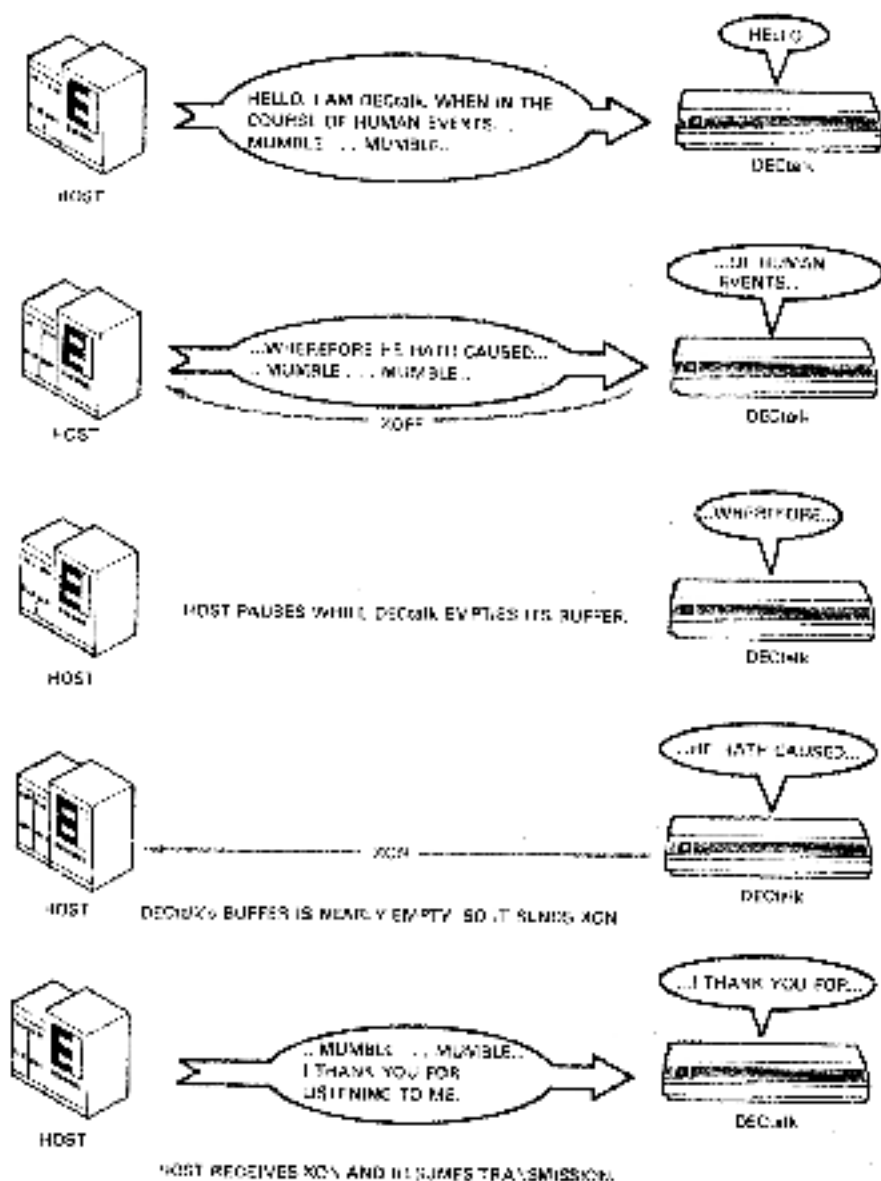
DECtalk's speech rate is much lower than the (potential) data transfer rate on the host communication line. DECtalk sends an XOFF character (CTRL-S) to the host when its input buffer is almost full, to signal that any more input will be discarded. When DECtalk's input buffer is almost empty, it sends an XON character (CTRL-Q); XON tells the host to start sending data again.

The DECtalk input buffer is large enough so that the host can continue sending data at the highest speed (9600 baud) for up to 250 milliseconds after it receives the XOFF, without losing data.

Figure 1-5 shows how DECtalk synchronizes data transfer with the host through XON/XOFF signals.

If the host does not stop sending data in time, the input buffer may overflow and characters may be lost. DECtalk does not give an audible warning of this overflow, except for the obvious garbling of partial words. The host can issue a device status request (DSR) command to determine if an input buffer overflow occurred.

Most operating systems have a HOSTSYNC option (or its equivalent) in the terminal setup characteristics. If this characteristic is set on the DECtalk communications line, the host computer handles XON and XOFF signals. If XON/XOFF coordination is not available, the application program may be able to avoid buffer overflow by using the DT_SYNC command and controlling the program's output rate; however, Digital does not recommend this method because it causes errors. The "Data Synchronization" section in Chapter 3 discusses DT_SYNC.



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Figure 1-5 Synchronizing DECtalk and Host Communications

DECtalk-Host Program Sequence

After you set up a parsing method so data can pass between the host computer and DECtalk, you should set up the host for the kinds of data to receive. How you set up information handling depends on the needs of the user. The following section provides some guidelines for developing your application's dialog.

DEVELOPING YOUR APPLICATION

DECtalk lets people use your computer-based applications from any keypad telephone. DECtalk speaks your messages in an understandable voice. When the user presses keypad keys, DECtalk sends those characters to your program. The following guidelines should help you adapt your application to your unique needs.

General Guidelines

- Keep the user's point of view, not the programmer's. Use commands that are logically related to the way users see the task.
- Most people will not carry a large user guide around with them.
- Frequent users become experts quickly.

Writing Dialog

- Keep dialog simple, but meaningful.
- Organize each message as follows.
 1. Put the hardest element to remember first.
 2. Put the easiest elements to remember in the middle.
 3. Put information for immediate recall at the end.
- Tell users only what they need to know in order to continue a task.
- Do not use humor or threats. Keep dialog strictly factual and informative.

Help Messages and Replies

- Make help messages optional. Let users decide when they want more information.
- Repeat significant phrases in help messages.
- Let users know that DECtalk is acting on their specific commands. For example, say "Sending reply to Ms. Jones," rather than "Sending reply."

Entering Keypad Commands

- Remember, there are only 12 keys on the telephone keypad.
- Keep the same function on the same key.
- Refer to keypad numbers, not letters. People do not remember which letter is on which key. Use "Press 1 for next, 2 for previous, 3 to exit," rather than "Press N for next, P for previous, E for exit."
- Create a standard method for users to exit from a subtask to the main dialog.

Names, Part Numbers, and Alphanumeric Text

In many DECtalk applications, you use the 12 keypad keys to enter a person's name or an alphanumeric part number. Since the application program only receives a string of digits (and the # and * characters), the program must use the digits as an index to the actual data item.

If you are designing a new system, you could specify numeric part numbers only. However, in the real world, a company is not going to change its existing warehouse methods to match DECtalk. So the user will have to enter something that your application can translate into the current system.

Direct Numeric Encoding

Using this method, the user simply presses the key labeled with the desired letter. For example, to select "DIGITAL" the user would press **3444825**. You could assign the letters Q and Z to the 7 (PQRS) and 9 (WXYZ) keys, respectively.

Numeric encoding is a simple method to describe and implement. Since users can recall more than one item for a given digit string, your application must provide a way to select alternatives. You could have users select alternatives by number. Or you could have them step through a list, using next and previous commands.

Numeric encoding is probably the best method for lists of names and for many part number applications. You can even use this method for ID or password entry.

Two-Character Encoding

Some applications use specific letters in their codes (for example, three-character airport codes). You cannot use direct numeric encoding to select specific letters on the keypad.

One possible solution is two-character encoding. This method matches the three letters on each key to the three columns of keys on the keypad. The user presses two keys to select a letter.

1. The key with the desired letter
2. The 1, 2 or 3 key (to select the specific letter)

For example, to select "DEC" the user would press **313223**. You could have users enter numbers together with the **D (OPER)** key. And you could assign the missing **Q** and **Z** (plus the space character) to the **1** key.

The United States Federal Aviation Administration used the above method to provide a voice response weather system. (The USFAA used stored segments of speech - DECtalk was not available at the time.)

Ending Commands and Data

You can use single-character commands and fixed-length data fields for many applications. But for complex applications or variable-length data you may find it simpler to ask the user to end all commands and data by pressing a special key (such as #). Pressing # lets the program know that the right number of characters have been entered.

You could also use DECtalk's flexible keypad timeout facility. If the user is entering a variable-length numeric field, use a long timeout for the first digit and (possibly) a shorter timeout for successive digits.

Application Development Tips

Here are some tips for encoding the application itself.

- Use timeouts for everything. Assume that the user may hang up the phone at any time. Also assume that data entry will be quite slow. This is important when planning data base entry and record-locking strategies.
- The DECtalk applications support library may return an error code due to transient problems (such as a system overload). The simplest recovery is to hang up the call and reinitialize DECtalk. Log the problem for future action.
- People can recall about 5 seconds of text without difficulty. You can use entries such as "1 for yes, 2 for no, 3 for maybe," but do not ask an untrained user to remember anything more complex.
- DECtalk tends to spell out text that may be ambiguous (for example, part numbers). You can write a small filter subroutine that recognizes certain strings and pronounces them in a form more suitable for your specific application.
- If your application accepts data from the telephone keypad, make sure the operating system can buffer type-ahead characters. Also, make sure the operating system responds to DECtalk's XOFFs.
- DECtalk speaks pending text if the host system stops delivering text for 5 seconds. This feature may be a problem on an overloaded system. You may need help from the system manager to obtain more resources or adjust program priorities.
- When you have DECtalk speak information from a data base, remember that the listener hears the information only once. You should offer a *repeat* function for complex subject matter. If you have DECtalk read mail or other unstructured text, you should offer a *back up one sentence* function, using the Index Test command (Chapter 3) to signal what has been heard.

SETUP ESCAPE SEQUENCES **2**

DECtalk has several features you can change to control the operating environment. These parameters include the following.

- line characteristics (such as line speed)
- character sets (to send and receive information)
- modes (to control DECTalk's interpretation of special characters and phonemic text)

There are also several testing and inquiry commands, described in Chapter 5.

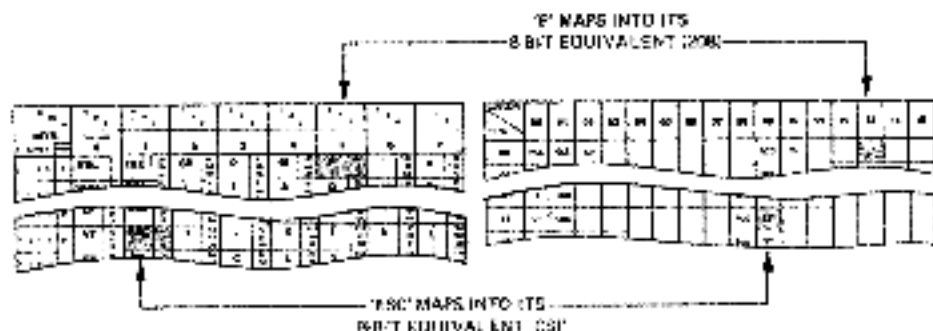
SELECTING ASCII CHARACTER SETS

DECtalk is a computer terminal device, and conforms to the standards for computer terminals.

DECtalk speech does not include much of the visual information of character sets. For example, DECtalk uses the following rules for all character sets.

1. Uppercase and lowercase letters are considered the same. For example, DECtalk speaks the letter G as "gee," not "uppercase gee."
2. Foreign letters (as found in the multinational character set) are spoken as English. For example, DECtalk speaks the letter ä as "a," not "a umlaut."
3. You can translate or map 7-bit codes into 8-bit codes, and 8-bit codes into 7-bit codes (Figure 2-1). This mapping has no effect on spoken text. Table 2-1 gives the escape sequences that change DECtalk to 7-bit or 8-bit modes.

The following paragraphs describe how DECtalk interprets certain keyboard (or host computer) generated codes.



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Figure 2-1 Mapping 7-Bit and 8-Bit Tables

Table 2-1 Selecting 7-Bit or 8-Bit Mode

Mnemonic	Escape Sequence Decimal Value	Function
Transmit		
SDCT	ESC SP 8 027 032 050	Select 7-bit C1 character transmission.
SDCT	ESC SP 9 027 032 051	Select 8-bit C1 control character transmission.
Receive		
DECT01	ESC SP 8 027 032 054	Select 7-bit character reception. The high order (eighth) bit is ignored in all received C1 control characters.
DECT01	ESC SP 9 027 032 055	Select 8-bit C1 control character reception. The high order (eighth) bit is accepted in all received C1 control characters.

CODING STANDARDS

The DTC01 uses an 8-bit character encoding scheme and a 7-bit code extension technique that are compatible with the following ANSI and ISO standards. ANSI (American National Standards Institute) and ISO (International Organization for Standardization) specify the current standards for character encoding used in the communications industry.

Standard	Description
ANSI X3.4 - 1977	American Code for Information Interchange (ASCII)
ISO 646 - 1977	7-Bit Coded Character Set for Information Processing Interchange
ANSI X3.41 - 1974	Code Extension Techniques for Use with the 7-Bit Coded Character Set of American National Code Information Interchange
ISO Draft International Standard 2022.2	7-Bit and 8-Bit Coded Character Sets - Code Extension Techniques
ANSI X3.32 - 1973	Graphic Representation of the Control Characters of American National Code for Information Interchange
ANSI X3.64 - 1979	Additional Controls for Use with American National Standard for Information Interchange
ISO Draft International Standard 8429.2	Additional Control Functions for Character Imaging Devices

CODE TABLE

A code table is a convenient way to represent 7-bit and 8-bit characters, because you can see groupings of characters and their relative codes clearly.

7-Bit ASCII Code Table

Figure 2-2 is the 7-bit ASCII code table. There are 128 positions corresponding to 128 character codes arranged in a matrix of 8 columns and 16 rows.

ROW	COLUMN							
	0	1	2	3	4	5	6	7
BITS								
7 6 5 4 3 2 1 0								
0	0 0 0 0	NUL	DLE	SP	0	@	P	160
1	0 0 0 1	SOH	DC1	!	1	A	Q	161
2	0 0 1 0	STX	DC2	"	2	B	R	162
3	0 0 1 1	ETX	DC3	#	3	C	S	163
4	0 1 0 0	EOT	DC4	\$	4	D	T	164
5	0 1 0 1	ENO	NAK	%	5	E	U	165
6	0 1 1 0	ACK	SYN	&	6	F	V	166
7	0 1 1 1	BEL	ETB	'	7	G	W	167
8	1 0 0 0	BS	CAN	(	8	H	X	168
9	1 0 0 1	HT	EM	)	9	I	Y	169
10	1 0 1 0	LF	SUB	*	:	J	Z	170
11	1 0 1 1	VT	ESC	+	;	K	[	171
12	1 1 0 0	FF	FS	,	<	L	\	172
13	1 1 0 1	CR	GS	-	=	M	]	173
14	1 1 1 0	SO	RS	.	>	N	^	174
15	1 1 1 1	SI	US	/	?	O	_	175

KEY

CHARACTER	ESC	HEX	DECIMAL	ASCII
		1B	27	

Figure 2-2 7-Bit ASCII Code Table

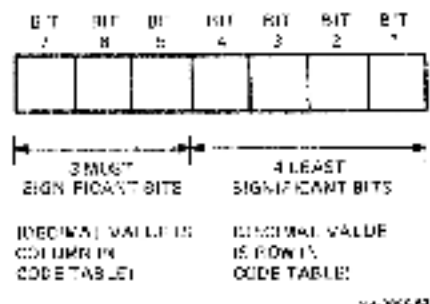


Figure 2-3 7-Bit Code

Each row represents a possible value of the four least significant bits of a 7-bit code (Figure 2-3). Each column represents a possible value of the three most significant bits.

Figure 2-2 shows the octal, decimal, and hexadecimal code for each ASCII character. You can also represent any character by its position in the table. For example, the character H (column 4, row B) can be represented as 4/8.

DECtalk processes received characters based on two character types defined by ANSI, graphic characters and control characters.

Graphic characters are characters you can display on a video screen. The ASCII graphic characters are in positions 2/1 through 7/14 of Figure 2-2. They include alphanumeric characters plus punctuation marks and various text symbols. Examples are C, n, ", !, -, \$.

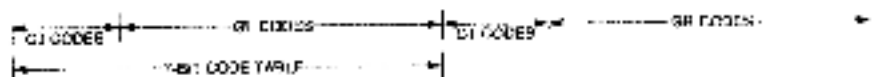
Control characters are not displayed. They are single-byte codes that perform specific functions in data communications and text processing. The ASCII control characters are in positions 0/0 through 1/15 (columns 0 and 1) of Figure 2-2. The SP character (space, 2/0) can be considered either a graphic character or a control character depending on the context. DEL (7/15) is always used as a control character.

Control character codes and functions are standardized by ANSI. Examples of ASCII control characters with their ANSI-standard mnemonics are CR (carriage return), FF (form feed), and CAN (cancel).

8-Bit Code Table

The above conventions can be generalized to the 8-bit character encoding used on DECtalk. Figure 2-4 shows the 8-bit code table. It has twice as many columns as the 7-bit table, because it contains 256 versus 128 code values.

ROW \ COLUMN	00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
00	NUL	SUE	SP							DCS	WT					
01	SOH	DO1								TOP						
02	STX	DO2								PL2						
03	ETX	DC3								SIB						
04	ECT	DO4							INC	DOF						
05	END	NAK							NEL	WW						
06	ACK	SYN							ESA	SPA						
07	DEL	ETB							ESA	EPA						
08	DS	CAN							HTS							
09	HT	EM							HTL							
10	LF	SUB							VTS							
11	VT	ESC							PLD	DBI						
12	FF	PS							PLU	ST						
13	CH	CS							RI	DISC						
14	SO	RO							SRE	PM						
15	S	LT						OEL	ST3	APU						U



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Figure 2-4 8-Bit ASCII Code Table

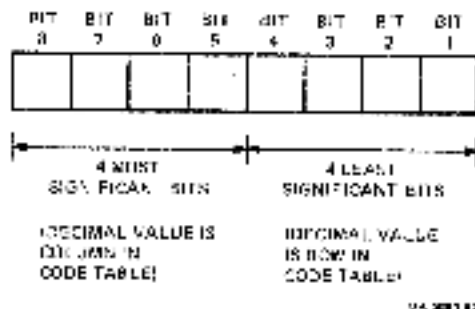


Figure 2-5 8-Bit Code

As with the 7-bit table, each row represents a possible value of the four least significant bits of an 8-bit code (Figure 2-5). Each column represents a possible value of the four most significant bits.

All codes on the left half of the 8-bit table (columns 0 through 7) are 7-bit compatible: their eighth bit is not set and can be ignored or assumed to be 0. You can use these codes in either a 7-bit or an 8-bit environment. All codes on the right half of the table (columns 8 through 15) have their eighth bit set. You can use these codes only in an 8-bit compatible environment.

The 8-bit code table (Figure 2-4) has two sets of control characters, C0 (control zero) and C1 (control one). The table also has two sets of graphic characters, GL (graphic left) and GR (graphic right).

On DECtalk, the basic functions of the C0 and C1 codes are as defined by ANSI. C0 codes represent the ASCII control characters described earlier. The C0 codes are 7-bit compatible. The C1 codes represent 8-bit control characters that let you perform more functions than those possible with the C0 codes. C1 codes can be used directly only in an 8-bit environment. Some C1 code positions are left blank because their functions are not yet standardized.

NOTE: DECtalk only recognizes the SS2, SS3, DCS, CSI, and ST control codes. The others are ignored.

The GL and GR sets of codes are reserved for graphic characters. There are 94 GL codes in positions 2/1 through 7/14 and 94 GR codes in positions 10/1 through 15/14. By ANSI standards, positions 10/0 and 15/15 are not used. You can use GL codes in 7-bit or 8-bit environments. You can use GR codes only in an 8-bit environment.

CHARACTER SETS

You cannot change the functions of the C0 or C1 codes. However, you can map different sets of graphic characters into the GL and/or GR codes. The sets are stored in the terminal. But they are not available for use until mapped into the GL or GR codes.

Selecting Alternate Character Sets (G0 - G3)

DECtalk has four alternate character set areas: G0, G1, G2, and G3. When DECtalk powers up, it loads the ASCII_G (7-bit) character set in alternate buffers G0 and G1. The DEC multinational (8-bit) character set is loaded in alternate buffers G2 and G3.

DECtalk does not call the alternate character sets directly from G0, G1, G2, or G3. The selected set is first mapped into the GL or GR areas, then used to interpret the next received (or transmitted) character. So, three factors determine the active character set.

- Which character area is active: GL or GR
- Which alternate set is mapped into the active area: G0, G1, G2, or G3
- Which character set is loaded in the alternate (G0 or G1) set: ASCII_G or multinational

Figure 2-6 shows how you can map the ASCII_G and multinational sets into the alternate character set buffers. Figure 2-7 shows how you can select active character sets.

Table 2-2 gives the escape sequences and control characters that load and select alternate character sets. Table 2-3 gives the escape sequences to load active character sets into G0 through G3.

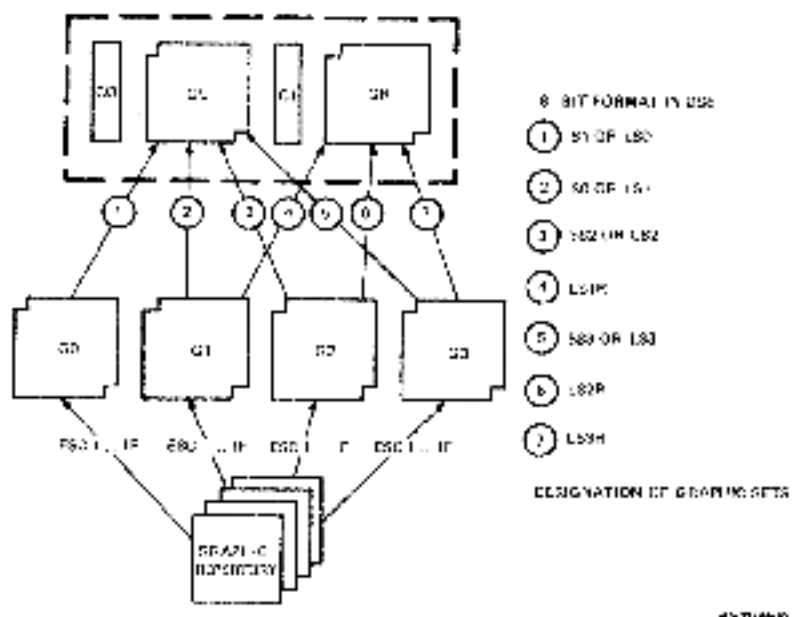


Figure 2-6 Loading 8-Bit Characters

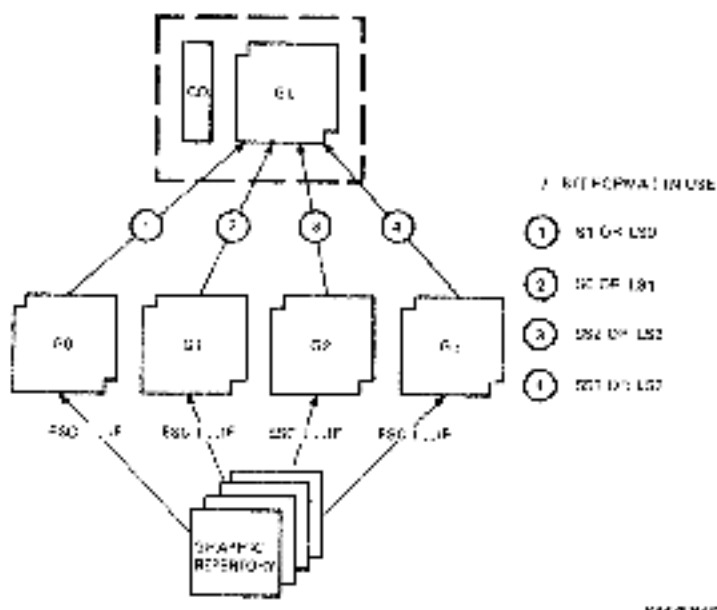


Figure 2-7 Selecting Active Character Sets

Table 2-2. Selecting the Active Character Set

Command	Mnemonic	Escape Sequence	Graphics Set	Table Position
Locking shift 0	LS0	SI 015	G0	GL
Locking shift 1	LS1	SQ 016	G1	GL
Single shift 2	SS2	ESC 027	G2	GL
Single shift 3	SS3	ESC 027	G3	GL
Locking shift 2	LS2	ESC 027	G2	GL
Locking shift 3	LS3	ESC 027	G3	GL
Locking shift 1 right	LS1R	ESC 027	G1	GR
Locking shift 2 right	LS2R	ESC 027	G2	GR
Locking shift 3 right	LS3R	ESC 027	G3	GR

SS2 (single shift 2) and SS3 (single shift 3) are special cases. These commands select the next character value from the G2 or G3 set, respectively, regardless of the setting of the shift key.

Table 2-3. Selecting the Character Set

Character Set	G0	G1	G2	G3
ASCII	ESC [B 027 040 066	ESC [B 027 041 086	ESC * B 027 042 086	ESC + B 027 043 086
Multisymbol	ESC [< 027 040 080	ESC [< 027 041 080	ESC * < 027 042 080	ESC + < 027 043 080

DEC Multinational Character Set

By factory default, when you power up or reset DECTalk, the DEC multinational character set is mapped into the 8-bit code matrix (columns 0 through 15). Figure 2-8 shows the DEC multinational character set.

COL. #	0	1	2	3	4	5	6	7
ROW	0	1	2	3	4	5	6	7
0	NUL	DLE	SP	0	@	P	^	0
1	SOH	DC1	!	1	A	Q	a	q
2	STX	DC2	"	2	B	R	b	r
3	ETX	DC3	#	3	C	S	c	s
4	EOT	DC4	\$	4	D	T	d	t
5	ENO	NAK	%	5	E	U	e	u
6	ACK	SYN	&	6	F	V	f	v
7	BEL	ETB	'	7	G	W	g	w
8	BS	CAN	(	8	H	X	h	x
9	HT	EM	)	9	I	Y	i	y
10	LF	SUB	*	0	J	Z	j	z
11	VT	ESC	+	1	K	[	k	{
12	FF	FS	,	2	L	\	l	
13	CR	GS	-	3	M	]	m	}
14	SO	RS	.	4	N	^	n	~
15	SI	US	/	5	O	_	o	DEL

05 CODES GL CODES (ASCII GRAPHICS)

KEY

CHARACTER ESC 30 DECIMAL
 91 DECIMAL
 1B HEX

Figure 2-8 DEC Multinational Character Set (Left Half)

[illegible]

Figure 2-8 DEC Multinational Character Set (Right Half)

The 7-bit compatible left half of the DEC multinational character set is the ASCII graphics set: the CO codes are the ASCII control characters and the GL codes are the ASCII graphics set.

The 8-bit compatible right half of the DEC multinational character set includes the C1 8-bit control characters in columns 8 and 9. The GR codes are the DEC supplemental graphics character set. The DEC supplemental graphics character set has alphabetic characters with accents and diacritical marks that appear in the major Western European alphabets. It also has other symbols not included in the ASCII graphics character set.

DECtalk removes the accent from characters in the supplemental graphics character set, which are accented versions of characters in the ASCII graphics set. (Naïve is the same as naive.) Other supplemental graphic characters are ignored.

WORKING WITH 7-BIT AND 8-BIT ENVIRONMENTS

To take advantage of DECTalk's 8-bit character set, your program and communication environment must be 8-bit compatible.

Conventions for Codes Transmitted to the Terminal

DECTalk expects to receive character codes in a form consistent with 8-bit coding. Your application can freely use the 8-bit codes as well as the 7-bit code extensions if it has enabled 8-bit controls.

When your program sends GL or GR codes, DECTalk interprets these according to the graphic character mapping currently being used. The factory default mapping, which is set when you power up or reset DECTalk, is the DEC multinational character set.

Mode Selection (DT_MODE)

This sequence acts like the SET MODE command in setup mode. DT_MODE controls how DECTalk handles particular characters in spoken text. The general DT_MODE escape sequence is as follows.

ESC	P	0	;	8	0	;	P3	z	ESC	\
027	080	048	059	056	048	059	~	122	027	092

Use the following method to obtain the P3 value.

1. Add up the values of the MODE flags in Table 2-4 that you want to use.
2. Convert the sum to ASCII digits. Use these digits in place of P3 in the escape sequence.

For example, assume you want to set `MODE_SQUARE` and `MODE_MINUS`, and clear `MODE_ASKY`.

`MODE_SQUARE` - 1
`MODE_MINUS` - 4

Desired P3 value - 5

`ESC P 0 ; 8 0 ; 5 z ESC \`
 027 080 048 059 056 048 059 053 122 027 092

Table 2-4. DTG MODE Parameters

Mnemonic	Value	Function
<code>MODE_SQUARE</code>	1	DECtalk interprets the following graphic characters as commands: { } Define phonetic text strings. [word] You can use a [word] parenthesis immediately before a word to select an alternate pronunciation for certain words, such as read, whose pronunciation depends on usage.
<code>MODE_ASKY</code>	2	DECtalk interprets phonetic text in single-character "asky" ASCII instead of multicharacter "spelled" phonetic mode. This feature determines which phonetic representation is used by DECtalk phonetic logging. See the DECtalk <i>DTG01 Owner's Manual</i> for more information.
<code>MODE_MINUS</code>	4	DECtalk pronounces the hyphen (-) character as "minus." Usually, it is pronounced "dash."

VOICE COMMANDS, PHONEMIC TEXT, AND THE USER DICTIONARY

3

The *DECtalk DTC01 Owner's Manual* describes how to modify the DECtalk voice (using phonemic commands and the phonemic alphabet) from a terminal. This chapter describes a special series of escape sequences that gives a host computer slightly greater control over DECtalk. For example, escape sequences can turn the DECtalk voice on or off and load the user dictionary.

SPEECH CONTROL

There are three ways to control DECtalk speech.

1. *Through English text* (sentences in standard English format and spelling). DECtalk speaks this text as written.
2. *Through phonemic spelling* (sentences or phrases written in phonemic symbols). Phonemic spelling is closer to the actual pronunciation of the text.
3. *Through phonemic commands*. Phonemic commands control features of speech that are not obvious from the visible text, such as rate of speech, sex of the speaker, and excitement level.

SPEECH TIMEOUT

Usually, DECtalk does not begin speaking until the host computer sends a clause terminator (period, comma, exclamation point, or question mark); however, there is a 5-second timeout limit. If the host does not send data within 5 seconds, DECtalk speaks the pending text in its input buffer, as if a comma had been sent.

Programs with long interruptions (such as pauses to search a database) should collect complete sentences before sending anything to DECtalk. Otherwise, this timeout may cause unnatural breaks in sentences and jerky-sounding speech.

ENGLISH TEXT

DECtalk speaks sentences written in standard English, if the text follows three rules.

1. Sentences end with a period, exclamation point, or question mark.
2. All commas, periods, exclamation points, and question marks are followed by a space (or an equivalent character from Table 1-1).
3. A period must be followed by enough text to distinguish between abbreviations and the end of a sentence.

The host computer can send English text in paragraph format; that is, sentences can be broken in the middle by carriage returns.

If a sentence is too long to store in DECtalk's buffers, the sentence is spoken in sections. DECtalk breaks up the sentence and speaks it as if clause boundaries were present; the effect is similar to a person trying to speak a long sentence and running out of breath. Keep sentences down to a reasonable length to avoid this effect.

See the *DECtalk DTC01 Owner's Manual* for more information on speech phrasing and emphasis. The "Data Synchronization" section in this chapter also describes how to coordinate speech and interaction commands to prevent loss of information.

SPEAK PHONEMIC TEXT (DT_PHOTEXT)

When MODE SQUARE is on, you can embed phonemic text in normal text with square brackets. When sending data from the host computer, you can use the DT_PHOTEXT escape sequence as well as the square brackets; MODE SQUARE does not have to be on. The DT_PHOTEXT escape sequence is as follows.

```
ESC P 0 ; 0 z text ESC \
027 080 048 059 048 122 .....027 092
```

ESC P 0 ; 0 z is the same as a left bracket ([), and ESC \ is the same as a right bracket (]). DECtalk uses phonetic speech for all text between the command terminator z and sequence terminator ESC \.

Appendix C lists the phonemic alphabet used by DECtalk. The *DECtalk DTC01 Owner's Manual* describes the alphabet in detail.

Within the phonemic text string, the host computer can transmit comments (for program maintenance) enclosed in /* and */ sequences. (An ESC \ can also terminate any comment.)

For example, in the following sequence the word Hello is a comment.

```
ESC P 0 ; 0 z hx'ehlow /* Hello */ ESC \
```

DECtalk processes a phonemic text escape sequence as though the introducer and terminator were spaces. This means phonemic text cannot replace part of a word.

In addition to transmitting the proper pronunciation, the phonemic text escape sequence can send control phonemes. This example changes the speech rate to 250 words per minute.

```
ESC P 0 ; 0 z :ra250 /* Rate = 250 wpm */ ESC \
```

NOTE: You cannot use STX (CTRL-B) and ETX (CTRL-C) to delimit phonemic text. Use the DT_PHOTEXT escape sequence instead.

STOP SPEAKING (DT_STOP)

This escape sequence immediately stops speech, even if DECTalk is in the middle of a sentence. DT_STOP is useful for stopping speech to perform other actions. For example, the user may press a key to get more instructions, warnings, or shortened versions of explanations (such as lengthy HELP information).

The DT_STOP escape sequence is as follows.

```
ESC P 0 ; 1 0 x ESC \
027 080 048 059 049 048 122 027 092
```

Speech stops immediately and all internal buffers are reinitialized.

DATA SYNCHRONIZATION (DT_SYNC)

The application program can send data to DECTalk faster than DECTalk can speak it. If the user must carry on a dialogue with the application program (through the telephone keypad), the application program should know whether or not DECTalk has finished speaking the text sent to it. DT_SYNC provides this coordination between the application program and DECTalk speech.

When the host sends DT_SYNC, DECTalk finishes speaking any pending text before processing the next command from the host. This ensures that the user hears a message before any other action starts, such as hanging up the phone or starting the phone timeout clock. Note that DT_SYNC acts as a clause boundary, the same as a comma, period, exclamation point, or question mark.

DECTalk considers a section of text to be spoken as soon as the parameters for that section are successfully sent to its signal processing section. Audio output runs approximately 6 milliseconds behind the transmission of the parameters. Applications that switch the audio output of a single DECTalk to a number of sites may need to take this delay into account.

The DT_SYNC escape sequence is as follows.

```
ESC P 0 ; 1 1 x ESC \
027 080 048 059 049 049 122 027 092
```

DT_SYNC does not reply to the host when processing is complete. However, you can do this by following the DT_SYNC command with a DT_INDEX_QUERY command.

ENABLE OR DISABLE SPEAKING (DT_SPEAK)

The DT_STOP sequence stops speech in progress. The DT_SPEAK sequence turns speech processing off or on, so received text is either spoken or discarded. DT_SPEAK is useful if the host computer can recognize such things as electronic mail letterheads and discard them as unnecessary. The host can act as a filter, removing extraneous speech.

The DT_SPEAK escape sequence is as follows.

ESC	P	D	:	1	2	:	P3	z	ESC	\
027	080	048	059	049	050	059	...	122	027	092

If P3 is 0, DECTalk stops speaking text; that is, it stops passing characters received from the host to the text-to-speech processing section. If P3 is not 0, DECTalk resumes speaking.

DECTalk also resumes speaking if the host sends DT_SYNC, DT_STOP, RIS, DECSTR, or DT_PHONE:ph_answer.

INDEXING

Text sent to DECTalk can contain index marks. DECTalk remembers these marks when they are spoken. The host application can listen to the spoken text (by reading the value of the last index) to determine how much transmitted text was actually spoken.

Index markers affect the way numbers and abbreviations are spoken. For example, DECTalk says \$ 12.45 as "twelve dollars and forty-five cents." (The space after the \$ is optional.) If an index marker separates the \$ and 1, then DECTalk says "dollar twelve point four five."

The following paragraphs describe how to mark text and return their values to the application program.

Index Text (DT_INDEX)

This sequence inserts an index marker (flag) in the text stream sent to DECtalk.

The DT_INDEX escape sequence is as follows.

```
ESC   P   0   ;   2   0   ;   P3   z   ESC   \
027  080  048  059  050  048  059  ***  122  027  092
```

The P3 parameter may range from 0 to 32767, sent as the ASCII characters for the number. Numbers outside the range are brought into range by masking off the overflow bits.

For example, the host computer sends the following data stream to DECtalk and marks the second word with the index 15.

Hello ESC P 0 ; 2 0 ; 1 5 z ESC \ there.

After speaking the text before DT_INDEX, DECtalk remembers the value 15. The host may use DT_INDEX_QUERY (described later in this chapter) to get this stored value.

Index Reply (DT_INDEX_REPLY)

DT_INDEX simply marks a position in the text. DT_INDEX_REPLY marks a position, but also has DECtalk inform the host when the index is spoken.

The DT_INDEX_REPLY escape sequence is as follows.

```
ESC   P   0   ;   2   1   ;   P3   z   ESC   \
027  080  048  059  050  049  059  ***  122  027  092
```

The P3 parameter is in the range 0 to 32767, using ASCII characters for the selected number.

When DECtalk speaks the DT_INDEX_REPLY sequence, it sends a reply (containing the P3 parameter of the index) to the host. The escape sequence reply format is as follows.

```
ESC   P   0   ;   3   1   ;   P3   z   ESC   \
027  080  048  059  051  049  059  ***  122  027  092
```

P3 has the original value specified in DT_INDEX_REPLY.

Index Query (DT_INDEX_QUERY)

DT_INDEX_QUERY requests DECTalk to reply to the host with the last index marker spoken (that is, the last portion of spoken text that had an index marker). The DT_INDEX_QUERY escape sequence is as follows.

```
ESC P 0 ; 2 2 z ESC \
027 080 048 059 050 050 122 027 092
```

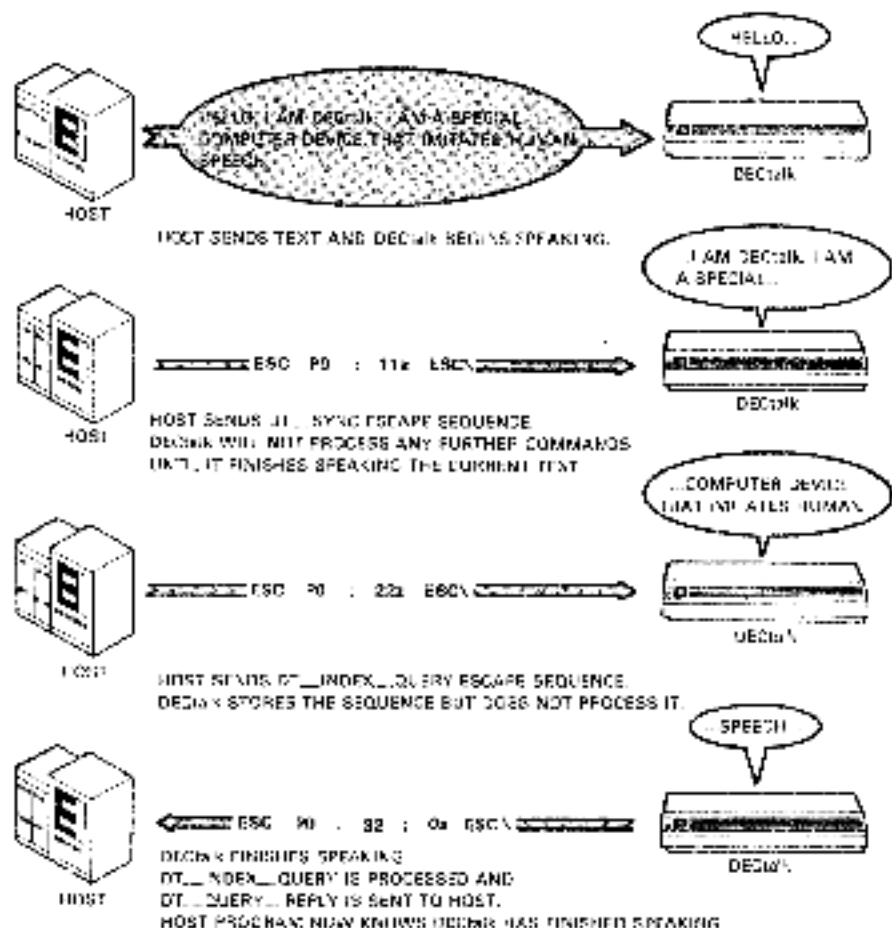
DECTalk immediately returns a DECTalk reply escape sequence to the host in the following format.

```
ESC P 0 ; 3 2 ; P3 z ESC \
027 080 048 059 051 050 059 "" 122 027 092
```

P3 contains the last index spoken. The P3 value is ASCII 0 under any of the following conditions.

- The last index passed was ASCII 0.
- No index has been passed yet.
- No index has been marked in the text; that is, the host has not sent a DT_INDEX or DT_INDEX_REPLY sequence.

Figure 3-1 shows how DT_SYNC and DT_INDEX_QUERY can coordinate host-DECTalk communications.



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Figure 3-1 Using DT_SYNC and DT_INDEX_QUERY to Coordinate Communications

LOAD DICTIONARY (DT_DICT)

The user dictionary is used for processing abbreviations, and for providing phonemic equivalents of unusual words. The **DT_DICT** escape sequence is as follows.

```
ESC P 0 ; 4 0 z name substitution ESC \
027 080 048 059 052 048 122 ..... 027 092
```

Whenever the word represented by "name" appears in the input text, the phonemic pronunciation given by "substitution" is used.

Any uppercase characters in the name only match uppercase characters in the input text. Lowercase characters in the name match both uppercase and lowercase characters in the input text. DECtalk always searches dictionary entries in the order entered.

If a name ends with a period (.), a period must follow the word in running input text. This period is included as part of the word, and is not recognized as a sentence terminator.

Here are some examples of dictionary entries.

```
ESC P 0 ; 4 0 : z ms m'ihz ESC \
ESC P 0 ; 4 0 : z ms. m'ihz ESC \
ESC P 0 ; 4 0 : z DEC d'ehk ESC \
ESC P 0 ; 4 0 : z dec d'iysahmber ESC \
ESC P 0 ; 4 0 : z Goethe g'owth'ly ESC \
ESC P 0 ; 4 0 : z GOSLOW :r# 120 ESC \
```

DECtalk does not recognize an error in phonemic spelling until the word is used. You can use comments in the substitution, but they are not recommended. Note the use of capitalization in the previous examples to distinguish between abbreviations with the same spelling.

If you do not enter a substitution, DECtalk removes the word from the user text dictionary. You cannot remove words from the built-in dictionary.

After loading the word and its definition, DECtalk replies with a dictionary status report.

```
ESC P 0 ; 5 0 ; P3 2 ESC \
027 080 048 059 053 048 059 *** 122 027 082
```

P3 may have one of the following values.

0 048	Word entered correctly.
1 049	No room in dictionary.
2 050	Entry too long (256 characters maximum).

TELEPHONE COMMUNICATIONS 4

You can connect DECtalk to the public telephone system to provide a dial-up link between remote users on telephones and a computer application program. DECtalk sends and receives information as a link between a remote user and the host computer.

DECtalk communicates with the phone through the voice circuits, passing on spoken data to the listener. DECtalk passes information back to the host both as ordinary ASCII characters, and as escape sequences. The user can communicate with the host (through DECtalk) by using the Touch-Tone keypad, if available.

The DT_PHONE escape sequence is the controlling sequence for all telephone operations.

TELEPHONE MANAGEMENT (DT_PHONE)

This escape sequence takes one or more parameters and controls the attached telephone and Touch-Tone keypad interface. The DT_PHONE escape sequence is as follows.

```
ESC P 0 ; 6 0 ; Pn : Pn z text ESC \
027 080 048 059 054 048 059 ^^ 059 ^^ 122 .....027 092
```

The Pn parameters act as a list of telephone management commands and execute in sequence. Table 4-1 lists the valid Pn parameters.

A single DT_PHONE sequence can perform several commands. Some commands can take additional parameters.

All DT_PHONE commands return a status report to the host in the following escape sequence. Table 4-2 lists the valid P3 values.

```
ESC P 0 ; 7 0 ; P3 z ESC \
027 080 048 059 056 048 059 ^^ 122 027 092
```

All telephone management commands return a reply sequence back to the host upon command execution. PH STATUS is only needed to check the telephone status when a DT_PHONE command is not pending. Note that PH ANSWER generates an additional status report when the phone is answered.

Telephone keypad characters are sent as text, not escape sequences.

Note that the R3_PH_TIMEOUT reply sequence is sent when a timeout occurs; that is, the reply sequence may arrive as unrequested input, and the application program must be ready to receive it.

Table 4-1 BT_PHONE Parameters

Mnemonic	ASCII Code Decimal Value	Function
PH_STATUS	0 048	Send a telephone status report
PH_ANSWER	1 0 049 048	Enable autoanswer of the telephone
PH_HANDUP	1 1 049 049	Hang up the telephone and disable the keypad
PH_KEYPAD	2 0 050 048	Enable the keypad and select direct keypad-dialing
PH_NOKEYPAD	2 1 050 049	Disable the keypad (without hanging up the telephone)
PH_TIMEOUT	3 0 051 048	Enable timeouts on telephone keypad input. Timeout equals P4 parameter value
PH_TONE_DIAL	4 0 052 048	Dial an outgoing phone call using Touch-Tones
PH_PULSE_DIAL	4 1 052 049	Dial an outgoing phone call using pulse-dialing

Table 4-2 Phone Status Reply Codes

Mnemonic	ASCII Code Decimal Value	Function
R3_PH_ONHOOK	0 048	Telephone is on-hook (hung up)
R3_PH_OFFHOOK	1 049	Telephone is off-hook (active)
R3_PH_TIMEOUT	7 050	No response after TIMEOUT command
R3_PH_TOOLONG	3 051	Number dialed is longer than 255 characters

PH_ANSWER

DECTalk is set up to answer incoming phone calls. The parameter that follows the PH_ANSWER parameters indicates the number of rings to wait before answering the telephone. A parameter of 0 or 1 means answer the telephone after the first ring; 2 means answer after 2 rings, and so on.

If the telephone is off-hook when the host sends a PH_ANSWER parameter, DECTalk hangs up the telephone (disconnects any active call) before executing the PH_ANSWER command.

DECTalk sends two status replies to a PH_ANSWER request. The first status reply informs the host that the DT_PHONE command was correctly received. The second reply informs the host that the telephone has actually been answered.

DECTalk stops waiting for incoming calls whenever the host sends PH_HANGUP, PH_TONE_DIAL, PH_PULSE_DIAL, RIS, or DECSTR.

PH_HANGUP

This command hangs up the telephone. The status reply is delayed until the telephone is back on-hook (disconnected). The host should wait for the R3_PH_ONHOOK reply before sending other commands to DECTalk.

PH_KEYPAD

This command enables the telephone keypad. The request is ignored if the phone is inactive (on-hook); however, DECTalk returns an R3_PH_ONHOOK status reply.

PH_NOKEYPAD

This command disables the telephone keypad, but maintains the phone connection. This request is ignored if the phone is inactive (on-hook); however, DECTalk returns an R3_PH_ONHOOK status reply.

PH_TIMEOUT

This command starts (or restarts) an internal DECTalk timer. If the user does not press a telephone keypad button within the timeout interval, an R3_PH_TIMEOUT status is returned (Table 4-2).

The application program should set PH_KEYPAD on before sending a PH_TIMEOUT command; otherwise, the user cannot respond to DECTalk requests for input.

The parameter following **PH_TIMEOUT** is the number of seconds to wait for a response from the caller. A parameter of 0 cancels any active timeouts. After a timeout, the timer is stopped. The application program must send a new **PH_TIMEOUT** command to restart the timer.

Timeouts are the only way to detect that the caller has hung up the telephone.

The public telephone system in your country may have another timeout requirement, independent of DECTalk. If this is true, a phone call may be automatically terminated (hung up) if a response is not given in a certain length of time. Your application program should accept unsolicited **R3_PH_ONHOOK** replies.

PH_TONE_DIAL and PH_PULSE_DIAL

DECTalk can dial an outgoing call by using these two commands. If DECTalk is connected to a Touch-Tone public telephone network, then use the **PH_TONE_DIAL** parameter; otherwise, use **PH_PULSE_DIAL**. **PH_PULSE_DIAL** works like an old rotary phone dial.

If the telephone is on-hook when the host sends a dialing command, DECTalk picks up the telephone and inserts a 2-second delay.

The text between the command terminator **z** and the **ESC ** sequence is the number to dial. For the Touch-Tone dialing system, the characters **0123456789*#ABCD!** are recognized. For the pulse dialing system, the characters **0123456789!** are recognized.

The **|** character inserts a 1-second delay into the dialing stream. DECTalk pauses during the dialing sequence every time it finds a **|** character.

On some telephone systems, a user can press the switch hook to transfer calls or otherwise interrupt a phone call. This signal is called a switch-hook flash. The **^** character inserts a 250-millisecond switch-hook flash signal into the dialing stream. You can use successive **^** characters to generate longer flashes.

With Touch-Tone dialing, the characters **ABCD** generate the extra four tones of the military handset. **A** is the character to the right of the **3**, **B** is the character below it, and so on.

Figure 4-1 shows a complete phone call session, including a timeout sequence initiated because a user disconnected.

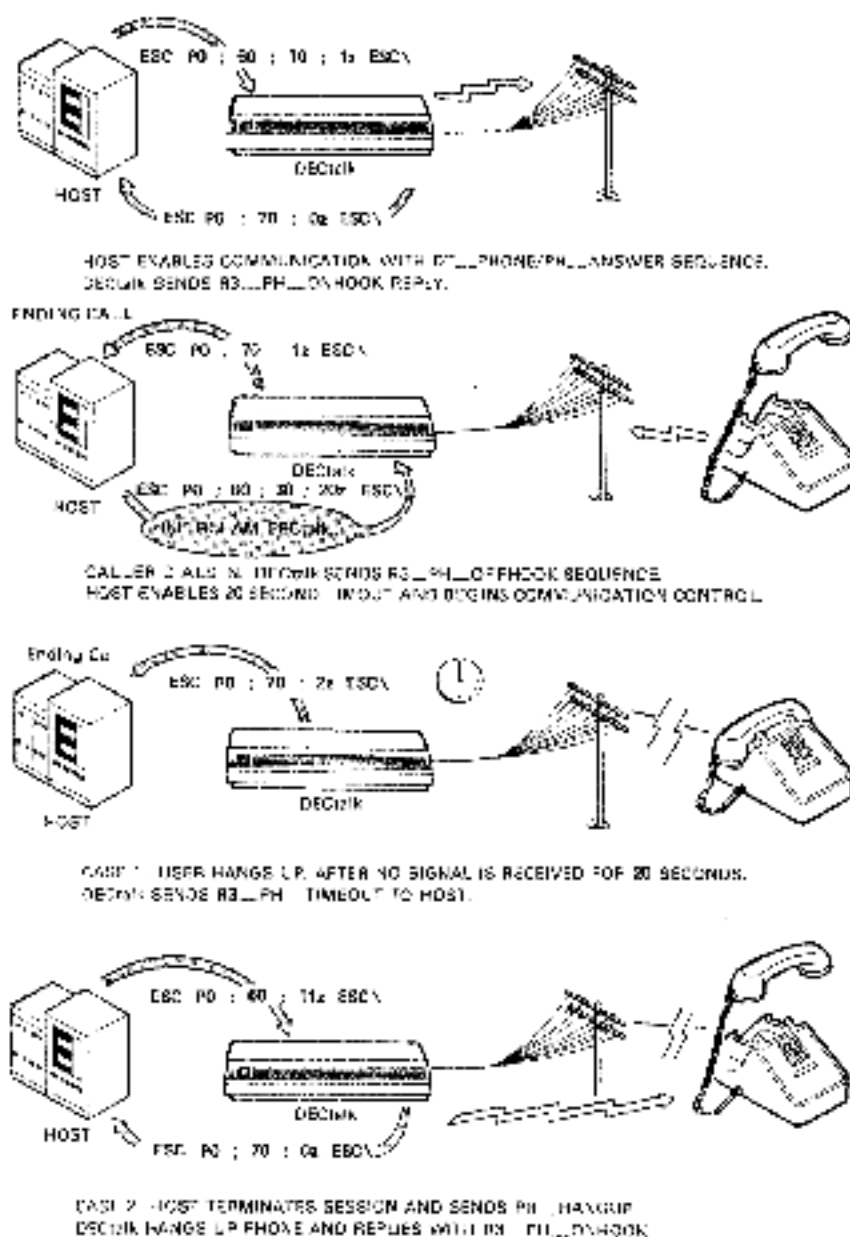


Figure 4-1 Telephone Communications

MAINTENANCE AND DEBUGGING COMMANDS

5

DECTalk has a set of commands that set DECTalk operating features, test DECTalk, and help debug application programs. Most of these commands have an inquiry-response format. DECTalk returns an answer to the host computer after the action is complete (or in response to a pure inquiry).

DEVICE ATTRIBUTE REQUEST

DECTalk responds to device identity requests from the host computer. For compatibility with an older escape sequence, DECTalk recognizes two different request sequences, described in the following paragraphs.

Device Attribute Request (DA Primary)

The preferred device attribute request escape sequence is as follows.

ESC	[	0	c
027	091	048	099

DECTalk identifies itself by sending the following sequence.

ESC	[	?	1	9	c
027	091	063	049	057	099

DECTalk does not respond to secondary device attribute requests, since its product identification code is less than 50.

Identify Terminal (DECID)

DECTalk responds to the old Identify terminal sequence (DECID) exactly as it responds to the DA Primary request.

The old Identify sequence is as follows.

ESC	Z
027	090

DECTalk identifies itself by sending the following sequence.

ESC	[	7	1	9	c
027	091	063	049	057	099

This is the same sequence as the DA Primary answer.

DEVICE TEST AND STATUS

A special set of escape sequences run DECTalk hardware self-tests. Another set of escape sequences forces DECTalk to return status reports. The following paragraphs describe these sequences.

DECTalk Power-Up Status

You can reset DECTalk to its power-up state. The method you use to reset DECTalk may affect the operating features (such as baud rate). You can reset DECTalk with any of the following methods. This chapter describes methods 2 through 4.

1. Power-up (PUP) is the state that DECTalk is in when first turned on.
2. Return to initial state (RIS) is a hard reset you can set with an escape sequence.
3. Soft reset (DECSTR) partially restores DECTalk to its power-up state.
4. Nonvolatile memory reset (DECNVR) lets you reset the operating features in permanent memory. At power-up, DECTalk restores the feature settings that you reset in this memory.

Table 5-1 lists the DECTalk operating features and their factory default settings; the reset methods in column three restore the feature to its power-up setting.

The power-up setting is the factory default, unless you changed the setting and stored it with a DECNRV sequence. See the section on DECNRV in this chapter.

Table 5-2 lists some other DECtalk actions performed by certain reset methods.

Table 5-1 Restoring DECtalk Operating Features

Feature	Factory Default	Restored from NVR by
Local line speed	9600 baud	PUP, DECNRV
Local line format	No parity	PUP, DECNRV
Host line speed	1200 baud	PUP, DECNRV
Host line format	No parity	PUP, DECNRV
Host CT transmit mode	7 bit	PUP, DECNRV
Host CT receive mode	7 bit	PUP, DECNRV
Local log tags	0	PUP, DECNRV, RIS
Local terminal tags	6	PUP, DECNRV, RIS

Table 5-2 DECtalk Actions Performed at Resets

DECtalk Action	Performed By
Initiate CT SPEAK	PUP, RIS, DECSTR
Hang-up telephone	PUP, RIS, DECSTR
Delete user dictionary	PUP, RIS
Flush all pending text	PUP, RIS
Turn fast speech on	RIS, DECSTR

Device Self-Test (DECTST)

This sequence initiates local self-tests. The escape sequence is as follows.

```
ESC   [   5   ;   Pn   y
027   091   053   059   ***   121
```

The Pn parameter specifies the test to perform (Table 5-3).

The TEST_POWER parameter (Pn = 1) causes DECTalk to rerun its power-up initialization and test sequences. ALL DECTalk operating features return to the power-up state; the telephone is hung up, the user dictionary is deleted, and all features are reset to their power-up values.

The loopback tests require the appropriate loopback connectors.

The built-in message provides a quick check of the DECTalk system. The message includes the version number of the DECTalk firmware.

Table 5-3 Self-Test Parameters

Mnemonic	ASCII Code Decimal Value	Function
TEST_POWER	1 049	Rerun power-up tests.
TEST_HDATA	2 050	Run host port data loopback test.
TEST_HCONTROL	3 051	Run host port control loopback test.
TEST_DATA	4 052	Run local port data loopback test.
TEST_LOOPBACK	5 053	Speak a built-in message.

Device Status Request (DSR) (Brief Report)

The brief DSR escape sequence is as follows.

```
ESC [ 5 n
027 091 053 110
```

If no malfunctions are detected, DECTalk replies with the following sequence.

```
ESC [ 0 n
027 091 048 110
```

If a malfunction is detected, DECTalk replies with the following sequence.

```
ESC [ 3 n
027 091 051 110
```

Applications can use this brief DSR format in most cases, because a brief request does not reset any of DECTalk's internal error flags. The following extended DSR format is useful when a malfunction is detected.

Device Status Request (DSR) (Extended Report)

The extended DSR escape sequence lets an application program determine when DECTalk was first powered on. The application sends the extended DSR escape sequence as follows.

```
ESC [ n
027 091 110
```

If no malfunctions are detected, DECTalk replies with one of two sequences. If this is the first extended DSR since DECTalk was powered on, DECTalk replies with the following sequence.

```
ESC [ 0 n ESC [ 7 2 1 n
027 091 048 110 027 091 063 050 049 110
```

For later requests, DECTalk replies with the following sequence.

```
ESC [ 0 n ESC [ 7 2 0 n
027 091 048 110 027 091 063 050 049 110
```

If a malfunction is detected, DECTalk sends the following sequence.

```
ESC [ 3 n ESC [ ? Pn ; ... Pn n
027 091 051 110 027 091 063 ~ 059 ... ~ 110
```

Each Pn parameter specifies an error as follows. The extended status request sequence resets the error flags.

2	2	Communication failure.
050	050	
2	3	Input buffer overflow.
050	051	
2	4	Last NVR operation failed.
050	052	
2	5	Error in phonemic transcription.
050	053	
2	6	Error in DECTalk private control sequence.
050	054	
2	7	Last DECTST failed.
050	055	

Reset to Initial State (RIS)

Table 5-1 shows how the reset to initial state affects DECTalk. The RIS escape sequence is as follows.

```
ESC c
027 099
```

This sequence resets DECTalk to its power-up state, without changing the speeds or data formats used on the host and local communication lines. All pending, unspoken text is lost. All user-defined dictionary entries are deleted. The telephone is returned to the on-hook state. Some operating features are restored from nonvolatile memory (NVR).

The RIS sequence always turns host speech on, even if host speech is turned off by the setup commands.

This NVR recall is almost identical to a DECNVR recall from user memory. (See "NVR Parameters" in this chapter.) RIS does not change the line characteristics, and RIS updates the "status of the last NVR operation" flag reported by device status reply sequences.

Digital recommends always using the DT_PHONE:ph_hangup sequence to hang up the telephone. If DECTalk receives an RIS sequence when the telephone is off-hook, and reads the telephone status during the hangup, DECTalk may report an off-hook status (instead of the expected on-hook status).

Soft Terminal Reset (DECSTR)

Table 5-2 shows how the soft terminal reset affects DECTalk. The DECSTR escape sequence is as follows.

```
ESC [ 1 p
027 091 033 112
```

This sequence resets DECTalk to its power-up state, without changing the speeds or data formats used on the host and local communication lines, or resetting user convenience features on the local terminal. Pending, unspoken text is not lost. The telephone returns to the on-hook state.

Digital recommends always using the DT_PHONE:ph_hangup sequence to hang up the telephone. If DECTalk receives a DECSTR sequence when the telephone is off-hook, and reads the telephone status during the hangup, DECTalk may report an off-hook status (instead of the expected on-hook status).

The DECSTR sequence always turns host speech on, even if host speech is turned off by the setup commands.

NVR Feature Settings (DECNVR)

You can store operating feature settings permanently in nonvolatile memory (NVR). DECtalk restores these settings at the next power-up. To save or restore the current settings in NVR, use the following DECNVR escape sequence.

```
ESC  [  Pn  :  Pm  t  r
027  091  ***  059  ***  033  114
```

If Pn is 0, this sequence restores all feature settings from NVR. This action may change the speeds or data format of the serial lines, so communication with the host or local terminal may be lost. The user dictionary is not deleted. The telephone is not hung up.

If Pn is 1, this sequence stores all current feature settings in NVR. DECtalk stops processing host line commands until the feature settings are safely stored.

The Pm parameter specifies which NVR memory to use. Memory 0 is a read/write memory you can use to store feature settings. DECtalk normally uses memory 0 at power-up. Memory 1 is a read-only memory, and always contains the factory-default DECtalk feature settings. DECtalk uses memory 1 at power-up if memory 0 cannot be used. Diagnostics may use memory 1 to force DECtalk back to its factory settings.

DECtalk remembers the success or failure status of the last NVR operation command. A device status request (DSR) sequence can check this status.

TRACING AND DEBUGGING COMMANDS

You can set DECtalk to log its actions and reactions to various commands on the local terminal. These commands are useful for testing and debugging during application program development.

Local Log Control (DT_LOG)

This sequence controls the logging of trace and debugging information on the local terminal. DT_LOG works like the SET LOG command in setup mode. (See the *DECtalk DTC01 Owner's Manual*.) The DT_LOG escape sequence is as follows.

```
ESC  P  0  :  8  1  ;  P3  z  ESC  \
027  080 048 059 056 049 059  ***  122 027  D82
```

Use the following method to obtain the P3 value.

1. Add up the values of the DT_LOG parameters in Table 5-4 that you want to use.
2. Convert the sum to ASCII digits. Use these digits in place of P3 in the escape sequence.

Table 5-4: DT_LOG Parameters

Mnemonic	Value	Function
LOG_TEXT	1	Enable ASCII text logging.
LOG_PHONEME	2	Enable phonemic text logging.
LOG_RAWHOST	4	Send all characters from the host to the terminal without inspection.
LOG_INHOST	8	Enable logging of text read from the host.
LOG_OUTHOST	16	Enable logging of text sent to the host.
LOG_ERROR	32	Enable the display of DECtalk error messages.
LOG_TRACE	64	Synchrnically display all escape sequences that affect DECtalk operations.
LOG_DEBUG	128	Reserved for Digital internal use.

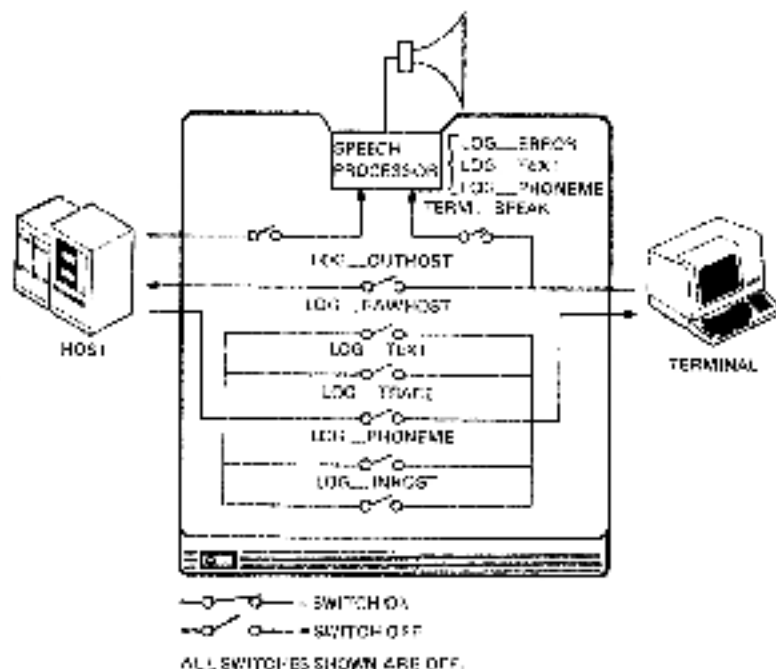
For example, assume you want to set LOG_TEXT and LOG_RAWHOST.

```
LOG_TEXT      - 1
LOG_RAWHOST   - 4
```

```
Desired P3 value - 5
```

```
ESC  P  O  ;  8  1  ;  5  z  ESC  \
027 060 048 059 056 049 059 053 122 027 092
```

Table 5-4 lists the P3 parameters. Figure 5-1 shows the data paths for logging and debugging.



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Figure 5-1 Data Paths for Logging and Debugging

LOG_TEXT

This command logs all spoken text. The text source does not matter; text is logged from both the host and the terminal.

LOG_PHONEME

This command logs all spoken text in its phonemic transcription. LOG_PHONEME is useful for testing the phonemic form of words and phrases.

LOG_RAWHOST

This command logs all control and text characters as received, except NUL characters (which are always deleted) and XON/XOFF characters (which still perform flow control functions).

LOG_INHOST

This command logs all characters received from the host. Control characters also print.

LOG_OUTHOST

This command logs all characters sent to the host. Control characters also print.

LOG_ERROR

This command logs all error messages. Usually DECtalk error messages are returned as escape sequences. Setting the LOG_ERROR flag causes error messages to be logged also.

LOG_ERROR is useful during the early stages of application program development.

LOG_TRACE

This command displays all escape sequences symbolically rather than as escape sequences. If you use LOG_TRACE in debugging, you do not have to look up the meaning of escape sequences.

LOCAL TERMINAL COMMAND (DT_TERMINAL)

This escape sequence controls the destination of characters typed on the local terminal when the terminal is not in setup mode. (The TERM_FILTER parameter affects characters sent to the local terminal when the terminal is not in setup mode.) Figure 5-2 shows the data paths in local terminal operations.

The format of the DT_TERMINAL escape sequence is as follows.

ESC	P	0	:	8	2	:	P3	z	ESC	\
027	080	048	059	056	050	059	***	122	027	092

Use the following method to obtain the P3 value.

1. Add up the values of the DT_TERMINAL parameters in Table 5-5 that you want to use.
2. Convert the sum to ASCII digits. Use those digits in place of P3 in the escape sequence.

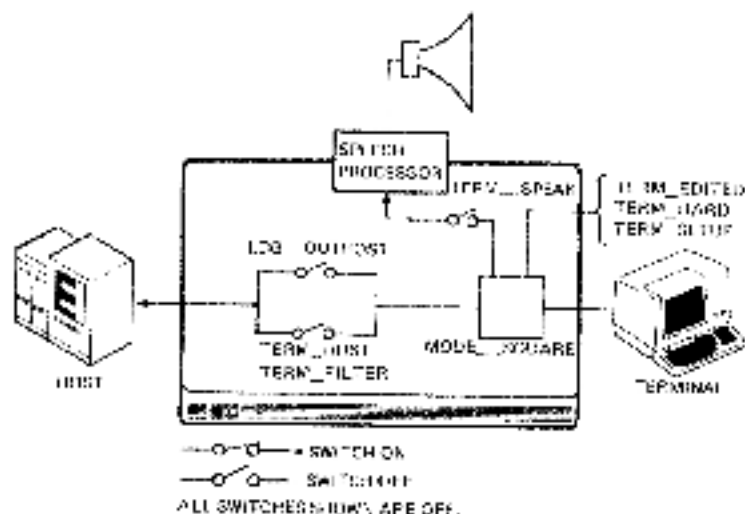


Figure 5-2 Data Paths for Local Terminal Operations

For example, assume you want to set TERM_HOST and TERM_EDITED.

```
TERM_HOST      = 1
TERM_EDITED    = 4
```

```
Desired P3 value = 5
```

```
ESC P 0 ; 8 2 ; 5 z ESC \
027 080 048 059 056 050 059 053 122 027 092
```

Table 5-5 lists the possible P3 values.

NOTE: If LOG_RAW and TERM_HOST are in effect and the host sends a device attribute request, both DECtalk and the terminal will respond. The application program sample in Chapter 6 turns off TERM_HOST for this reason.

Table 5-5 DT_TERMINAL Parameters

Mnemonic	Value	Function
TERM_HOST	1	Send all characters typed on terminal to host line.
TERM_SPEAK	2	Speak all characters typed on terminal.
TERM_EDITED	4	Line edit all characters typed on terminal. (See the <i>DECtalk DTGDT Owner's Manual</i> .)
TERM_HARD	8	Do local terminal echo operations in hardcopy terminal format.
TERM_SETUP	16	Speak all characters displayed on the terminal when in setup mode.
TERM_FILTER	32	Do not send DECtalk-specific escapes sequences to the terminal.

NOTE: When you set TERM_FILTER, DECtalk also ignores non-DECTalk escape sequences (except those needed for character set and communications setup). You still need to set LOG_RAWHOST on to have DECtalk send text to the local terminal.

TERM_FILTER is useful when you use DECtalk as a link between a general-purpose operating system and an applications terminal. **TERM_FILTER** modifies the operation of **LOG_RAWHOST** to prevent sending DECtalk-specific escape sequences to the local terminal.

When you set **TERM_FILTER**, the following escape sequences usually processed by DECtalk are now only processed by the local terminal.

- Device self-test (ESC [5 ; Ps y)
- Brief device status request (ESC] 5 n)
- Extended device status request (ESC [n)
- Reset to initial state (ESC c)
- Soft terminal reset (ESC [! p)
- NVR parameters (ESC [Pn ; Pn ! r)
- Device attributes inquiry (ESC [0 a)
- Identify terminal (ESC z)

The following escape sequences are acted on by both DECtalk and the local terminal.

- Select active character set (several sequences)
- Select graphics repertoire (ESC i B and ESC i c)
- Select 7-bit C1 transmission (ESC SP F)
- Select 8-bit C1 transmission (ESC SP G)
- Truncate high-order bit in C1 (ESC SP S)
- Accept high-order bit in C1 (ESC SP 7)

Because **TERM_FILTER** must parse and understand escape sequences, you can only use **TERM_FILTER** when the local terminal supports ANSI escape sequences. Digital's VT100 and VT200 series terminals and the terminals communications programs available for Digital's personal computers support ANSI escape sequences.

KEYPAD MASK COMMAND (DT_MASK)

This command controls how DECtalk sends escape sequences and keypad characters to the host. **DT_MASK** simplifies application development when DECtalk is connected to a host via a packet-switched network or a network using the SNA (systems network architecture) protocol. These networks have a significant overhead associated with each message, so sending a line of text (several characters) is more economical than sending a single character.

DT_MASK is also useful when DECtalk is connected to an operating system that prefers to communicate line-by-line, rather than character-by-character. For example, when DT_MASK is on, you can use BASIC's INPUT LINE command to read text from DECtalk.

The command takes one parameter, which is interpreted as a 16-bit value. If a bit is set, DECtalk sends a carriage return after sending the associated keypad character. If any bit is set, DECtalk sends a carriage return after its escape sequence replies. (The carriage return follows the ESC \ string terminator.) The DT_MASK escape sequence is as follows.

```
ESC P 0 ; 8 3 ; P3 z ESC \
027 080 048 059 056 051 059 *** 122 027 092
```

The P3 parameter is bit-encoded. Specified values have associated characters (Table 5-6). If you specify a value, DECtalk sends a carriage return after the associated character (when a user presses that key).

Table 5-6 DT_MASK Parameters

Value	Bit	Character
1	0	0
2	1	1
4	2	2
8	3	3
16	4	4
32	5	5
64	6	6
128	7	7
256	8	8
512	9	9
1024	10	*
2048	11	#
4096	12	A
8192	13	B
16384	14	C
32768	15	D

For example, to have DECtalk treat the # and * characters as response terminators (but not the digits), a program would send the following sequence.

```
ESC P ; 8 3 ; 3 0 7 2 z ESC \
027 080 059 056 057 059 051 048 055 050 122 027 092
```

(3072 = 1024 * 3)

If the person calling the application presses **123#** followed by a keypad time-out, DECtalk would send the following.

1 2 3 # <carriage return>

```
ESC P ; 7 0 ; 2 z ESC \ <carriage return>
027 080 059 055 048 059 050 122 027 092
```

This allows the application program to use standard line-oriented input routines, rather than character-oriented routines. If you specify a P3 parameter of 0 with DT_MASK, DECtalk will not send a carriage return after keypad characters or escape sequences.

NOTE: DECtalk will not send carriage return after all sequences, including responses to non-DECtalk-specific sequences such as device status request. Only responses generated within DECtalk are affected. Characters and escape sequences generated by a local terminal are sent without interpretation.

The DECtalk support library does not interpret carriage return characters. You have to process carriage returns with an application program. (Usually, an application will ignore them.)

DETERMINING FIRMWARE REVISION LEVEL

If your application environment has DECTalk units with different versions of firmware (1.8 and 2.0) you may need to determine the revision level of a particular unit. You can use the following steps to determine the firmware revision level.

1. Use the extended DSR escape sequence in this chapter to clear all DECTalk errors. (Remember to note the DECTalk reply.)
2. Use the following escape sequence to send a [+] phoneme.

```
ESC P ; z + ESC \
027 080 059 122 043 027 092
```

This is silent and new to revision level 2.0 only.

3. Send another extended DSR escape sequence. If DECTalk is a firmware revision level 1.8, it will report an error in the phonemic transcription. If DECTalk is revision level 2.0, it will not report any errors.

```
ESC [ 0 n ESC [ ? 2 0 n
027 091 048 110 027 091 063 050 048 110
(firmware 2.0 report)
```

```
ESC [ 3 n ESC [ ? 2 5 n
027 091 051 110 027 091 063 050 053 110
(firmware 1.8 report)
```

Phonemic Alphabet

Appendix A lists all phonemes you can use in the DECTalk phonemic alphabet.

Figure 1. The 12 test items of the TSCC.

C PROGRAM EXAMPLE 6

This chapter provides the source listings of a sample DECTalk application written in C programming language. The program uses DECTalk, a host computer, and a telephone connection to the United States public telephone network.

You can copy and use this application program; however, the program is only a model, and cannot cover all possible DECTalk applications. You will find many algorithms and sections within the application that you can use in your own program; however, you will probably have to modify large sections of this program for your own needs. Also, there is no guarantee that this application program will run in the same way on your computer or on your public telephone system (especially if you do not live in the United States).

The source programs are available from the DECUS Library (Digital Equipment Corporation User's Society) as 11-SP-58 (for PDP-11s) or V-SP-20 (for VAX/VMS). RSX and RSTS operating systems need a system services library distributed with DECUS C (DECUS 11-SP-18). All operating systems require a C compiler to compile the programs. The DECUS library also has versions of the library written in BASIC-PLUS and COBOL.

To order the latest version of source programs from the DECUS Library, mail your request to:

DECUS Order Processing
MR02-1/C11
One Iron Way
Marlboro, MA 01752

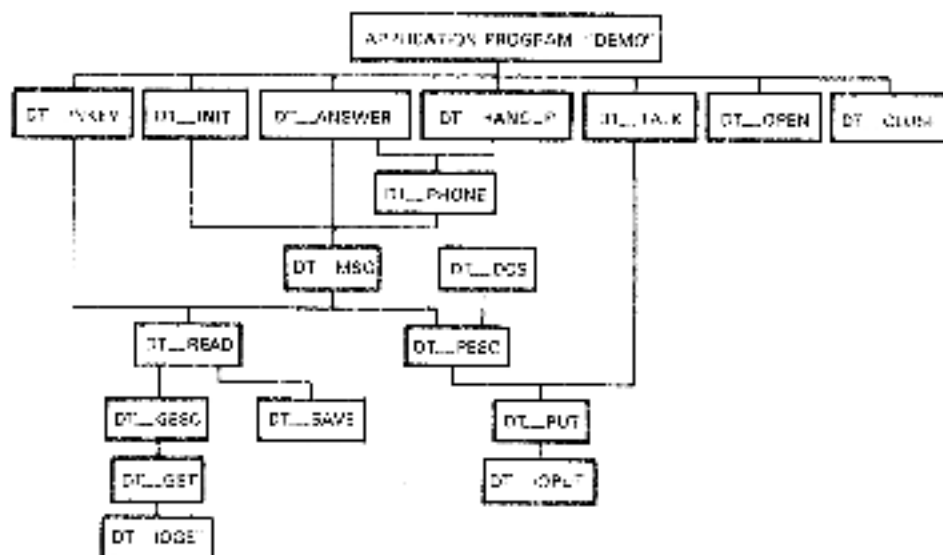
For general information before placing an order, call (617) 480-9422.

PROGRAM LANGUAGE AND STRUCTURE

This application program is written in C, a language originally written for the UNIX operating system. C is a highly structured language, similar to Pascal, ALGOL, and COBOL in form and syntax. C is also reasonably transportable: the application program shown here can run on RSTS/E, RSX, UNIX, or VAX/VMS operating systems (if the correct compilers are on those systems).

The application is written in many small modules, which are called according to a tree structure (Figure 6-1). There are many modules, because each module has only one or two functions within the program. The small, tight structure of each module means that their function is easy to read and grasp.

All variables, constants, and other special values are listed in one module: DECTLK.H. You must include DECTLK.H with the compilation of all other modules.



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Figure 6-1 Calling Tree of DECTalk Application Program

HOW THE PROGRAM WORKS

The application program waits for a caller to dial the DECtalk phone number. DECtalk then acts as a link between the host computer and the caller, passing a canned message to the caller and informing the host when the caller presses any keypad buttons. DECtalk releases the phone line (1) when the caller hangs up, or (2) if no response is received after a certain length of time.

The program works as follows.

1. When started, the program establishes the DECtalk-telephone-host operating environment. DECtalk is set to wait for an incoming call.
2. When a phone call is received, DECtalk answers the call and informs the host that a call is active.
3. The host then sends a message for DECtalk to speak to the caller. This message informs the caller that the keypad can be used.
4. At the end of the host message, the telephone keypad is enabled and the caller can send responses back to the host.
5. The host responds with a "you pressed button ..." message when the caller presses a keypad button. If the caller doesn't press a button for 15 seconds, the host tells DECtalk to hang up the phone.

VARIABLE NAMES AND DEFINITIONS

All global variables and constants are defined in the module DECTLK.H. The function of an escape sequence or coded reply from DECTalk is not clear when embedded within a program; therefore, all escape sequences and status codes are given their mnemonic names in DECTLK.H. The program then refers to these names rather than the escape codes themselves.

What follows is a list of the global variables, mnemonics, and codes used in the application program.

Flags

Two flags are used throughout the application program. The flags control certain critical actions, as follows.

<code>dt_abort</code>	This flag is normally FALSE. If <code>dt_trap()</code> is called, the library will trap a CTRL-C (or INTERRUPT on UNIX). If the user types CTRL-C, the flag is set to TRUE and all library modules exit as quickly as possible.
<code>dt_debug</code>	This flag can be set nonzero by an application program to enable debug printouts. Note that the library must have been compiled with <code>dt_debug</code> defined in order to compile in the necessary print calls.

Error Codes

The library may return the following error codes. The error codes are all less than zero, so they cannot be defined as part of the ASCII character set.

<code>DT_ERROR</code>	An operating system error occurred.
<code>DT_TIMEOUT</code>	An input operation did not complete in the required (operating system) time.
<code>IO_ERROR</code>	This is an error exit code for the <code>exit()</code> library routine. The value selected depends on the particular operating system.

DECTalk-Specific Parameters

Certain codes apply only to DECTalk (and not other devices, such as terminals). These codes are as follows.

CSI_DA_PRODUCT	The DECTalk product identification code.
DCS_F_DECTALK	The DECTalk specific device control sequence (DCS) final character.
P1_DECTALK	All DTC01-AA DCS sequences send this for their first (P1) parameter.
R1_DECTALK	All DTC01-AA DCS replies send this for the first (R1) reply parameter.

DECTalk Commands

The DECTalk commands that do not require specific parameters are coded as follows.

P2_PHOTEXT	Speak phonemic text.
P2_STOP	Stop speaking.
P2_SYNC	Synchronize.
P2_SPEAK	Enable/disable speaking.
P2_INDEX	Index text.
P2_IX_REPLY	Index with reply.
P2_IX_QUERY	Return last spoken index.
P2_DICT	Load user dictionary.
P2_PHONE	Telephone control (See "Telephone Control Parameters.")

P2_MODE	Synthesis mode control.
P2_LOG	Local terminal log control.
P2_TERMINAL	Local terminal control.

Telephone Control Parameters

The telephone control command P2_PHONE takes an additional parameter to specify the specific telephone action.

P3_PH_STATUS	Send a status report.
P3_PH_ANSWER	Answer on P4 rings.
P3_PH_HANGUP	Hang up the phone.
P3_PH_KEYPAD	Enable keypad data entry.
P3 PH_NOKEYPAD	Disable keypad data entry.
P3_PH_TIMEOUT	Send a timeout report if no data entered in P4 seconds if P4 is greater than zero; disable timeouts if P4 is zero.
P3_PH_TONE	Dial out using Touch-Tones.
P3_PH_PULSE	Dial out using pulses.

DECtalk Replies

Several P2_ commands return messages to the host.

R2_IX_REPLY	Reply to P2_IX_REPLY. R3 contains the last index processed.
R2_IX_QUERY	Reply to P2_IX_QUERY. R3 contains the last index processed.
R2_DICT	Reply to P2_DICT. R3 contains the dictionary entry status code.
R2_PHONE	Reply to P2_PHONE. R3 contains the telephone status.

DECtalk returns the following R3 parameters after a P2_PHONE command.

R3_PH_ONHOOK	Telephone is hung up (inactive).
R3_PH_OFFHOOK	Telephone is answered (active).
R3_PH_TIMEOUT	No data was entered by the telephone user within the required number of seconds.
R3_PH_TOOLONG	A telephone number to dial is too long.

DECtalk returns the following R3 parameters after a P2_DICT command.

R3_DI_LOADED	Dictionary entry was loaded.
R3_DI_NOROOM	The user dictionary is full.
R3_DI_TOOLONG	The dictionary entry is too long.

Self-Test Parameters

The following parameters control the DECtalk self-test (DECTST).

TEST_POWER	Run power-up test.
TEST_HDATA	Run host data link loopback test.
TEST_HCONTROL	Run host line control test.
TEST_LDATA	Run local line data test.
TEST_SPEAK	Speak a canned message.

The following status codes are returned by the extended DSR sequence.

DSR_OK	No errors detected.
DSR_COMFAIL	Communication failure.
DSR_INBUFOVER	Input buffer overflow.
DSR_DECNVRFAIL	Last restore from nonvolatile memory failed.
DSR_PHONEME	Incorrect phoneme entered.
DSR_PRIVATE	DECtalk DCS parameter error.
DSR_DECTSTFAIL	Last DECTST self-test failed.

Logging Command Parameters

The following parameters configure the P2_LOG command.

LOG_TEXT	Log spoken text.
LOG_PHONEME	Log generated phonemes.
LOG_RAWHOST	Log all characters received from host without change.
LOG_INHOST	Log all characters received from host in visible format.
LOG_OUTHOST	Log all output to host in visible format.
LOG_ERROR	Log error messages.
LOG_TRACE	Log commands in mnemonic form.

The following parameters are for the P2_TERMINAL command.

TERM_HOST	Send text entered from the local terminal to the host.
TERM_SPEAK	Speak text entered from the local terminal.
TERM_EDITED	Line-edit text entered from the local terminal.
TERM_HARD	Use hardcopy edit conventions.
TERM_SETUP	Speak setup dialog.
TERM_FILTER	Filter sequences sent to the local terminal.

The following parameters are for the P2_MODE command.

MODE_SQUARE	Accept [] bracket phonemic text.
MODE_ASKY	Use single-letter phonemic alphabet.
MODE_MINUS	Pronounce a hyphen (-) as "minus."

THE SEQUENCE DATA STRUCTURE

The C language uses a powerful form of information control called a data structure. Data structures closely resemble Pascal records and can pass and hold multiple pieces of information.

All information needed to generate and parse escape sequences is in the SEQUENCE data structure. SEQUENCE is configured by the following size constants.

SEQ_INTMAX	Maximum number of intermediate characters.
SEQ_PARMAX	Maximum number of parameters.

The SEQUENCE data structure contains the following components.

short state	Processing state or introducer character to send.
char final	Final character in sequence.
char private	Private introducer character (or X to indicate an error).
short param[]	Private parameters (unsigned); param[0] contains the number of parameters.
char inter[]	Intermediate characters; inter[0] contains the number of intermediates.

All information needed by the application program is in the DECTALK data structure which is created by `dLopen()` and freed by `dt_close()`. The DECTalk data structure is configured by the following parameters.

PEND_SIZE	Maximum number of keypad characters that may be typed ahead. Additional characters are discarded.
IN_BUFLen	Size of the operating system input buffer.
OUT_BUFLen	Size of the operating system output buffer.

The data buffer contains the following information.

DECTALK *link	Chains together all active units.
int unit	Operating system I/O channel.
short timeout	TRUE if timeouts enabled.
short pend_fc	Bytes in pending buffer.
short pend_fo	Index to free byte in pending buffer.
short pend_ep	Index to next byte to return from pending buffer.
char *in_ptr	Input buffer pointer.
char *in_end	Input buffer end.
char *out_ptr	Output buffer free pointer.
SEQUENCE send	Last DCS sequence sent.
SEQUENCE reply	Last DECTalk reply received.
SEQUENCE seq	Look-ahead for string terminator processing.
char *device	Remember dt_open() device name for debug printouts.
char pend[]	Type-ahead buffer.
char in_buff[]	Input buffer.
char out_buff[]	Output buffer.
struct sgty stty_save	Terminal characteristics block (UNIX only).
FILE *fides	File descriptor (RSX only).
struct iosb iosb	I/O status block (RSX only).
struct qioparm parm	QIO parameter block (RSX only).

APPLICATION PROGRAMS

The rest of this chapter lists the modules used to build the complete application program. All modules with the indicator comment

```
/*)LIBRARY
```

should be compiled and loaded into an object library. The main program, DEMO.C, is compiled and linked with the DECtalk library and the C standard library.

The modules appear in the following order (Table 6-1).

Table 6-1 Application Program Modules

Module	Brief Description
DECTALK.H	This file must be included in all modules that use the DECtalk applications library. Contains common definitions (for example, escape sequence parameters).
DEMO.C	This is the main module of the program.
DTANSW.C	Picks up the phone and answers on rings.
DTCLOSE.C	Closes the DECtalk channel and frees all buffers.
DTCMD.C	Sends a DCS command to the DECtalk terminal.
DTDCHA.C	Formats characters into a visible ASCII datacodes format and writes the text to the indicated file.
DTDCS.C	Sends a DECtalk DCS control sequence.
DTDIAL.C	Dials the DECtalk telephone.
DTDRAL.C	Absorbs any type-ahead characters.
DTDUMP.C	Writes an escape sequence buffer to the standard output file (for debugging).
DTENDL.C	Writes an end-of-line to DECtalk.
DTGESC.C	Reads an escape sequence or keypad character.

Table 5-1 Application Program Modules (Cont)

Module	Brief Description
DTGET.C	Reads a character from the DECtalk terminal line.
DTHANG.C	Hangs up the telephone connected to DECtalk.
DTINIT.C	Initializes the DECtalk terminal on the channel opened on <i>fd</i> .
DTINKE.C	Reads a telephone keypad button.
DTIOBE.C	Reads one character from the DECtalk terminal line.
DTIOPU.C	Either writes the output buffer contents to the DECtalk device or stores the character in a local buffer.
DTISKE.C	Indicates if the telephone user typed any characters.
DTISLC.C	Tests the result of a dt.phone (i) message for keypad hit/lock.
DTISVA.C	Indicates if the argument character is one of 0123456789*+ABCD.
DTKEYP.C	Enables or disables the telephone keypad.
DTMBO.C	Sends a DECtalk DCS control sequence and reads a DCS reply.
DTOFFHC.C	Tests the result of a dt.offone (i) message for OFFHOOK.
DTONHOC.C	Tests the result of a dt.phone (i) message for ONHOOK.
DTOPEN.C	Initiates communications by performing operating system-specific initializations.
DTPEEK.C	Tests if a character is pending from DECtalk.
DTPEEC.C	Computes an appropriate escape sequence from the parameter buffer.
DTPHON.C	Sends a DECtalk phone message.
DTPTER.C	Tests a phone reply.

Table 6-1. Application Program Modules (Cont.)

Module	Brief Description
DTPUT.C	Sends one character to the DECTalk terminal's line. No value is returned.
DTREAD.C	Reads a sequence of character.
DTRESET.C	Sends a soft-reset escape sequence.
OTSAVE.C	Saves user-type-ahead characters.
DTSPLOC.C	Lets you control a terminal connected to DECTalk's local port.
DYST.C	Sends a string terminator (for phonecall text and telephone dial commands) to DECTalk.
DTSYNC.C	Synchronizes DECTalk and the application.
DTTALK.C	Speaks one line of text.
BTEEST.C	Tests a DECTalk reply.
DTTIME.C	Enables or disables a telephone keypad timeout.
DTTONE.C	Sends the msg text string as a tone dialing sequence.
DTTRAP.C	Traps CTRL-C interrupts.
DTVISI.C	Generates visible ASCII character representations.
HELLO.C	Tests that DECTalk is operating correctly.

DECTLK.H

DECTLK.H must be included in all modules that use the DECTalk applications library. This file also defines common ASCII characters, DECTalk escape sequence parameters, library globals, and the DECTalk buffer structure. You can edit this file to enable debugging code defined by the DTDEBUG flag.

```

/*
 *      D e f i n i t i o n s   a n d   G l o b a l s
 *
 * This file contains symbolic definitions of the structures
 * and characters used by DECTalk application programs,
 * including all DECTalk escape sequence parameters.
 *
 * Notes on RSX-11M, your program must start #include <stdio.h>
 */

/*
 * Select a UNIX "flavor" (hizarrs code as DECUS C looks "defined()")
 */
#ifdef unix
#ifdef BSD_42
#ifdef UNIXLV
#define UNIXLV
#endif
#endif
#endif

#ifdef DOCUMENTATION

title    dectlk.h          DECTalk Library Header File
index    DECTalk library header file

synopsis
    #include "dectlk.h"

description

    This file is included in the compilation of all
    modules that use the DECTalk applications library.
    It defines common ASCII characters, DECTalk
    escape sequence parameters, library globals,
    and the DECTALK buffer structure.

configuration

    You can edit dectlk.h to enable debugging code
    by defining the DT_DEBUG flag as follow.

    #define DT_DEBUG 1

    This changes the primary input and output routines
    so that they become capable of logging all characters
    transmitted to and from the DECTalk device.

```

globals

The library provides two global flags which are used as follows.

<code>dt_abort</code>	This is set non-zero by an intercepted CTRL-C trap (if you have called <code>dt_trap()</code>). When set, no I/O will be performed, and library subroutines will exit as quickly as possible.
<code>dt_debug</code>	This may be set nonzero by an applications program to enable debug printouts. Note that the library must have been compiled with <code>DT_DEBUG</code> defined in order to compile in the necessary print calls.

error codes

The library may return the following error codes. These are all less than zero, and consequently cannot be part of the ASCII character set.

<code>DT_ERROR</code>	An operating-system error.
<code>DT_TIMEOUT</code>	An input operation did not complete in the required (operating-system) time.
<code>IO_ERROR</code>	An error exit code for the <code>exit()</code> library routine. The value is selected as appropriate for the particular operating system.

Routines implemented as macros

Certain frequently routines may be implemented as macros (if macro expansion is supported by the particular C compiler). These are as follows.

<code>dt_iskey(d1)</code>	TRUE if data is currently stored in the keypad type-ahead buffer.
<code>dt_isvalid(c)</code>	TRUE if the character is a valid keypad character. Note: evaluation of the argument must not have side-effects, i.e., you must not write <code>dt_isvalid(*p++)</code> .
<code>dt_phew(dt,r3)</code>	Phone test, TRUE if the current reply is <code>R2_PHONE</code> , <code>R3</code> .

```

dt_offhook(dt)    Phone test, TRUE if the current
                  reply is R2_PHONE, R3_PH_OFFHOOK.
:
dt_onhook(dt)     Phone test, TRUE if the current
                  reply is R2_PHONE, R3_PH_ONHOOK.
:
dt_islineout(dt)  Phone test, TRUE if the current
                  reply is R2_PHONE, R3_PH_TIMEOUT.
:
dt_phone(dt,p3,p4) Send a phone message.
:
dt_well(dt)       Send "end of line" and force
                  output to DECTalk.

```

general definitions

The following variables are defined.

```

EOS             End of string
FALSE           For TRUE/FALSE testing
TRUE            For TRUE/FALSE testing

```

ascii characters

The following C0 control characters are defined.

```

NUL STX ETX BEL BS  VI  LS1
:
LSD  XDN  XOFF CAN  SUB  ESC  DEL

```

The following C1 control characters are defined.

```

SS2  SS3  DCS  DCDT0 DCT  ST  ESC
:
PN  APC  RDEL

```

The following DECTalk-specific parameters are also defined.

```

CSI_DA_PRODUCT  The DECTalk product
                  identification code.
:
DCS_F_DECTALK   The DECTalk specific device
                  control sequence (DCS) final
                  character.
:
P1_DECTALK      All DCT01 DCS sequences
                  transmit this for their first
                  (P1) parameter.
:
R1_DECTALK      All DCT01 DCS replies transmit
                  this for the first R1 reply
                  parameter.
:
:
:

```

The P2 and P3 parameters select the specific DECtalk command.

P2_PHOTEXT	Speak phonetic text.
P2_STOP	Stop speaking.
P2_SYNC	Synchronize.
P2_SPEAK	Enable/disable speech.
P2_INDEX	Index text.
P2_IX_REPLY	Index with reply.
P2_IX_QUERY	Return last spoken index.
P2_DICT	Load user dictionary.
P2_PHONE	Telephone control.
P2_HMODE	Synthesis mode control.
P2_LDG	Local terminal log control.
P2_TERMINAL	Local terminal control.
P2_MASK	Keypad mask control.

The telephone control command takes an additional parameter to specify the specific telephone action.

P3_PH_STATUS	Return a status report.
P3_PH_ANSWER	Answer on P4 rings.
P3_PH_HANGUP	Hangup the phone.
P3_PH_KEYPAD	Enable keypad data entry.
P3_PH_NOKEYPAD	Disable keypad data entry.
P3_PH_TIMEOUT	Send a timeout report if no data entered in P4 seconds if P4 is greater than zero; disable timeouts if P4 is zero.
P3_PH_TONE	Dial out using tones.
P3_PH_PULSE	Dial out using pulses.

Several P2 commands return messages to the host.

R2_IX_REPLY	Reply to P2_IX_REPLY. R3 contains the last index processed.
R2_IX_QUERY	Reply to P2_IX_QUERY. R3 contains the last index processed.
R2_DICT	Reply to P2_DICT. R3 contains the dictionary entry status code.
R2_PHONE	Reply to P2_PHONE. R3 contains the telephone status.

The following R3 parameters are returned after a P2_PHONE command.

R3_PH_ONHOOK	Telephone is hung up (inactive).
R3_PH_OFFHOOK	Telephone is answered (active).
R3_PH_TIMEOUT	No data was entered by the telephone user within the required number of seconds.
R3_PH_TOO_LONG	A telephone number to dial is too long.

The following R3 parameters are returned after a P2-DICT command.

R3_DI_LOADED	Dictionary entry was loaded.
R3_DI_HORROR	The user dictionary is full.
R3_DI_TOO LONG	The dictionary entry is too long.

The following codes are used to control host-requested self test (DECTST).

TEST_POWER	Rerun power up test.
TEST_HDATA	Host data link loopback test.
TEST_HCONTROL	Host line control test.
TEST_LDATA	Local line data test.
TEST_SPEAK	Speak a canned message.

The following status codes are returned by the extended DSR sequence.

DSR_OK	No errors detected.
DSR_CMFAIL	Communication failure.
DSR_INBUFOVER	Input buffer overflow.
DSR_DECNVWFAIL	Last restore from nonvolatile memory failed.
DSR_PHONEME	Incorrect phoneme entered.
DSR_PRIVATE	DECtalk DCS parameter error.
DSR_DECTSTFAIL	Last DECTST self-test failed.

The following flags configure the P2-LOG command.

LOG_TEXT	Log spoken text.
LOG_PHONEME	Log generated phonemes.
LOG_RAWHOST	Log all characters received from host without change.
LOG_INHOST	Log all characters received from host in "visible" format.
LOG_OUTHOST	Log all output to host in visible format.
LOG_ERROR	Log error messages.
LOG_TRACE	Log commands in mnemonic form.

The following flags are for the P2_TERMINAL command:

TERM_HOST	Send text entered from the local terminal to the host.
TERM_SPEAK	Speak text entered from the local terminal.
TERM_EDITED	Line-edit text entered from the local terminal.
TERM_HARD	Use hard-copy edit conventions.
TERM_SETUPSPEAK	Speak SETUP dialog.
TERM_FILTER	Filter escape sequences sent to the local terminal.

The following flags are for the P2_MODE command.

MODE_SQUARE	[] bracket phonetic text.
MODE_ASKY	Use single-letter phonetic alphabet.
MODE_MINUS	Pronounce '-' as "minus."

The following flags are for the displace() function.

SPLICE_SPEAK	DEtalk speaks text if set.
SPLICE_LOG	Text sent to DEtalk is sent to the terminal (P2_LOG, LOG_REMOTE).
SPLICE_TERM	The terminal may send text to DEtalk (P2_TERM, TERM_HOST).

Escape sequence data buffer

All information needed to generate and parse escape sequences is contained in the SEQUENCE data structure. It is configured by the following size constants.

SEQ_INTMAX	Maximum number of intermediate characters.
SEQ_PARMAX	Maximum number of parameters.

It contains the following components.

short state	Processing state or introducer character to send.
char final	Final character in sequence.
char private	Private introducer character or 'X' to indicate an error.

```

short param[]    Private parameters (unsigned);
                  param[0] contains the number of
                  parameters.

char inter[]     Intermediate characters;
                  inter[0] contains the number of
                  intermediates.

```

DECTALK data buffer definition

All information needed by the DECTalk applications library is contained in the DECTALK data structure which is created by `dt_open()` and freed by `dt_close()`. It is configured by the following parameters.

```

PEND_SIZE       Maximum number of keyed
                  characters that may be typed-ahead.
                  Additional characters are discarded.

IN_BUFLen       Size of the operating system input
                  buffer.

OUT_BUFLen       Size of the operating system output
                  buffer.

```

The data buffer contains the following information.

```

DECTALK *link    Chains together all active units.

short unit       Operating system I/O channel.

short timeout    Current timeout value.

short flag       Speed and dt_splice flags.

short pend_fc    Bytes in pending buffer.

short pend_fp    Index to free byte in pending
                  buffer.

short pend_lp    Index to next byte to return
                  from pending buffer.

char *in_ptr     Input buffer pointer.

char *in_end     Input buffer end.

char *out_ptr    Output buffer free pointer.

SEQUENCE send    Last DCS sequence sent.

SEQUENCE reply   Last DECTalk reply received.

SEQUENCE seq     Look-ahead for string terminator
                  processing.

char *device     Remember dt_open() device name
                  for debug printouts.

```

```

char pend[]      Type-ahead buffer.

char in_buff[]   Input buffer.

char out_buff[]  Output buffer.

struct termios stty_save  Terminal characteristics
                           block (UNIX System V).

struct stty stty_save     Terminal characteristics
                           block (UNIX 4.2 BSD).

FILE *fdw          File descriptor (RSX).

struct ioab ioab     I/O status block (RSX).

GIOPARM parm       GIO parameter block (RSX).
                   (RSX only).

int fdpos_xr       TRUE if PDS XR; driver
                   (RSX only).

```

The flag entry controls library internal states.

```

FLAG_SPEAK      Set if DECtalk is speaking.
FLAG_LOG        Set if LOG RAWHOST is set.
FLAG_TERM       Set if TERM HOST is set.
FLAG_EIGHTBIT   Set to read and write eight-bit
                 data and control sequences.

```

FLAG_SPEAK, FLAG_LOG, and FLAG_TERM should not be changed by application programs.

FLAG_EIGHTBIT must be set by the application program if DECtalk sends and receives C1 control sequences in their 8-bit form. Note that the application program must ensure that the operating system passes 8-bit data correctly and DECtalk setup must set HOST FORMAT to NONE.

UNIX Notes

On UNIX System V, the DECtalk terminal line is forced to 9600 Baud. This may be changed to retain the current Baud rate. Also, you should be aware that there are numerous subtle differences between operating systems.

Note

UNIX and System V are trademarks of AT&T Bell Laboratories.

```
#endif
```

```
/*
```

```
* Define DT_DEBUG to enable debug printouts of transmitted
* characters.

```

```
*/
```

```

#define BT_DEBUG

#define FALSE 0
#define TRUE 1
#ifndef EOS
#define EOS '\0'
#endif

#ifdef unix
#ifdef BSD_42
#include <sgtty.h>
#else
#ifdef UNIX_V
#include <termios.h>
#endif
#endif
#endif

/*
 * These error codes may not be in the ASCII range.
 */

#define BT_ERROR (-1)
#define BT_TIMEOUT (-2)

/*
 * C0 control characters
 */

#define NUL 0x00 /* NUL code */
#define STX 0x02 /* Start of text */
#define ETX 0x03 /* End of text */
#define BEL 0x07 /* Bell */
#define BS 0x08 /* Backspace */
#define VT 0x0B /* Vertical tab ('\013') */
#define LST 0x0E /* LST (ESC) */
#define LSO 0x0F /* LSO (ESC) */
#define XON 0x11 /* DC1 */
#define XOFF 0x13 /* DC3 */
#define CAN 0x18 /* Cancel (CTRL-X) */
#define SUB 0x1A /* Substitute */
#define NU_ 0x1C /* Null code */
#define ESC 0x1B /* Escape */
#define DEL 0x7F /* Delete */

/*
 * C1 control characters
 */

#define SS2 0x8E /* Single shift 2 */
#define SS3 0x8F /* Single shift 3 */
#define DCS 0x90 /* Device control sequence */
#define OLDID 0x9A /* ESC 2 */
#define CSI 0x9B /* Control Sequence Introducer */
#define ST 0x9C /* String terminator */
#define OSC 0x9D /* Operating System sequence */
#define PM 0x9E /* Privacy Message */
#define APC 0x9F /* Application Program Control */
#define RDEL 0xFF /* Delete in right side */

```

```

#define CSI_DA_PRODUCT 19      /* DecTalk DA product code */
/*
 * Basic definitions for DECtalk device control
 * arrange. All DECtalk sequences have a first parameter of
 * P1_DECTALK. This provides an easy place for future DECtalk
 * products to fit into the scheme of things.
 */

#define DCS_F_DECTALK 'f'      /* DECtalk final */
#define P1_DECTALK 0           /* DECtalk param 1 */
#define P1_DECTALK 0           /* DECtalk reply param 1 */

/*
 * The second parameter selects the basic command.
 */

#define P2_PHOTEXT 0           /* Speak phonetic text */
#define P2_STOP 10            /* Stop speaking */
#define P2_SYNC 11            /* Synchronize */
#define P2_SPEAK 12           /* Enable or disable speaking */
#define P2_INDEX 20           /* INDEX */
#define P2_IX_REPLY 21         /* INDEX_REPLY */
#define P2_IX_QUERY 22        /* INDEX_QUERY */
#define P2_DICT 40            /* Dictionary control */
#define P2_PHONE 60           /* Phone control */
#define P2_NODE 80            /* Synthesis node control */
#define P2_IDG 81             /* LBG information on local tty */
#define P2_TERMINAL 62        /* Local terminal control */
#define P2_MASK 83            /* Set keypad mask */

/*
 * Additional parameters for the phone command.
 */
#define P3_PH_STATUS 0         /* Send a status report */
#define P3_PH_ANSWER 10        /* Answer (P4 has ring number) */
#define P3_PH_HANGUP 11        /* Hangup */
#define P3_PH_KEYPAD 20        /* Raw keypad */
#define P3_PH_NKEYPAD 21       /* Disable keypad */
#define P3_PH_TIMEOUT 30       /* Status report on timeout */
#define P3_PH_TONE 40          /* Dial out */
#define P3_PH_PULSE 41         /* Dial out */

/*
 * The second parameter in a reply specifies the general class
 * of the reply sequence.
 */

#define R2_IX_REPLY 31         /* Sent after INDEX_REPLY */
#define R2_IX_QUERY 32        /* Sent after INDEX_QUERY */
#define R2_DICT 60            /* Sent after DICT */
#define R2_PHONE 70           /* Telephone status report */

```

```

/*
 * Additional reply information is passed in the third parameter.
 */

#define R3_PH_ONHOOK      0      /* Hung Up                      */
#define R3_PH_OFFHOOK     1      /* Phone is lifted              */
#define R3_PH_TIMEOUT     2      /* No reply in N seconds        */
#define R3_PH_TOOLONG     3      /* Telephone # text too long    */
#define R3_DI_LOADED      0      /* Dictionary entry loaded ok    */
#define R3_DI_NOROOM      1      /* No room in dictionary         */
#define R3_DI_TOOLONG     2      /* String too long              */

/*
 * Test specification codes for the request self test.
 * (DECTST) sequence.
 */

#define TEST_POWER        1      /* Rerun power up test         */
#define TEST_HDATA        2      /* Host line data loopback test */
#define TEST_HCENTROL     3      /* Host line control test      */
#define TEST_LDATA        4      /* Local line data test        */
#define TEST_SPEAK        5      /* Speak a canned message      */

/*
 * Error (and success) codes for the extended DSR sequence.
 */

#define DSR_OK             20     /* All OK                       */
#define DSR_COMMFAIL       22     /* Communication failure        */
#define DSR_INBUFDVER      23     /* Input buffer overflow        */
#define DSR_DECNVRFAIL     24     /* Last DECNVR failed          */
#define DSR_PHONEME        25     /* Error in phoneme text       */
#define DSR_PRIVATE        26     /* Error in DECTalk private DCS */
#define DSR_DECTSTFAIL     27     /* Last DECTST failed          */

/*
 * Local logging flags for the P2.LOG command.
 */

#define LOG_TEXT           0x0001 /* Log text that is spoken     */
#define LOG_PHONEME        0x0002 /* Log generated phonemes      */
#define LOG_RAWHOST        0x0004 /* Log raw host input          */
#define LOG_HOST          0x0008 /* Log host input              */
#define LOG_HOSTOUT        0x0010 /* Log host output             */
#define LOG_ERRORS         0x0020 /* Log errors                  */
#define LOG_TRACE          0x0040 /* Log sequence trace info.    */

/*
 * Local terminal flags for the P2_TERMINAL command.
 */

#define TERM_HOST          0x0001 /* Send text to host           */
#define TERM_SPEAK         0x0002 /* Speak local terminal input  */
#define TERM_EDITED        0x0004 /* Edited                      */
#define TERM_HARD          0x0008 /* Local terminal is hardcopy   */
#define TERM_SETUPSPEAK    0x0010 /* Spoken setup mode          */
#define TERM_FILTER        0x0020 /* Filter logged esp. sequences */

```

```

/*
 * Mode flags for the P2_MODE command.
 */

#define MODE_SQUARE    0x0001 /* [ ] are phonetic brackets */
#define MODE_PSKY     0x0002 /* Use ASKv alphabet */
#define MODE_MINUS    0x0004 /* "-" is pronounced "minus" */

/*
 * Flags for dt_splice() and ((DECtalk *dt)->flag)
 */

#define SPLICE_SPEAK    0x0001 /* Speak text if set */
#define SPLICE_LOQ     0x0002 /* Log rawhost if set */
#define SPLICE_TERM    0x0004 /* Local host if set */
#define _FLAG_SPEAK    0x0001 /* Speaking, set by dt_splice() */
#define _FLAG_LOQ     0x0002 /* Log rawhost from dt_splice() */
#define _FLAG_TERM    0x0004 /* Term host from dt_splice() */
#define _FLAG_EIGHTBIT 0x0008 /* Read eight-bit Cv controls */

/*
 * These macros and structure definitions are used by the escape
 * sequence parser.
 */

#define SEQ_INTMAX      2      /* Max. # of intermediates */
#define SEQ_PARMAX     16     /* Max. # of parameters */

/*
 * dt_getseq() (get escape sequence) and dt_send() (put escape
 * sequence) use this structure for all processing.
 */

typedef struct {
    short    state;          /* Processing state or intro */
    char     final;          /* Final character in seq. */
    char     private;        /* Private introducer */
#ifdef decus
    unsigned param(SEQ_PARMAX+1);
#else
    unsigned short param(SEQ_PARMAX+1);
#endif
    char     inter(SEQ_INTMAX+1); /* Intermediate count, values */
} SEQUENCE;

/*
 * The DECTALK structure is used to maintain all information
 * needed to produce a DECTalk device. It is allocated by
 * dt_open(), freed by dt_close() and a required parameter
 * by essentially all routines.
 */

```

```

#ifdef RAX
/*
 * The qio parameter block controls all RSX11-M I/O requests.
 */
typedef struct qioperm {          /* QIO parameter block */
    char    *buffer;              /* Buffer location */
    int     size;                 /* Bytes to transfer */
    char    *p3;                 /* For ctrl/c ast */
    char    *table;              /* Terminator table */
    int     unused[2];           /* Not used here */
} QIOPARM;

/*
 * The iio status block receives the status of all I/O requests.
 */
typedef struct iio {              /* I/O status block */
    char    status;              /* Operation status */
    char    terminator;          /* Input terminator byte */
    int     count;               /* Bytes read from device */
} IOSEB;
#endif

#ifdef PEND_SIZE
#define PEND_SIZE 32              /* Pending buffer size */
#endif
#ifdef IN_BUFLen
#define IN_BUFLen 32
#endif
#ifdef OUT_BUFLen
#define OUT_BUFLen 128
#endif
#if IN_BUFLen < 1 || OUT_BUFLen < 1 || PEND_SIZE < 1
    << error, mandatory parameters aren't correct >>
#endif

typedef struct DECTalk {
    struct DECTalk *link;         /* Chain all units together */
    short    unit;               /* I/O channel */
    short    timeout;            /* For d1_timeout() */
    short    flags;              /* Speed and "splice" flags */
    short    pend_tos;           /* Bytes in pending buffer */
    short    pend_fp;            /* Pending buffer fill index */
    short    pend_ep;            /* Pending buffer empty index */
    char    *in_ptr;             /* I/O input buffer pointer */
    char    *in_end;             /* -> end of input buffer */
    char    *out_ptr;            /* -> free spot in output buff. */
    SEQUENCE send;               /* Last sequence sent */
    SEQUENCE reply;              /* Last sequence read */
    SEQUENCE seq;               /* Sequence look-ahead */
    char    *device;             /* DECTalk hardware device */
    char    pend[PEND_SIZE];     /* Type-ahead ring buffer */
    char    in_buff[IN_BUFLen]; /* I/O input buffer */
    char    out_buff[OUT_BUFLen]; /* I/O output buffer */
}

```

```

/*
 * The following entries are operating-system specific.
 */
#ifdef unix
#ifdef BSD_42
    struct sgttyb stty_saves; /* Terminal flags */
#else
#ifdef UNIX_V
    struct termio stty_saves; /* Terminal flags (UNIX V7) */
#endif
#endif
#endif
#ifdef rx
    FILE      *fildes; /* File descriptor */
    IOSB      iosb; /* I/O status block */
    QIDPARAM  parms; /* QID parameter block */
    short      pos_xls; /* Device characteristics word */
#endif
} DECTALK;

/*
 * Certain short routines and common tests are expressed as
 * macros. In all instances, 'dd' is a DECTalk I/O descriptor
 * as returned by dt_open(). Note that the arguments should
 * not have "side-effects".
 *
 * dt_iskey(dd) TRUE if something in type-ahead buffer.
 * dt_isvalid(c) TRUE if argument is a valid keypad key.
 *
 * The following are only useful after executing dt_phone().
 *
 * dt_test(dd, r3) TRUE if specific phone reply.
 * dt_offhook(dd) TRUE if last DECTalk reply is OFFHOOK.
 * dt_onhook(dd) TRUE if last DECTalk reply is ONHOOK.
 * dt_timeout(dd) TRUE if last DECTalk reply is TIMEOUT.
 *
 * The following simple commands may be written as macros:
 *
 * dt_phone(dd,p3,p4) Send a phone message.
 * dt_get(dd, c) Read a character (with timeout)
 * dt_put(dd, c) Send a character in DECTalk
 * dt_eol(dd, c) Send "end of line", flush output buffers
 *
 * If DT_DEBUG is defined, dt_get() and dt_put() are functions
 * which may log all characters to the standard output stream.
 */

```

```

#ifdef DT_DEBUG
#define dt_get      dt_input
#define dt_put      dt_output
#endif
#ifdef nonacarg
#define dt_iskey(dd) (dd->pend.fc != 0)
#define dt_isvalid(c) ((c >= '0' && c <= '9') \
                      || c == '*' || c == '+' \
                      || c == 'A' && c <= 'D'))
#define dt_please(dd,r3) (dt_wait(dd, R2_PHONE, r3))
#define dt_offhook(dd) (dt_please(dd, R3_PH_OFFHOOK))
#define dt_onhook(dd) (dt_please(dd, R3_PH_ONHOOK))
#define dt_timeout(dd) (dt_please(dd, R3_PH_TIMEOUT))
#define dt_phone(dd,p3,p4) (dt_msg(dd, \
                                   P2_PHONE, p3, p4, R2_PHONE, -1))
#endif
#ifdef onix
#define dt_echo(dd) (dt_put(dd, '\n'), dt_put(dd, 0))
#else
#define dt_echo(dd) (dt_put(dd, '\n'), \
                    dt_put(dd, '\n'), dt_put(dd, 0))
#endif
#endif
#ifdef decus
#ifdef DT_DEBUG
/*
 * This forces traceback on Decus C systems.
 */
#define exit      error
#define IO_ERROR  "fatal DECtalk I/O error"
#endif
#endif
#ifdef IO_ERROR
#ifdef vms
#include <ssdef.h>
#define IO_ERROR  SS1_ABORT
#else
#define IO_ERROR  2
#endif
#endif
/*
 * dt_abort may be set by a user program at any time to
 * stop DECtalk. Typically, it would be set by dt_trap()
 * when a CTRL/C (UNIX INTERRUPT signal) is typed by the
 * terminal user.
 */
extern int dt_abort; /* Set TRUE to stop */
extern DEC_TALK *dt_root; /* Root of device chain */
#ifdef DT_DEBUG
extern int dt_debug; /* TRUE if debug log */
#endif

```

DEMO.C

The executable program's name is DEMO, derived from this program. DEMO.C is the main module of the program.

```
#include <stdio.h>
#include "demo.h"

main(argc, argv)
int argc;
char *argv[];
{
    register DECTALK *dt; /* DECTalk device */
    register int retries; /* Initializations */
    register int ncalls; /* Completed calls */
    char *dev;
    extern DECTALK *dt_open();

    dev = "TT2";
    if (argc > 1)
        dev = argv[1];
    retries = 0;
    ncalls = 0;
    dt_debug = TRUE;
    if ((dt = dt_open(dev)) == NULL) {
        perror(dev);
        return;
    }
    dt_trap(); /* Catch CTRL-C abort */
    while (dt_init(dt)) { /* One-time setup */
        dt_dcs(dt, RS_MODE, MODE_SQUARE, -1);
        retries++; /* Count attempts */
        while (dt_answer(dt, 1)) { /* Answer the phone */
            if (dt_process(dt)) { /* Do user process */
                ncalls++; /* User ran ok. */
                retries = 0; /* Clear retry count */
            }
            dt_hangup(dt); /* Hangup the phone */
            if (dt_abort()) /* Check interrupt */
                goto finish; /* Error exit */
        }
        if (dt_abort())
            goto finish; /* Error exit */
        if (retries > 2) { /* Got lost? */
            printf("Too many retries\n");
            break;
        }
    }
    fprintf(stderr, "Shouldn't initialize DECTalk\n");
}
```

```

    finish: dt_abort = FALSE;          /* Restart output */
    dt_reset(dt);                      /* Hangup DECtalk */
    dt_put(dt, 0);                     /* Force out buffer */
    dt_close(dt);                      /* Close up DECtalk */
}

process(dt)
register DECTALK *dt;
{
    register char c;                  /* Keypad character */
    char work[30];                    /* For echo message */

    dt_talk(dt, "Welcome to DECTalk");
    if (!dt_keypad(dt, TRUE))          /* Enable keypad */
        return (FALSE);               /* Error occurred */
    for (;;) {                         /* Do forever... */
        c = dt_inkey(dt, 15);          /* key with timeout */
        if (!dt_isvalid(c))             /* Check for timeout */
            break;                     /* Exit if so */
        sprintf(work, "You pressed %c", c);
        dt_talk(dt, work);
        if (c == '^') {                 /* Meta ^^ special */
            dt_timeout(dt, 0);          /* No timeouts now */
            dt_talk(dt, "Long message...");
        }
    }
    /*
     * Timeout is normal, others are errors.
     */
    return ((c == '^') ? TRUE : FALSE);
}

```

DTANSW.C

This routine hangs up the phone and answers on n rings.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_answer      Answer the Telephone
index               Answer the telephone
```

synopsis

```
#include <stdio.h>
#include "dectlk.h"
int
dt_answer(dt, nrings)
DECTALK *dt; /* Device descriptor */
int nrings; /* Number of rings */
```

description

Hang up the phone (by calling dt_hangup()) and answer the phone after the specified number of rings.

Return TRUE if successful, FALSE if in error.

#endit

```
#include <stdio.h>
#include "dectlk.h"

int
dt_answer(dt, nrings)
register DECTALK *dt;
int nrings;
/*
 * Hang up the phone and answer on nrings.
 */
{
    register int code;

again: if (!dt_hangup(dt)) /* Make sure it's */
        return (FALSE); /* on-hook. */
    dt_devctl(dt, P2_PHONE, P3_PH_ANSWER, nrings);
    while (dt_read(dt, 0), dt_onhook(dt)) {
        if (dt_abort)
            return (FALSE);
    }
    if (dt_onhook(dt))
        goto again;
    if (!dt_offhook(dt)) /* Did it answer ok? */
        return (FALSE);
    /*
     * OK, clear timeout flag and type-ahead counters.
     */
    dt->timeout = 0;
    dt->pend_lo = dt->pend_lo = dt->pend_lo = 0;
    return (TRUE);
}
```

DTCLOS.C

This routine closes the DECTalk channel and frees all buffers.

```

/*) LIBRARY
*/

#ifdef DOCUMENTATION

title dt_close      Terminate DECTalk Operation
index              Terminate DECTalk Operation

synopsis

        #include      <stdio.h>
        #include      "dectlk.h"

        dt_close(dt)
        DECTALK      *dt; /* DECTalk device */

description

        Close the DECTalk channel and free all buffers.
        No error is returned.

#endif

#include      <stdio.h>
#include      "dectlk.h"

#ifdef rx
#include      <rx.h>
#include      <qiofun.h>
#include      <qioext.h>
#include      <qiocttd.h>
#define RIDEFM 1
#endif

static QIDPARM noparm; /* QID parm (all zero) */
#endif

dt_close(dt)
register DECTALK      *dt;
/*
 * Close the DECTalk channel.
 */
{
        register DECTALK      **linfo;

#ifdef unix
#ifdef BSD_42
        sity(dt->unit, dt->sity_save); /* Restore tty flags */
#else
        UNIST_V
        scttldt->unit, TCSETA, dt->sity_save); /* Restore tty flags */
#endif
#endif
}

```

```

#endif
    close(dt->unit);
#endif
#ifdef vms
    sys$dassign(dt->unit);
#endif
#ifdef null
    rs_close(dt->unit);
#endif
#ifdef rx
    qlow(10LDET, dt->unit, 010LERN, NULL, NULL, #noperm);
    fclose(dt->files);
#endif
/*
 * Unlink the device from the chain.
 */
for (linkp = &dt_root; *linkp != NULL;
     linkp = &(*linkp->link)) {
    if (*linkp == dt) {
        *linkp = dt->link;
        break;
    }
}
free(dt->device);
free((char *)dt);
return (NULL);
}

```

DTCMD.C

This routine sends a DCS command to the DECTalk terminal.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_end          Send DCS w/o String Terminator
index                Send DCS w/o string terminator
```

```
synopsis
```

```
    #include          <stdio.h>
    #include          "dectalk.h"

    int
    dt_end(dt, p2, p3)
    DECTALK            *dt;    /* Device descriptor */
    int                p2;     /* P2... parameter */
    int                p3;     /* P3... parameter */
```

```
description
```

This routine sends a DCS command to the DECTalk terminal. The string terminator is not sent. This is needed to send phonetic text or telephone dial commands.

The p2 or p3 parameter may be -1 if it is to be omitted.

A phonetic text sequence would be sent as follows.

```
    dt_end(dt, p2, p3);
    dt_talk(dt, "hh'ehlow.");
    dt_at(dt);
```

```
#endif
```

```
#include          <stdio.h>
#include          "dectalk.h"
```

```
static SEQUENCE command = {
    DCS, DCS_F_DECTALK, 0, { 3, P1_DECTALK, 0, 0 }
};
```

```
dt_end(dt, p2, p3)
register DECTALK    *dt;    /* Device descriptor */
int                p2;     /* P2...command or -1 */
int                p3;     /* P3...command or -1 */
```

```
/*  
 * Send a DCS command, no string terminator  
 */  
{  
    if (p2 == -1)  
        command.param[0] = 1;  
    else if  
        command.param[2] = p2;  
        if (p3 == -1)  
            command.param[0] = 2;  
        else if  
            command.param[0] = 3;  
            command.param[9] = p3;  
        }  
    }  
    dl_send(d1, &command);  
}
```

DTDCHAR.C

This routine formats characters into a visible ASCII datascopes format and writes the resulting text to the indicated file. Note that this routine is independent of DECTalk definitions. Output is via the C standard library. Dumps to terminals are unbuffered.

```
/*>LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_dchar          Dump One Character Visibly
index      :            Dump one character visibly
```

```
synopsis
```

```
    #include      <stdio.h>

    dt_dchar(c, iow)
    int          c;          /* Character to dump      */
    FILE         *iow;       /* File to write to  */
```

```
description
```

The character is formatted into a visible ASCII Datascopes format and the resulting text written to the indicated file.

Note that this routine is independent of DECTalk definitions.

Output is via the C standard library. If the dump is to a terminal, it is unbuffered.

```
#endif
#include      <stdio.h>

dt_dchar(c, iow)
register int    c;
register FILE   *iow;
/*
 * Dump a character.
 */
{
    char        work[12];

    dt_visible(c, work);
    fprintf(iow, "%s", work);
    if (!isatty(fileno(iow)))
        fflush(iow);
}
```

DTDCS.C

This routine sends a DECTalk DCS control sequence using the p2, p3, and p4 parameters. Pn parameters are -1 if not sent. No errors are possible.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_dcs      Send a DECTalk DCS Command
index            Send a DECTalk DCS command
```

```
Synopsis
```

```
    #include      <stdio.h>
    #include      "dectlk.h"

    dt_dcs(dt, p2, p3, p4)
    DECTALK      *dt;      /* Device descriptor      */
    int          p2;      /* P2_xxx parameter      */
    int          p3;      /* P3_PH_xxxx parameter  */
    int          p4;      /* timeout or rings      */
```

```
Description
```

This routine sends a DECTalk DCS control sequence using the p2, p3, and p4 parameters.

Note that the Pn parameters are -1 if they are not sent.

No errors are possible.

```
#endif
```

```
#include      <stdio.h>
#include      "dectlk.h"
```

```
static SEQUENCE DT_string_terminator = {
    ST                                /* String terminator      */
};
```

```
dt_dcs(dt, p2, p3, p4)
register DECTALK *dt;      /* Default device      */
int            p2, p3, p4; /* Parameters to send  */
```

```

/*
 * Load the parameter buffer and send the sequence.
 * dt->send.param[0] contains the number of additional parameters.
 */
{
    dt->send.state = DCS;
    dt->send.final = DCS_F_DECTACK;
    dt->send.private = 0;
    dt->send.interl0 = 0;
    dt->send.param[0] = 1;
    if (p2 >= 0) {
        dt->send.param[0]++;
        dt->send.param[2] = p2;
    }
    if (p3 >= 0) {
        dt->send.param[0]++;
        dt->send.param[3] = p3;
    }
    if (p4 >= 0) {
        dt->send.param[0]++;
        dt->send.param[4] = p4;
    }
    dt->param(dt, dt->send);
    dt->param(dt, $DT_string_terminator);
}

```

DTDIAL.C

This routine dials the DECTalk telephone, depending on whether the telephone used is Touch-Tone or pulse type.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dtdial.c      Dial the telephone
index              Dial the telephone
```

synopsis

```
#include <stdio.h>
#include "dectlk.h"

int
dtdial(cot, p3, numb, wait, msg)
DECTALK *dt; /* Device descriptor */
int p3; /* P3_PH_XXXX parameter */
char *numb; /* Number to dial */
int wait; /* See below */
char *msg; /* Announcement */
```

description

This routine dials the DECTalk telephone. The P3 parameter must be either P3_PH_TONE (tone dial) or P3_PH_PULSE (pulse dial).

For tone dialing, the number text may contain any valid touch-tone characters ("0123456789*#ABCD") or the characters '?' (for a one second delay) or the '^' for a 250 millisecond switch-hook flash. All other characters are ignored.

If pulse dialing is selected, only the digits, '*' and '^' are interpreted.

Note that the telephone will not be hung up before dialing if it is offhook when the command is issued.

Call Progress Detection

DECTalk cannot tell if or when someone answers the phone. The only way to do this is to speak a message, such as "This is DECTalk, please press any button on the keypad," and wait some limited time for the person to press the button. The wait and msg parameters provide this capability.

If wait is less than or equal to zero, DECTalk returns without attempting to verify that someone has answered the phone. The return will be TRUE if the phone is offhook.

If wait is greater than zero, it specifies the number of seconds to wait for a response, and msg is the message to speak. (If msg is NULL, the sample text shown above will be used.) The message is repeated continuously until either the allotted time has elapsed or a button is received. dt_dial() then returns TRUE if the phone is offhook, as above.

To cause DECTalk to silently wait for a message, use a zero-length string (""). Note, however, that an audible message is required by some public telephone systems.

When DECTalk returns after call progress detection, keypad data entry and keypad timeout will be disabled.

```
#endif

#include <stdio.h>
#include "dectalk.h"

#define ANNOUNCEMENT "This is DECTalk, please press any key."

int
dt_dial(dt, p3, number, wait, message)
register DECTALK *dt; /* Device descriptor */
int p3; /* P3_PH_PULSE or TONE */
register char *number; /* Number to dial */
int wait; /* Call progress delay */
char *message; /* Announcement */
```

```

/*
 * Send a phone message.
 */
{
    register int    code;
    int            dialtime; /* Time to dial phone */
    long           endtime;
    extern long     time();

    if (number == NULL) /* Paranoia, */
        number = ""; /* Ahh, paranoia */

    dt_cmd(dt, P2_PHONE, p3);
    dialtime = strlen(number);
    if (p3 == P3_PH_PULSE)
        dialtime *= 2;
    while (*number != EOS) /* Send the number */
        dt_put(dt, *number--);
    dt_wt(dt);
    do {
        code = dt_read(dt, dialtime + 30);
    } while (code == ST || dt_save(dt, code));
    if (wait < 0)
        return (dt_offhook(dt));
    /*
     * Call progress detection.
     */
    if (!dt_offhook(dt) || !dt_keypad(dt, TRUE))
        return (FALSE);
    endtime = time(NULL) + wait + 1;
    if (message == NULL)
        message = ANNOUNCEMENT;
    do {
        dt_tell(dt, message); /* Speak announcement */
        dt_put(dt, VT); /* Make sure it's heard */
    } while ((code = dt_read(dt, 5)) < 0
        || time(NULL) <= endtime);
    dt_dcs(dt, P2_STOP, -1, -1); /* Enough already */
    if (dt_isvalid(code)) { /* User key? */
        dt_keypad(dt, FALSE); /* Turn off keypad and */
        dt_drain(dt); /* Drop pending text */
        return (TRUE); /* Normal return */
    }
    else if (dt_phone(dt, -1, -1), dt_offhook(dt))
        dt_hangup(dt); /* No response, hangup */
    return (FALSE);
}

```

DTDRAIN.C

This routine absorbs any type-ahead characters. No errors are possible.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_drain Drain Pending Input
index Drain pending input
```

```
synopsis
```

```
    #include <stdio.h>
    #include "dectlk.h"

    dt_drain(dt)
    DECTALK      *dt; /* Device descriptor */
```

```
description
```

Absorb any type-ahead characters.
No errors are possible.

```
note
```

On UNIX systems, dt_drain() will also cancel pending output. This may cause DECTalk to receive word fragments or partial escape sequences.

The code is conditionally compiled for two varieties of UNIX: Ultrix-32 (or 4.2 BSD) and UNIX System V. Other varieties of UNIX and UNIX-like systems may need to edit this file.

```
#endif
```

```
#include <stdio.h>
#include "dectlk.h"
```

```
#ifdef unix
```

```
dt_drain(dt)
register DECTALK      *dt;
/* dt_drain() tosses out any pending type-ahead.
*/
```

```
{
    dt->pend_fc = dt->pend_fp = dt->pend_lp = 0;
```

```
#ifdef BSD_42
    tctlk(dt->unit, TIOCFUSH, NULL);
```

```
#else
```

```
#ifdef UNIX_V
    tctlk(dt->unit, TIOCFUSH, 0); /* UNIX V? */
```

```
#endif
```

```
#endif
    dt->in_ptr = dt->in_end = dt->in_buff;
}
```

```
#endif
```

```

#ifdef vax
#include <ioctl.h>
dt_drain(dt)
register DECTALK *dt;
/*
 * dt_drain() tosses out any pending type-ahead.
 */
{
    dt->pend_fp = dt->pend_bp = dt->pend_ep = 0;
    /*
     * This is probably sub-optimal. It should be possible
     * to do "sysfqlowt..."
     * [O%_READBLK | IO%_PURGE | IO%_TIMED
     * with a zero-length timeout, but I sure don't know.
     */
    while (fcntl_vmrread(dt,
        [O%_READBLK | IO%_NOECHO | IO%_NOFILTR | IO%_TYMCD,
        IO%_BUFLN, 0] >= IO%_BUFLN)
    {
        dt->in_ptr = dt->in_end = dt->in_buff;
    }
}

#ifdef rtd1
#include <rtm.h>

dt_drain(dt)
register DECTALK *dt;
/*
 * dt_drain() tosses out any pending type-ahead.
 */
{
    dt->pend_fp = dt->pend_bp = dt->pend_ep = 0;
    clrxbf();
    xrb.xrten = 7; /* Cancel type-ahead */
    xrb.xrcr = dt->uncl + 2;
    xrb.xrbitm = TTYHND;
    rtisysf(SPSC);
    dt->in_ptr = dt->in_end = dt->in_buff;
}

#endif

#ifdef rax
dt_drain(dt)
register DECTALK *dt;
/*
 * dt_drain() tosses out any pending type-ahead.
 */
{
    dt->pend_fp = dt->pend_bp = dt->pend_ep = 0;
    do {
        dt->in_ptr = dt->in_end = dt->in_buff;
    } while (dt->getf(dt, 1) > 0);
    dt->in_ptr = dt->in_end = dt->in_buff;
}

#endif

```

DTDUMP.C

This routine writes an escape sequence buffer to the standard output file. This mode is for debugging.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_dump      Dump Escape Sequence Buffer
index             Dump escape sequence buffer
```

synopsis

```
#include <stdio.h>
#include "dectlk.h"

int
dt_dump(what, seq)
char *what; /* Explanation */
SEQUENCE *seq; /* Buffer to dump */
```

description

The requested escape sequence buffer is written (visibly) to the standard output file.

If what is not NULL, it is written as an identifier.

Output is via the C standard library.

For example,

```
#include <stdio.h>
#include "dectlk.h"

DECTALK *dt;
extern DECTALK *dt_open();

...
/*
 * Open a DECTalk device,
 * request phone status and
 * dump returned status sequence.
 */
dt = dt_open("/dev/b2:");
dt_phone(dt, P2_PH_STATUS, -1);
dt_dump("status", dt->reply);
```

```
#endif
```

```
#include <stdio.h>
#include "dectlk.h"
```

```

dt_dump(what, seq)
char          *what;
register SEQUENCE *seq;
{
    register int      i;
    register char     *wp;
    char            work[81];
    extern char       *dt_visible[];

    if (what != NULL)
        printf("%s: (%s, %s)", what, what);
    wp = dt_visible(seq->state, work);
    switch (seq->state) {
    case ESC:
    case CSI:
    case DCS:
        if (seq->private != 0)
            wp = dt_visible(seq->private, wp);
        for (i = 1; i <= seq->param[0]; i++) {
            if (i > 1)
                *wp++ = '|';
            if (seq->param[i] != 0) {
                sprintf(wp, "%u", seq->param[i]);
                wp += strlen(wp);
            }
        }
        for (i = 1; i <= seq->inter[0]; i++)
            wp = dt_visible(seq->inter[i], wp);
        break;
    default:
        break;
    }
    if (seq->final != 0)
        wp = dt_visible(seq->final, wp);
    *wp = EOS;
    printf("(%s%s", work, (what == NULL) ? "" : " "); printf("\n");
}

```

DTEOLC

This routine writes an end of line to DECTalk and calls the operating system executive service to write the local output buffer to the terminal. No value is returned.

You need this routine on operating systems that enforce line wraparound on the terminal. DTEOLC also improves the appearance of the debugging logs.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION

title dt_eol:      Write End of Line to DECTalk
index             Write End of Line to DECTalk

synopsis

#include <stdio.h>
#include <dectlk.h>

dt_eol(dt)
DECTALK      *dt; /* Device descriptor */

description

An "end of line" is written to DECTalk and the
operating system executive service is called to
cause the local output buffer to be written to
the terminal.

No value is returned.

This routine is needed on operating systems that
enforce "line wrap-around" on terminal devices.
It also improves the appearance of debugging logs.

#endif

#include <stdio.h>
#include <deotlk.h>

#ifdef dt_eol
#undef dt_eol
#endif

dt_eol(dt)
register DECTALK      *dt; /* Device descriptor */
{
#ifdef unix
    dt_put(dt, "\n");
#endif
    dt_put(dt, "\n");
    dt_put(dt, 0);
}

```

DTGESC.C

This routine reads an escape sequence or keypad character.

```
/*LIBRARY
*/
```

```
/*DEF DOCUMENTATION
```

```
title dt_gesc      Read Escape Sequence or Character
index      Read escape sequence or character
```

synopsis

```
#include      <stdio.h>
#include      "dtlib.h"

int
dt_gesc(dt, seq)
DECTALK      *dt;      /* Device descriptor */
char         seq;      /* O.S. timeout value */
```

description

Read an escape sequence or keypad character.

`dt_gesc()` interprets a stream of 7- or 8-bit characters including escape sequences adhering to the coded representations of ISO 646, ISO 2022, and ISO 6429 with extensions to the DCS introducer as required by DEC Standard 138.

The function `dt_gesc()` recognizes ESC, CSI, and DCS, and processes characters following each of these introducers until a complete sequence is encountered. In the case of DCS, control returns to the caller after the final character of the DEC Standard 138 introduction sequence, but before the first data character of the device control string.

When sandwiched between the application and a get character function (`dt_get()`), `dt_gesc()` transforms the input stream from a character stream to a stream of tokens consisting of characters, escape sequences, control sequences, and DCS introduction sequences. When any of the recognized sequence types is encountered, the function value returned is that of ESC, CSI, or DCS, and the interpreted body of the sequence is returned in the `seq` structure. The caller may treat `dt_gesc()` similarly to `getchar()`, ignoring the returned structure in all cases except when the returned function value is ESC, CSI, or DCS.

An additional function performed by `dl_getc()` is that all C1 control functions received in their 7-bit form are returned to the caller in their 8-bit form, thus eliminating the need for the caller to process C1 control functions in their (7-bit) escape sequence form and enforcing the equivalence of the 7-bit and 8-bit forms of the C1 control functions. The function also enforces the sequence cancellation effect of the SUB and CRM control characters.

The `dl_getc()` function calls the user-supplied `dl_get()` (read one character) function as many times as required to complete an escape sequence, control sequence, or Digital standard DCS introduction sequence. In the passed data structure, it returns the final character, intermediate characters, and parameter values.

Since 7-bit operation is a compatible subset of 8-bit operation, there is -- normally -- no distinction in the `dl_getc()` function between the two environments. The application program may set the `_FLAG_EIGHTBIT` bit in `dl_tflag` to receive C1 control characters in their eight-bit form. If `_FLAG_EIGHTBIT` is set on, the application program must also ensure that the host operating system communication line receives eight data bits, and that DECtalk setup has set `HOST FORMAT EIGHT`.

Also, `dl_getc()` may return two special values, `DLEERR` and `DL_TIMEOUT`, to indicate operating-system errors and communication line timeouts respectively.

Because C0 control characters may be embedded in sequences, and must be interpreted as if they occurred before the sequence in the stream, the `dl_getc()` function retains internal state information in the sequence data structure from call to call. The `seq.state` value is zero on return to indicate a complete escape sequence. If non-zero, it contains the sequence introducer.

If the "seq.state" element is zero, `dl_getc()` assumes that the remainder of the data structure is invalid and that there is no data being retained from a prior call. A non-zero value for the "seq.state" element indicates a particular internal state (ESC, CSI, or DCS) that the parser should assume on the next call. Intermediate characters and parameter values interpreted up to the occurrence of the embedded control character are also stored in the returned data structure and also should not be altered by the caller.

Escape sequence syntax errors are indicated by setting the `seq.private` parameter to 'X' (which is not a possible private parameter).

If the `dt_gene()` function encounters more than the allowed maximum number of intermediate characters, the returned data structure indicates that one more intermediate character was received than allowed. Of course, characters after the maximum are not stored.

If the `dl_getsol()` function encounters more than the allowed maximum number of parameters, the extra parameters are ignored and the returned data structure indicates that the allowed maximum number of parameters was received.

After each call to `di_gwact()` the `di-aseq` SEQUENCE contains the following information.

seq.start	Zero to indicate complete sequence
seq.final	The sequence final character
seq.private	Private parameter character; EOS, <, =, >, ?, or X for errors
seq.param[0]	The number of parameter values (0:SEQ_PARMAX)
seq.param[i]	(unsigned) The n th parameter value
seq.inter[0]	The number of intermediate characters (0:SEQ_INTMAX+1)
seq.inter[n]	(char) The n th intermediate character

In general, the intermediate and final characters should be taken as a whole to determine the action. It is easy to ignore sequences with too many intermediate characters since the returned number of intermediate characters will not match any action function.

To simplify the code, this module doesn't test for overly large parameter values and assumes that all overflow errors are due to invalid escape sequences.

```

#ifdef
#include <stdio.h>
#include "decslik.h"

int
dt_gwafdi, sec)
register DECTALK
int dt; /* Decslik device */
sec; /* B.G. timeout */

```

```

/*
 * Return a character or sequence
 */
{
    register int c;
#ifdef DECUS
    register unsigned *p;
#else
    register unsigned short *p;
#endif
#ifdef DT_DEBUG
    if (dt_debug) {
        dt_put(dt, 0);
        printf("get: \n");
        if (!isatty(fileno(stdout)))
            fflush(stdout);
    }
#endif
    for (;;) {
        /*
         * Loop until end of sequence forces an exit.
         * Get the next character from the input stream.
         * Note: we assume that negative values are
         * "out of band" signals.
         * Note that DT_TIMEOUT and DT_ERR must be negative values.
         */
        if ((c = dt_get(dt, sec)) > 0) {
            if ((dt->flag & FLAG_EIGHTBIT) == 0)
                c &= 0x7f; /* Enforce 7-bit input */
        }
        if (c == NUL || c == DEL)
            continue; /* Ignore NUL, DEL */
        /*
         * Branch to c1_continue when changing <ESC>
         * to CSI, etc.
         */
        if (c == ESC)
            continue; /* ESC, CSI, DCS */
        if (c == CSI)
            /* Introduce control */
        if (c == DCS) {
            /* sequence */
            dt->seq.state = 0;
            dt->seq.instr[0] = 0;
            dt->seq.prmval = 0;
            dt->seq.prm[0] = 0;
            dt->seq.prm[1] = 0;
            continue;
        }
    }
}
c1_continue:

```

```

else if (dt->seq.state == 0) /* No pending sequence */
    goto exit; /* Return the character */
else if ((c >= 0x80 && c <= 0xBF) /* C1 control */
        || (c == CAN) /* or sequence */
        || (c == SUB)) { /* reseller. */
    dt->seq.state = 0;
    goto exit;
}
else if (c <= 0x20) /* C0 control or error */
    goto exit;
else if (c <= 0x2F) { /* Intermediate */
    dt->seq.inter[0]++;
    if (dt->seq.inter[0] < SEQ_INTMAX)
        dt->seq.inter[dt->seq.inter[0]] = c;
}
else if (dt->seq.state == ESC) { /* ESC final */
    if (dt->seq.inter[0] == 0 && (c & 0x3F) < 0x20) {
        /*
         * This is the 7-bit form of a C1 control
         * character. Convert it to the actual
         * C1 control character and restart the
         * parse without getting another character.
         */
        n = (c & 0x3F) + 0x80;
        goto c1_continues;
    }
    else {
        break; /* Ordinary ESC ending */
    }
}
else if (c <= 0x3F) { /* Parameter */
    if (c >= 0x30) { /* Private introducer? */
        if (dt->seq.param[0] > 0) /* Is it first? */
            dt->seq.private = 'X'; /* error if not */
        else {
            dt->seq.private = 0; /* Store it */
            dt->seq.param[0]++; /* Flag seen */
        }
    }
    else {
        /* Not private */
        if (dt->seq.param[0] == 0)
            dt->seq.param[0]++; /* Record first */
        if (dt->seq.inter[0] != 0) {
            dt->seq.inter[0] = 0; /* Syntax error */
            dt->seq.private = 'X';
        }
    }
}

```

```

    if (c <= '9') { /* 0..9 */
        if (dt->seq.param[0] <= SEQ_PARMAX) {
            /*
             * There is room. Store it.
             *
             * a points to current parameter.
             * This should check for value
             * overflow.
             */
            p = &(dt->seq.param[dt->seq.param[0]]);
            *p = (*p * 10) + (c - '0');
        }
        else {
            dt->seq.private = 'f';
        }
    }
    else if (c == ':') { /* Separator */
        if (dt->seq.param[0] >= SEQ_PARMAX)
            dt->seq.param[0] = SEQ_PARMAX + 1;
        else {
            /*
             * There's room to setup for
             * another parameter value.
             */
            dt->seq.param[0]++;
            dt->seq.param[dt->seq.param[0]] = 0;
        }
    }
    else { /* colon is invalid */
        dt->seq.private = 'X';
    }
}
else { /* CBT/DOB terminator */
    if (dt->seq.param[0] == 0) /* No parameters: */
        dt->seq.param[0]++; /* want one zero-value */
    break; /* Exit parser */
}
/*
 * Control transfers to here as result of either of the
 * two break statements. Character is the final char.
 * of ESC, CBT, or DOB.
 */
if (dt->seq.param[0] > SEQ_PARMAX) {
    dt->seq.param[0] = SEQ_PARMAX; /* Set count to max. */
    dt->seq.private = 'X'; /* Flag an error */
}
dt->seq.final = c; /* Store final char. */
#ifdef DEBUG
c = dt->seq.state; /* Fetch return value */
#else
c = (unsigned short) dt->seq.state;
#endif

```

```
#endif
    dt->seq.state = 0; /* No sequence pending */
    exit; /* Here to return char */
#endif
    if (dt_debug)
        printf("%s\n", dt_debug);
#endif
    return (c); /* and return. */
}
```

DTGET.C

This routine reads a character from the DECtalk terminal line.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_get      Read one Character from DECtalk
index             Read one character from DECtalk
```

synopsis

```
#include <stdio.h>
#include "decstk.h"

int
dt_get(dt, sec)
DECtalk *dt; /* Device descriptor */
int sec; /* D.S. timeout param. */
```

description

One character is read from the DECtalk terminal line. The sec parameter enables operating-system timeout; it is zero if no timeout is needed.

dt_get() returns the character or an error code.

```
DT_ERROR      An operating system error
               (or CTRL-C interrupt) was received.
DT_TIMEOUT    The sec parameter was nonzero and no
               character was received in sec seconds.
```

If DT_DEBUG is #defined when the library is compiled and the global dt_debug is set nonzero (by the application program), the character received is logged to the standard output device.

```
#endif
```

```
#include <stdio.h>
#include "decstk.h"
```

```
#ifdef dt_get
#undef dt_get
#endif
```

```
int dt_debug;

int
dt_get(dt, sec)
register DECTALK *dt; /* Device descriptor */
int *sec; /* Operating system timeout */
{
    register int c;

    extern int dt_debug;

    c = dt_getc(dt, sec);
    if (dt_debug != 0)
        dt_debug(c, sec);
    return (c);
}
```

DTHANG.C

Hang up the telephone connected to DECTalk.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION

title    dt_hangup      Hangup the telephone
index    Hangup the telephone

synopsis

        #include      <stdio.h>
        #include      "dectlk.h"

        dt_hangup(dt)
        DECTALK        *dt;    /* Device descriptor */

description

        Hang up the telephone connected to DECTalk.
        Return TRUE if successful, FALSE if an error.

#endif

#include      <stdio.h>
#include      "dectlk.h"

int
dt_hangup(dt)
register DECTALK    *dt;
/*
 * dt_hangup() hangs up the phone.
 */
{
    register int    codes;

    dt_drain(dt);    /* Drain pending text */
    if (!dt_phone(dt, P3_PH_STATUS, -1)) /* Check state */
        return (FALSE);    /* Oops */
    if (dt_offhook(dt)) {    /* If it's not hung up */
        if (!dt_phone(dt, P3_PH_HANGUP, -1))
            return (FALSE);    /* Couldn't hangup? */
        while (dt_offhook(dt)) {    /* While still off-hook */
            if (dt_abort)    /* Exit if interrupt */
                return (FALSE);    /* signal sets */
            sleep(5);    /* Wait and pull again */
            if (!dt_phone(dt, P3_PH_STATUS, -1))
                return (FALSE);    /* Poll failed? */
        }
    }
    if (!dt_onhook(dt))    /* Did it hang up ok? */
        return (FALSE);
}

```

DTINIT.C

This routine initializes the DECTalk terminal on the channel opened on dt.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION
title    dt_init      DECTalk Initialization Routine
index    DECTalk initialization routine

synopsis

#include    <stdio.h>
#include    "dectlk.h"

int
dt_init(dt)
DECTALK    *dt;    /* Device descriptor */

description

    Initialize the DECTalk terminal on the channel opened
    on dt.

    Return TRUE if the device initialized successfully.
    Return FALSE on failure.

note

    This routine turns off "local mode" so a logging terminal
    does not inadvertently send a response to the "who are you"
    escape sequence.
#endif

#include    <stdio.h>
#include    "dectlk.h"

static SEQUENCE DT_who_are_you = {
    CS, 'c'
};

int
dt_init(dt)
register DECTALK    *dt;

```

```

/*
 * dt_init() is called to initialize DECtalk.
 */
{
    register int    mode;

    dt_drain(dt);                /* Ignore pending input */
    dt_dev(dt, P2_TERMINAL, 0, -1); /* No local-host stuff */
    dt_flag |= _FLAG_TERM;      /* Remember this fact */
    /*
     * Read device attributes and fail if it isn't DECtalk.
     * Expected reply is <ESC>I?19c for the DTC01-A4
     */
    dt_pasn(dt, RDT_who_are_you);
    if (dt_read(dt, 15) == CSI)
    {
        dt->reply.final == 'c'
        dt->reply.private == ""
        dt->reply.intel[0] == 0
        dt->reply.param[0] == 1
        if ((code = dt->reply.param[1]) == CSI_DA_PRODUCT) {
            dt_reset(dt);          /* Reset device */
            return (TRUE);        /* Hang up and restart */
        }
    }
    return (FALSE);
}

```

DTINKE.C

This routine reads a telephone keypad button.

```
/* LIBRARY
 */
```

```
/* #def DOCUMENTATION
```

```
title dt_inkey      Read a Telephone Keypad Character
index              Read a Telephone Keypad Character
```

synopsis

```
#include <stdio.h>
#include "dectlk.h"

int
dt_inkey(dtl, sec)
DECTALK dtl; /* Device descriptor */
int sec; /* Seconds to wait */
```

description

This routine reads a telephone keypad button. The application program has previously enabled the keypad (by calling `dt_keypad(dtl, TRUE)`). `dt_inkey()` will call `dt_timeout()` to enable or disable timeouts.

If `sec` is nonzero, it will indicate the number of seconds to wait for a keypad response. If zero, it will turn off keypad timeouts. The operating-system timeout (needed to catch hardware or communication line problems) will be set to four times the timeout value, plus an operating-system specific additional timeout.

`dt_inkey()` returns a character as follows.

0123456789*#ABCD	A valid keypad button (Note that "ABCD" may be generated by certain keypad phones.)
E	An operating-system error
T	Keypad timeout
X	Badly parsed escape sequence.
H	Unexpected telephone hangup.

The 'H' code is received if the DECTalk device hangs up the phone (as may be required by specific telephone system requirements).

```

#endif

#include <stdio.h>
#include "dec11k.h"

/*
 * Fudge is needed because of terminal output buffering
 * capacities and strategies. It should be tuned by
 * inspection.
 *
 * The RSTS/E value is large because RSTS/E will resume a
 * program when less than 99 bytes remain to be transmitted
 * to DECtalk. DECtalk may have about 100 bytes in its input
 * buffers and two phrases in the buffer to sound and
 * synthesizer sections. If the value is set too low, the
 * application program may incorrectly assume that DECtalk
 * or the communication line is broken.
 */

#ifdef __MII
#define FUDGE 60 /* RSTS/E needs extra time */
#else
#define FUDGE 16 /* This is just a guess */
#endif

dt_inkey(dt, sec)
register DECTALK *dt; /* DECTalk device */
int sec; /* Keyup timeout */
{
    register int code;
    register int us_timeout;

    dt_timeout(dt, sec); /* Set/clear timeout */
    if (dt_iskey(dt)) {
        code = dt->pend(dt->pend_ep);
        if (++dt->pend_ep > PEND_SIZE)
            dt->pend_ep = 0;
        dt->pend_fc--;
    }
    else {
        if ((code = dt_read(dt,
            (sec < 0 ? 0 : (sec + 1 + FUDGE))) < 0)
            code = 'E';
        else if (dt_timeout(dt)) {
            code = 'T';
            dt->timeout = 0;
        }
        else if (dt_onhon(dt))
            code = 'H';
        else if (dt->reply.private < 'X')
            if (dt_isvalid(code))
                code = 'X';
    }
    return (code);
}

```

DTIOGE.C

This routine reads one character from the DECtalk terminal line. DTIOGE.C is maximized for efficiency.

```

/*>LIBRARY
*/
/*
 * Edit History
 * 04.06.15      MM      PPGTTY incorrectly specified.
 */

#first DOCUMENTATION

title    dt_ioget      Read one Character from DECtalk
index    Read one character from DECtalk

synopsis

#include    <stdio.h>
#include    "dectlk.h"

int
dt_ioget(dt, sec)
DECTALK    *dt;      /* Device descriptor */
int        sec;      /* E.S. timeout param. */

```

description

One character is read from the DECtalk terminal line. The sec parameter enables operating-system timeout; it is zero if no timeout is needed.

dt_ioget() returns the character or an error code.

DT_ERROR An operating system error (or <CTRL-C> interrupt) was received.

DT_TIMEOUT The sec parameter was nonzero and no character was received in sec seconds.

dt_ioget() is the operating-system specific input routine. It is the only routine to read data from the DECtalk terminal line.

note

On vms, an internally-used routine, dt_vmsread(), is also defined. Application programs should not call this routine.

This module contains specific code for Ultrix-386/UNIX 4.3BEO and UNIX System V. The maxfile for the library should #define one of these as appropriate.

```

#endif

#include <stdio.h>
#include "dectlk.h"

/*
 * Define all DECTalk library globals in this module.
 */
int dt_abort; /* TRUE on interrupt */
DECTALK *dt_root; /* Chain of all open units */

#ifdef unix
#include <errno.h>
#ifdef BSD_42
#include <sys/types.h>
#include <time.h>
#else
#ifdef UNIX_V
#include <signal.h>
#endif
#endif
static ignore_t() /* Dummy function for signals */
#endif

int
dt_getc(dt, snc)
register DECTALK *dt; /* DECTalk device */
int snc; /* Mail line, 0 == forever */
/*
 * UNIX: Fill the input buffer, return the next (first) character.
 */
{
    register int i; /* Count and error code */
#ifdef BSD_42
    auto int fdmask; /* File descriptor mask */
    struct timeval timeout; /* Select() timer value */
#else
#ifdef UNIX_V
    register int esize; /* For error handling */
    extern int errno; /* System error value */
#endif
#endif
    /*
     * Return buffered character (if any)
     */
    if (dt->in_ptr < dt->in_end)
        return (*dt->in_ptr++ & 0xFF);
    /*
     * We must refill the buffer
     */
    dt->in_ptr = dt->in_end = &dt->in_buff[0];
    dt->outputfd, 0); /* Flush output */
    if (dt_abort)
        return (DT_ERROR);
}

```

```

#ifdef BSD_42
fdmask = 1 << dt->unit; /* Select unit */
timeout.tv_usec = 0; /* No milliseconds */
timeout.tv_sec = sec; /* Max. seconds to wait */
incount = select((dt->unit + 1, &fdmask, 0, 0, &timeout);
if (incount < 0 || dt->abort)
return (DT_ERROR); /* Select failed? */
else if (incount == 0) /* Timeout triggered? */
return (DT_TIMEOUT); /* Guess so */
else {
incount = read(dt->unit, dt->in_buff, IN_BUFSIZE);
}
#endif
#ifdef UNIX_V
signal(SIGALRM, ignore); /* Enable alarms */
alarm(sec); /* Start timeout */
errno = 0; /* Clear error flag */
incount = read(dt->unit, dt->in_buff, IN_BUFSIZE);
ecode = errno; /* Save error code */
alarm(0); /* Cancel timeout */
signal(SIGALRM, SIG_IGN); /* Disable alarms */
if (incount < 0 && ecode == EINTR) /* Did it timeout? */
return (DT_TIMEOUT); /* Return failure */
#endif
#endif
if (dt->abort || incount <= 0) /* Other error? */
return (DT_ERROR); /* Return bad failure */
dt->in_end = &dt->in_buff[incount];
return (&dt->in_ptr++ & 0xFF);
}
#endif
#ifdef VMS
#include <ssdef.h> /* System status codes */
#include <slcdef.h> /* I/O request codes */
/*
* Define the possible vms input flavors
*/
#define RAW_READ (IOS_READBLK | IOSN_NOECHO | IOSN_NOFLTR)
#define TINED_READ (RAW_READ | IOSN_TINED)

typedef struct io_status_block {
short int status; /* I/O status code */
short int term_offset; /* Buffer size */
short int terminator; /* Input terminator */
short int term_size; /* Terminator size */
} IOSIAB;

int
di_read(dt, sec)
register DECTALK *dt; /* DECTalk device */
int sec; /* Wait time, 0 == forever */

```

```

/*
 * VMS: Fill the input buffer, return the next (first) character.
 */
{
    register int    incount;    /* Count and error code */

    /*
     * Return buffered character (if any)
     */
    if (dl->in_ptr < dl->in_end)
        return (*dl->in_ptr++ & 0xFF);
    /*
     * We must refill the buffer
     */
    dl->in_ptr = dl->in_end = &dt->in_buff[0];
    dt->outputfdt, 0);    /* Flush output */
    /*
     * First read anything in the system type-ahead
     * buffer by reading with a zero timeout.
     * If nothing was read, read one byte (with
     * timeout if specified).
     */
    incount = dt->vmsread(dt, TINED_READ, IN_BUFLen, 0);
    if (incount == DT_TIMEOUT) {
        incount = dt->vmsread(dt,
            (sec > 0) ? TINED_READ : RAW_READ, 1, sec);
    }
    if (incount < 0)
        return (incount);    /* Return error code */
    /*
     * Common exit from all read routines
     */
    dl->in_end = &dl->in_buff[incount];
    return (*dl->in_ptr++ & 0xFF);
}

int
dt->vmsread(d, command, howmany, timeout)
register DECTALK    *dt;    /* DECTalk device */
int    command;    /* QID command */
int    howmany;    /* How many bytes to read */
int    timeout;    /* Timeout value */

```

```

/*
 * Actually read from vnr. Return
 * (result > 0) the number of bytes read
 * (result < 0) error code (EOF or TIMEOUT)
 * (result cannot equal zero).
 */
{
    register int incount; /* Status parameter */
    IOSTAT status; /* I/O status block */
    register int i; /* For debugging */
    /*
     * termset is a terminator mask indicating "terminate
     * on any character". As implemented on VMS, this
     * allows the operating system to handle XOFF/XON.
     */
    static long termset(2) = { 0, 0 };

    if (di_abort)
        return (DT_ERROR);
    /*
     * The status entries term_offset and term_size
     * will yield the number of bytes read.
     */
    incount = sys$qiouv(i, /* Event flag */
        di_dev, /* Input channel */
        command, /* Taped read */
        status, /* I/O status block */
        NULL, /* AST block (none) */
        0, /* AST parameter */
        dt_in_buff, /* P1 - input buffer */
        how_many, /* P2 - buffer length */
        timeout, /* P3 - wait P3 seconds */
        &termset, /* P4 - terminator set */
        NULL, /* P5 - ignored (prompt buffer) */
        0); /* P6 - ignored (prompt size) */
    if (incount == SYS$TIMEOUT) /* Timeout returned */
        return (DT_TIMEOUT);
    else if (incount != SYS$NORMAL) /* Some other error */
        return (DT_ERROR);
    incount = status.term_offset + status.term_size;
    if (incount < 0) /* Nothing input? */
        return (DT_TIMEOUT); /* equals timeout. */
    return (incount);
}

#endif

/*
 * R S = S / E
 */
#include <sys.h>

int
dt_get(dt, sec)
register DECTALK *dt; /* DECTalk device */
int sec; /* wait time, 0 == forever */

```

```

/*
 * RSTS/E: Fill the input buffer, return the next (first) character.
 */
{
    register int    incount;        /* Count and error code */

    /*
     * Return buffered character (if any)
     */
    if (dt->in_ptr < dt->in_end)
        return (*dt->in_ptr++ & 0xFF);
    /*
     * We must refill the buffer
     */
    dt->in_ptr = dt->in_end = &dt->in_buff[0];
    dt->loput(dt, 0);                /* Flush output */
    if (dt->error)
        return (DT_ERROR);
    /*
     * RSTS/E handles timeout within
     * the operating system.
     */
    clrxb();
    xrb.xrlen = 4;                    /* No delimiter */
    xrb.xrc1 = dt->xunit * 2;
    xrb.xrbitm = TTYHND;
    rsys(SPEC);
    clrxrb();
    xrb.xrlen = 3;                    /* No echo */
    xrb.xrc1 = dt->xunit * 2;
    xrb.xrbitm = TTYHND;
    rsys(SPEC);
    incount = read(dt->xunit, dt->in_buff,
        IN_BUFLEN, 0, 0, sec, 0);
    if (incount == (-HNGTTY))          /* B4.B4.10 */
        return (DT_TIMEOUT);
    else if (incount <= 0)
        return (DT_ERROR);
    /*
     * Common exit from all read routines
     */
    dt->in_end = &dt->in_buff[incount];
    return (*dt->in_ptr++ & 0xFF);
}
#endif
#endif max

```

```

/*
 * Load in RSX specific information:
 *   cx.h           common header
 *   qiofun.h       I/O service function codes
 *   qioerr.h       I/O service error and status codes
 *   qlottd.h       Terminate I/O service bits and bytes
 *   lunbuf.h       Device characteristics buffer
 */

#include      cx.h
#include      cqiofun.h
#include      cqioerr.h
#include      qlottd.h
#include      clunbuf.h

#define QIO_EFN 1           /* I/O event flag */
#define MKT_EFN 2          /* Time event flag */
static char  gncbuf[2] = { 15, 15 }; /* get typeahead count */
static QIOPARM gncparm = { gncbuf, sizeof gncbuf };
static int   termtable[16]; /* Terminator bitmask */

int
dt_togel(dt, sec)
register DECIALK *dt; /* DECIalk device */
int sec; /* Wait time, 0 == forever */
/*
 * RSA: Fill the input buffer, return the next (first) character.
 */
{
    register int  incount; /* Count and error code */
    register char *lps; /* To copy to raw buff */
    int errorcode;
    int efn_buffer[4]; /* Event flag buffer */

    /*
     * Return buffered character (if any)
     */
    if (dt->in_ptr < dt->in_end)
        return (*dt->in_ptr++ & 0xFF);
    /*
     * We must refill the buffer
     */
    dt->in_ptr = dt->in_end = &dt->in_buff[0];
    dt->leputfd(, 0); /* Finish output */
    if (dt->abort)
        return (DT_ERROR);
    if (dt->pos_xk) {

```

```

/*
 * The PRD-350 KK: port is actually pretty simple.
 */
dt->parm.buffer = dt->in_buff;
dt->parm.size = IN_BUFLEN;
dt->parm.p2 = 0; /* No timeouts */
errorcode = qlow(10_RLB : TF_TMO, dt->unit, 010_EFN,
    &dt->iosb, NULL, &dt->parm);
if ((incount = fixiosb(dt)) == 0) {
    dt->parm.size = 1;
    if ((dt->parm.p2 * (256 * sec)) == 0) {
        errorcode = qlow(10_RLB, dt->unit, 010_EFN,
            &dt->iosb, NULL, &dt->parm);
    }
    else {
        errorcode = qlow(10_RLB : TF_TMO, dt->unit,
            010_EFN, &dt->iosb, NULL, &dt->parm);
    }
    if (errorcode != 15_SUC) {
        return (errorcode == 15_TMO
            ? DT_TIMEOUT : DT_ERROR);
    }
    if ((incount = fixiosb(dt)) == 0) {
        return (DT_TIMEOUT);
    }
}
}
else {
    /*
     * Read from a terminal.
     * First, check whether anything is in the
     * system type-ahead buffer.
     */
    errorcode = qlow(SF_GMB, dt->unit, 010_EFN,
        &dt->iosb, NULL, &gmparm);
    if (errorcode != 15_SUC)
        gmbuff[1] = 0;
    dt->parm.buffer = dt->in_buff;
    dt->parm.size = 1; /* Assume 1 byte read */
    if ((incount = (gmbuff[1] & 0xFF) > 0) {
        if (incount > IN_BUFLEN)
            incount = IN_BUFLEN;
        dt->parm.size = incount;
        errorcode = qlow(10_RTT : TF_RNE, dt->unit, 010_EFN,
            &dt->iosb, NULL, &dt->parm);
        incount = fixiosb(dt);
    }
    if (incount == 0) {
        if (ccc == 0) {
            dt->parm.table = termtable;
            qlow(10_RTT : TF_RNE, dt->unit, 010_EFN,
                &dt->iosb, NULL, &dt->parm);
            if ((incount = fixiosb(dt)) == 0)
                return (DT_ERROR);
        }
        else {

```

```

/*
 * V4) compatibility doesn't support read with
 * timeout (nor does it cause an error). Thus,
 * we have to do this the hard way.
 */
/* Set a max time (term) for "timeout" seconds.
 * Read one byte without waiting. If the wait
 * completes, cancel the timeout. If the timeout
 * completes, cancel the readin.
 */
if (mktime(MKT_EFN, sec, 2, NULL) != 15.SUC)
  if (qio(IOC_RFT : TF_RNE, dt->unit, QIO_EFN,
        &dt->iosb, NULL, &dt->parm) != 15.SUC)
    return (DT_ERROR); /* Can't happen */
/*
 * Wait until something completes.
 * read event flags then cancel the
 * request that didn't complete.
 */
while((QIO_EFN | MKT_EFN) & readlefn_buffer);
if ((lefn_buffer[0] & MKT_EFN) == 0)
  onk(MKT_EFN, NULL); /* Cancel timer */
if ((lefn_buffer[0] & QIO_EFN) == 0) {
  qsw(IOC_KIL, dt->unit, QIO_EFN,
    &dt->iosb, NULL, &dt->parm);
  return (DT_TIMEOUT);
}
if ((incount + fixiosb(dt)) == 0)
  return (DT_ERROR);
}
}
/*
 * Common (success) exit from all read routines
 */
dt->in_end = &dt->in_buff[incount];
return (*dt->in_ptr++ & 0xFF);
}
static int
fixiosb(dt)
register DECTALK *dt; /* DECTalk device */

```

```

/*
 * This routine returns the correct input count.
 * The code is unusual.
 *
 * fixiosbf() returns the true byte count.
 */
{
    extern int    $$ferr;

    if (dt->iosb.terminator != 0) {
        /*
         * Append the terminator to the buffer.
         */
        dt->in_buf[dt->iosb.count] = dt->iosb.terminator;
        dt->iosb.count++;
    }
    if (dt->short)
    {
        if (dt->iosb.status == IE_ABO
            || dt->iosb.count == 0) {
            return (0);                /* Read aborted */
        }
        else if (dt->iosb.status != IS_SJO
                 || dt->iosb.status != IS_TRD) {
            $$ferr = dt->iosb.status;
            return (0);                /* I/O error */
        }
    }
    return (dt->iosb.count);
}
#endif

```

DTIOPU.C

If the argument character is zero, or output buffer is full, this routine writes output buffer contents to the DECTalk device. Otherwise, DTIOPU.C stores the character in a local buffer.

```
/*DLIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_ioput Write one Character to DECTalk
index Write one character to DECTalk
```

synopsis

```
#include <stdio.h>
#include "dectlk.h"

int
dt_ioput(dti, byte)
DECTALK *dt; /* Device descriptor */
char byte; /* Character to write */
```

description

If the argument character is zero, or the output buffer is full, the output buffer contents are written to the DECTalk device.

If the argument character is nonzero, it is stored in the output buffer for subsequent transmission.

By buffering characters internally, the load on the operating system is significantly reduced. Note that the input routine (dt_get(), dt_getk()) will flush the output buffer before attempting to read any data. The "speek" routine, dt_talk(), also flushes the output buffer.

No data is returned. Errors are fatal.

dt_ioput() is the operating-system specific output routine. It is the only routine to write data to the DECTalk terminal line.

```

#endif

#include <stdio.h>
#include "dectalk.h"
#ifdef vms
#include <ssdef.h>
#include <iodef.h>

typedef struct io_status_block {
    short int status; /* I/O status code */
    short int term_offset; /* Data size */
    short int terminator; /* Input terminator */
    short int term_size; /* Terminator size */
} IOSTAB;

#endif

#ifdef RSX
/*
 * Load in RSX specific information:
 *   cx.h          common header
 *   qiofun.h      I/O service function codes
 *   qioref.h      I/O service error and status codes
 *   qiofid.h      Terminal I/O service bits and bytes
 */

#include <cx.h>
#include <qiofun.h>
#include <qioref.h>
#include <qiofid.h>

#define DIDLEFM 1 /* I/O event flag */
#endif

d1_outputds, c)
register DECTALK *d1; /* DECTalk device */
int c; /* Character to output */
/*
 * Store the byte (if not EOS). If the byte is EOS,
 * or the buffer is full, write it out.
 */
{
#ifdef vms
    register int size;
    register int code;
    IOSTAB status;
#else
    rtti
    register int code;
    extern int $ferr;
#endif
#ifdef RSX
    register int code;
    extern int $ferr;
#endif
    if (c != 0) {
#ifdef rtti
        *d1->out_ptr++ = (c == ESC ? (ESC | 0xB0) : c);
    } else
        *d1->out_ptr++ = c;

```

```

#endif
{
    size = (dt->out_ptr - dt->out_buff);
    if ((code == 0 && size > 0) || size > DUT_BUFLEN) {
        /*
         * No more: write the buffer.
         */
        if (!dt->abort) {
            #ifdef unix
                if (write(dt->unit,
                        dt->out_buff, size) == -1) {
                    perror(dt->device);
                    exit(1);
                }
            #endif
            #ifdef vms
                if ((code = sys$qio(1, /* Event flag */
                                     dt->unit, /* Input channel */
                                     IO$_WRITEBLK : IO$_NOFORMAT, /* format */
                                     &status, /* I/O status block */
                                     NULL, /* No AET block */
                                     0, /* No ASI parameter */
                                     dt->out_buff, /* P1 - buffer */
                                     size, /* P2 - bytes */
                                     0, /* P3 - ignored */
                                     0, /* P4 - no carriage ctrl */
                                     0, /* P5 - ignored */
                                     0)) /* P6 - ignored */
                    != SS$_NORMAL) {
                    perror(dt->device);
                    exit(code);
                }
            #endif
            #ifdef rt11
                if ((code = sys$write(dt->unit, dt->out_buff,
                                       size, 0, 0, 0)) != 0) {
                    iferr = code;
                    perror(dt->device);
                    exit(10_ERROR);
                }
            #endif
            #ifdef rx
                dt->parm.size = size;
                dt->parm.buffer = dt->out_buff;
                dt->parm.table = NULL;
                if ((code = cdev$IO_WRL, dt->unit, 0, 0, EFN,
                     &dt->ioSB, NULL, &dt->parm) != IS_SUC) {
                    iferr = code;
                    perror(dt->device);
                    exit(10_ERROR);
                }
            #endif
            dt->out_ptr = dt->out_buff;
        }
    }
}

```

DTISKE.C

This routine returns TRUE if the telephone user already typed any characters.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION

title dt_iskey      Text for type-ahead
index              Text for type-ahead

synopsis

#include <stdio.h>
#include "dectlk.h"

int
dt_iskey(dt)
DECTALK dt; /* Device descriptor */

description

This routine (which may be implemented as a macro)
returns TRUE if any characters have already been
typed by the telephone user, or if an asynchronous
status message (such as timeout) was received.

#endif

#include <stdio.h>
#include "dectlk.h"

#ifdef dt_iskey
#undef dt_iskey
#endif

int
dt_iskey(dt)
register DECTALK dt; /* Device descriptor */
/*
 * Test for type-ahead.
 */
{
    return(dt->pend_fc != 0);
}

```

DTISTLC

Used to test the result of a dt_phone () message for keypad timeout.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION

title    dt_listimeout    Test Phone Reply for Keypad Timeout
index    Test phone reply for keypad timeout

synopsis

#include    <stdio.h>
#include    "dectlk.h"

int
dt_listimeout(dt)
DECTALK    *dt;    /* Device descriptor    */

description

This routine (which may be implemented as a macro)
tests the result of a dt_phone() message.
It returns TRUE if the current reply is the DECTalk
phone reply with the R3 parameter equal to R3_PHLTIMEOUT.

#endif

#include    <stdio.h>
#include    "dectlk.h"
#ifdef dt_listimeout
#undef dt_listimeout
#endif

int
dt_listimeout(dt)
register DECTALK    *dt;    /* Device descriptor    */
/*
 * Text for telephone keypad timeout.
 */
{
    return (dt_test(dt, R2_PHONE, R3_PHLTIMEOUT));
}

```

DTISVA.C

This routine returns TRUE if the argument character is one of 0123456789#*ABCD.

```
/*)LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_isvalid      Test for Valid Keypad Character
index      Test for valid keypad character
```

```
synopsis
```

```
        #include      <stdio.h>
        #include      "dectlk.h"
```

```
        int
        dt_isvalid(c)
```

```
description
```

```
        This routine (which may be implemented as a macro)
        returns TRUE if the argument character is one of
```

```
        0123456789#*ABCD
```

```
#endif
```

```
#include      <stdio.h>
#include      "dectlk.h"
```

```
#ifdef dt_isvalid
#undef dt_isvalid
#endif
```

```
int
dt_isvalid(c)
char        c;
/*
 * Test for valid pushbutton key.
 */
{
    return ( (c >= '0' && c <= '9')
            || c == '*' || c == '#'
            || (c >= 'A' && c <= 'D'));
```

DTKEYP.C

This routine enables the telephone keypad if the flag is TRUE, and disables the keypad if it is FALSE.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_keypad      Enable or Disable the Telephone Keypad
index               Enable or Disable the Telephone Keypad
```

```
Synopsis
```

```
    #include    <stdio.h>
    #include    "dectlk.h"

    int
    dt_keypad(dt, flag)
    DECTALK     *dt;    /* Device descriptor    */
    int         flag;   /* TRUE to enable    */
```

```
Description
```

Enable the telephone keypad if the flag is TRUE, disable it if FALSE.

Returns TRUE if successful. If FALSE, the telephone may have been hung up.

```
#endif
```

```
#include    <stdio.h>
#include    "dectlk.h"
```

```
int
dt_keypad(dt, enable)
register DECTALK *dt;
int enable;
/*
 * Enable or disable the telephone keypad.
 */
```

```
{
    dt.phnufdt,
    (enable) ? P3_PH_KEYPAD : P3_PH_NOKEYPAD, -1);
    if (dt_ofhook(dt))
        return (TRUE);
    return (FALSE);
}
```

DTMSG.C

This routine sends a DECtalk DCS control sequence using the p2, p3, and p4 parameters. The r2 and r3 parameters are not checked by the module. A FALSE reply means an error occurred.

The user may have pressed keypad buttons or a timeout may have occurred. These values are saved for use by the dt_save routine.

```
/*LITERARY
*/
```

```
#ifndef DOCUMENTATION
```

```
title dt_msg      Send a DECtalk Command with Reply
index            Send a DECtalk command with reply
```

```
synopsis
```

```

#include <stdio.h>
#include "decstk.h"

int
dt_msg(dt, p2, p3, p4, r2, r3)
DECTALK *dt; /* Device descriptor */
int p2; /* P2_xxxx parameter */
int p3; /* P3_PH_xxxx parameter */
int p4; /* timeout or rings */
int r2; /* R2_xxxx parameter */
int r3; /* R3_xxxx parameter */

```

```
description
```

This routine sends a DECtalk DCS control sequence using the p2, p3, and p4 parameters. It then reads a DCS reply from DECtalk, returning TRUE if it matches the r2 and r3 ending parameters.

If p2 is -1, no sequence is sent, but a DCS reply is read and tested.

Note that the Pn and Rn parameters are -1 if they are not sent or checked respectively.

Returns TRUE if successful. If FALSE, something is funny.

Note: dt_msg() saves user keypad characters in the type-ahead buffer.

```

#endif

#include <stdio.h>
#include "dec11.h"

int
dt_msg(dt, p2, p3, p4, r2, r3)
register IECTALK *dt; /* Device descriptor */
int p2, p3, p4; /* Pn parameters to send */
int r2, r3; /* Reply R2 and R3 parameters */
/*
 * Send a DECtalk DCS message and wait for a reply.
 * Return TRUE if the proper reply was received.
 */
{
    register int code;

    if (p2 != -1)
        dt_dcs(dt, p2, p3, p4); /* Send the sequence */
    do {
        code = dt_read(dt, 60);
    } while (code == ST || dt_have(dt, code));
    return (dt_test(dt, r2, r3)); /* Check result */
}

```

DTOFFH.C

This routine tests the result of a dt_phone () message for OFFHOOK.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_offhook      Test Phone Reply for Offhook
index                 Test phone reply for Offhook
```

```
synopsis
```

```
    #include      <stdio.h>
    #include      "dectlk.h"

    int
    dt_offhook(dt)
    DECTALK      *dt;      /* Device descriptor      */
```

```
description
```

```
    This routine (which may be implemented as a macro)
    is used to test the result of a dt_phone() message.
    It returns TRUE if the current reply is the DECTalk
    phone reply with the R3 parameter equal to R3_PH_OFFHOOK.
```

```
#endif
```

```
#include      <stdio.h>
#include      "dectlk.h"
#ifdef dt_offhook
#undef dt_offhook
#endif

int
dt_offhook(dt)
register DECTALK      *dt;      /* Device descriptor      */
/*
 * Test whether the phone is off-hook.
 */
{
    return (dt_test(dt, R2_PHONE, R3_PH_OFFHOOK));
}
```

DTONHOOK.C

This routine tests the result of a dt_phone() message for ONHOOK.

```
/* LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_onhook      Test Phone Reply for Onhook
index               Test phone reply for onhook
```

```
Synopsis
```

```
    #include          <stdio.h>
    #include          "dectlk.h"

    int
    dt_onhook(dt)
    DECTALK           *dt;    /* Device descriptor */
```

```
Description
```

```
This routine (which may be implemented as a macro)
is used to test the result of a dt_phone() message.
It returns TRUE if the current reply is the DECTalk
phone reply with the R3 parameter equal to R3_PH_ONHOOK.
```

```
#endif
```

```
#include          <stdio.h>
#include          "dectlk.h"
```

```
#ifdef dt_onhook
#undef dt_onhook
#endif
```

```
int
dt_onhook(dt)
register DECTALK     *dt;    /* Device descriptor */
/*
 * Test whether the phone is on-hook.
 */
{
    return (dt_test(dt, R2_PHONE, R3_PH_ONHOOK));
}
```

DOPEN.C

This routine performs operating-specific initializations to initiate communications with a DECTalk device. Operating systems include UNIX, RSX, RSTS/E, and VMS (either compatibility or native modes).

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_open      Connect to DECTalk Terminal
index             Connect to DECTalk terminal
```

synopsis

```

#include <stdio.h>
#include "dectlk.h"

DECTALK *
dt_open(dev)
char      *dev; /* Terminal device name */
```

description

Perform operating-specific initializations to initiate communicating with a DECTalk device. (This routine is similar to `fopen()` for FILE devices.) If the open fails, return NULL; else return a pointer to a data descriptor block that will be used for all other DECTalk operations.

If the open failed, the standard library `perror()` routine may be called to print error information.

This routine does not communicate with DECTalk.

For example, the following sequence opens DECTalk, checks that it is responding, sets "square-bracket" mode, and speaks a message:

```

#include <stdio.h>
#include "dectlk.h"

DECTALK *dt;
...
main() {
    if ((dt = dt_open("kb2:")) == NULL) {
        perror("kb2:");
        printf("Can't open DECTalk\n");
    }
    else if (!dt_init(dt))
        printf("Can't initiate DECTalk\n");
    else {
        dt_desc(dt, P2_MODL, MODL_SQUARE, -1);
        dt_talk(dt, "Hello world.");
        dt_sync(dt);
        dt_close(dt);
        printf("Success.\n");
    }
}
```

UNIX notes

This routine conditionally compiles for Ultrix-32 (4.2BSD) and System V. There is also a conditional for the Zilog Zeus version of UNIX. This hasn't been independently checked.

UNIX implementors are encouraged to read and understand this module when developing DECtalk applications.

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```
#endif

#include <stdio.h>
#include "decstk.h"

#ifdef UNIX
/*
 * UNIX specific definitions
 */
#include <signal.h>
#include <errno.h>
#endif

#ifdef VMS
/*
 * VMS native specific definitions
 */
#include <ssdef.h> /* Status definitions */
#include <iodef.h> /* I/O request codes */
#include <descrsp.h> /* String descriptors */

typedef struct desc$descriptor_1 STRING_t /* string descriptor */
/*
 * The following macro builds a descriptor from an argument string.
 */
#define descriptor1(p) \
    ((p)->desc$pointer = text, \
     (p)->desc$length = strlen(text), \
     (p)->desc$type = DSC$K_DTYPE_T, \
     (p)->desc$class = DSC$K_CLASS_S)

#endif

#ifdef AT&T
/*
 * AT&T native specific definitions
 */
#include <csa.h>
#endif

#ifdef RSX
#include <cs.h>
#include <qiofunc.h>
#include <qioctrl.h>
#include <qioadd.h>
#include <clmbuf.h>
#define BIOEFN 1
static BIOFARM noparm; /* BIO parm (all zeros) */
#endif
```

```

DECTALK *
dt open(name)
char      *name;          /* Device name      */
/*
 * Initialize the DECTalk terminal line.
 */
{
    register DECTALK      *dt;
    register int          i;          /* Channel search, temp */

    #ifdef unix
    register char          *tname;    /* -> stdin name      */
    #endif
    #ifdef BSD_42
    struct sgttyb          stty_buffers; /* Terminal flags    */
    #else
    #ifdef UNIX_V
    struct termio          stty_buffer; /* Terminal flags    */
    #endif
    #endif
    extern char            *ttyname(i); /* Get stdin name    */
    #endif
    #ifdef VMS
    STRING                 dev;
    #endif
    #ifdef rti
    char                   word(80);
    extern int             %status;
    extern char             *%$NOID;    /* Invalid device    */
    extern char             *%$FAT;     /* Fatal error       */
    extern char             *%$ENDC;    /* No more channels  */
    #endif
    #ifdef rsx
    extern int             %status;     /* TRUE if RSTS/E    */
    extern int             %pus;        /* TRUE if P/VS      */
    extern int             %dsw;        /* Dir. status word   */
    extern int             %error;      /* DECUS C error value */
    struct lunbuf          lunbuf;      /* Del lun information */
    #endif
    extern char            *delloc();
    extern char            *nalloc();

    /*
     * Allocate the DECTalk buffer and save the
     * device name (for debugging).
     */
    if ((dt = (DECTALK *)nalloc(sizeof (DECTALK), 1)) == NULL)
        return (NULL);
    if ((dt->device = nalloc(strlen(name) + 1)) == NULL)
        goto error2;
    strcpy(dt->device, name);
}

```



```

#endif
#ifdef rt11
if ($$rsts) {
    $!err = (int) $E$FOT; /* illegal function */
    goto error;
}
/*
 * Search for a free channel.
 */
for (i = 0; i < 3; i++) {
    clrxb0();
    xrb.xrb1 = 1 * 2;
    if (rstsya4_HQSTN) == NOTOPN)
        break;
}
if (i < 3) { /* Fail if all channels */
    $!err = (int) $E$HDD; /* are in use. */
    goto error;
}
di->unit = i; /* Save unit number */
/*
 * On RSTS, the terminal is opened in a special mode:
 * 1 binary
 * 16 do not abort on CTRL-C or modem hangup
 * 32 terminal service handles XOFF/XON
 */
sprintf(work, "%s/mn:ld", name, '+'6+32);
if (res_open(1, work, "r") != 0)
    goto error;
if ($$rqb.fqflag & 0xFF) != YTHHD) {
    $!err = (int) $E$HDD; /* Not a terminal */
    res_close(1);
    goto error;
}
#endif
#endif
max
if ($$rsta) {
    $!err = IF_LFB; /* Not on RSTS/F */
    goto error;
}
/*
 * We only call fopen() to get a free luh.
 */
if ((di->fides = fopen(name, "r")) == NULL)
    goto error;
di->unit = f; $mofdi->fides);
glun(di->unit, slunbuf);
if ($$psa
    && lunbuf.g_luna[0] == 'Y'
    && lunbuf.g_luna[1] == 'K')
    di->psa_xk = TRUE;
else
    di->psa_xk = FALSE;
if ((i = qlw(CID_RTI, di->unit, 010_EFN,
    NULL, NULL, &psarm)) != 15_EUC) {
    fclose(di->fides);
    $!err = i;
    goto error;
}
)

```

```

#endif
/*
 * Normal exit, initialize other pointers
 */
dt->link = dt->root;
dt->root = dt;
dt->out_ptr = dt->out_buff; /* Out buffer setup */
dt->flag = _FLAG_SPEAK;     /* Normally speaking */
return (dt);               /* Normal exit */

error1: free(dt->device);    /* Error, free device */
error2: free(char *) dt;    /* and DECTALK buffer */
return ((DECTALK *)NULL);  /* Error exit */
}

```

DTPEEK.C

This routine tests if a character is pending from DECTalk. The character may be a keypad character (user selected) or part of an escape sequence.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION

title    dt_peak      Test if Character Available from DECTalk
index    Test if character available from DECTalk

synopsis

        #include      <stdio.h>
        #include      "dectlk.h"

        int
        dt_peak(di)
        DECTALK      *di;    /* Device descriptor */

description

        Returns TRUE if a character is pending from DECTalk.
        Note that this may be a keypad input character (as
        entered by the user) or part of an escape sequence.

        dt_peak() does not flush pending output. It contains
        operating-system specific code.

note

        This module contains specific code for UNIX
        4.2BSD. The makefile for the library should
        #define BSD_42.

bugs

        Tested only on VMS.

#endif

#include      <stdio.h>
#include      "dectlk.h"

/*
 * Define all DECTalk library globals in this module.
 */

#ifdef UNIX
#include      <errno.h>
#ifdef BSD_42
#include      <sys/types.h>
#include      <time.h>
#endif
#endif

```

```

int
dt_pending(dl, sec)
register DECTALK *dt; /* DECTalk device */
/*
 * UNIX.
 */
{
    register int incount; /* Count and error code */
#ifdef BSD_42
    bzero long pending; /* Number pending */
#else
    register int ecode; /* For error handling */
    extern int errno; /* System error value */
#endif

    /*
     * Anything buffered?
     */
    if (dt->pend.fc > 0 || dt->in_ptr < dt->in_end)
        return (TRUE);
#ifdef BSD_42
    /*
     * Works for 4.1 BSD, too.
     * Won't work for Unix V7 or System H (4 >= 3)
     */
    ioctl(dt->unit, FIONREAD, &pending);
    return(pending > 0);
#else
    dt->in_ptr = dt->in_end + dt->in_buff[0];
    alarm(1); /* Start timeout */
    errno = 0; /* Clear error flag */
    incount = read(dt->unit, dt->in_buff, IN_BUFSIZE);
    ecode = errno; /* Save error code */
    alarm(0); /* Cancel timeout */
    if (incount < 0 && ecode == EINTR) /* Did it timeout? */
        return (FALSE); /* Return failure */
    if (dt->abort || incount <= 0) /* Other error? */
        return (FALSE); /* Return bad failure */
    dt->in_end = dt->in_buff[incount];
    return (TRUE);
#endif
}

#ifdef vms
#include <sysdef.h> /* System status codes */
#include <ioconf.h> /* I/O request codes */
typedef struct io_status_block {
    short int status; /* I/O status code */
    short int term_offset; /* Datum size */
    short int terminator; /* Local terminator */
    short int term_size; /* Terminator size */
} IOSTATB;

```

```

int
dt_peak(dt)
register DECTALK *dt; /* DECTalk device */
/*
 * VHS: Fill the input buffer, too.
 */
{
    register int incount;
    struct typeahead {
        short pending_count;
        char first_character;
        char char_reserved;
        int long_reserved;
    } typeahead;
    JUSTAB status; /* I/O status block */

    if (dt->pend_cnt > 0 || dt->in_ptr < dt->in_end)
        return (TRUE);
    incount = sys$qio(1, /* Event flag */
        dt->unit, /* Input channel */
        IUS_SENSEMODE | SIO_MLT*PEAHDONT,
        &status, /* I/O status block */
        NULL, /* AST block (none) */
        0, /* AST parameter */
        &typeahead, /* P1 - buffer */
        sizeof typeahead, /* P2 - buffer length */
        0, /* P3 - */
        NULL, /* P4 - */
        NULL, /* P5 - ignored (prompt buffer) */
        0); /* P6 - ignored (prompt size) */
    return (incount == SSI_NORMAL && typeahead.pending_count > 0);
}
#endif

#ifdef R11
/*
 * R S = S / E
 */
#include <crsta.h>

int
dt_peak(dt)
register DECTALK *dt; /* DECTalk device */

```

```

/*
 * RSTSD: Fill the input buffer, return the next (first) character.
 */
{
    register int    incount;          /* Count and error code */

    if (dt->pend_fc > 0 || dt->in_ptr < dt->in_end)
        return (TRUE);
    /*
     * We must refill the buffer
     */
    dt->in_ptr = dt->in_end = &dt->in_buff[0];
    clrxb();
    xrb.xrlen = 4;                    /* No delimiter          */
    xrb.xrcb = dt->xunit + 2;
    xrb.xrblen = 1;YHND;
    rstsys(LSPEC);
    clrxb();
    xrb.xrlen = 3;                    /* No echo              */
    xrb.xrcb = dt->xunit + 2;
    xrb.xrblen = 1;YHND;
    rstsys(LSPEC);
    incount = re_rread(dt->xunit, dt->in_buff,
        IN_BUFLEN, 0, 0, 0, 0102);
    if (incount == -(HNGTTY))
        return (FALSE);
    else if (incount < 0)
        return (FALSE);
    dt->in_end = &dt->in_buff[incount];
    return (TRUE);
}
#endif

#ifdef RSX
/*
 * Load in RSX specific information:
 *
 * cx.h          common header
 * qlotun.h      I/O service function codes
 * qlorot.h      I/O service error and status codes
 * qlottd.h      Terminal I/O service bits and bytes
 * lunbuf.h      Device characterization buffer
 */

#include      cx.h
#include      qlotun.h
#include      qlorot.h
#include      qlottd.h
#include      lunbuf.h

#define QIOLEFN 1                    /* I/O event flag      */
#define MKTLEFN 2                    /* Time event flag     */
static char   gacbuf[2] = { TCTTY }; /* get typeahead count */
static QIOPARM gacparm = { gacbuf, sizeof gacbuf };
static int    lenntab[16];          /* terminator bitmask  */

```

```

int
dt_peekdt)
register DECtalk *dt; /* DECtalk device */
/*
 * RSX:
 */
{
    register int incount; /* Count and error code */
    register char *bp; /* To copy to rsx buff */
    int errorcode;
    /*
     * Return buffered character (if any)
     */
    if (dt->pend.fc > 0 || dt->in_ptr < dt->in_end)
        return (TRUE);
    /*
     * We must refill the buffer
     */
    dt->in_ptr = dt->in_end = &dt->in_buff[0];
    if (dt->pos_xl) {
        /*
         * The PRO-350 JK port is actually pretty simple.
         */
        dt->parm.buffer = dt->in_buff;
        dt->parm.size = IN_BUFLen;
        dt->parm.p3 = 0; /* No timeout */
        errorcode = qios(FIO_RLB, F_TMO, dt->unit, 0, 0, 0,
            &dt->ioab, NULL, &dt->parm);
        if ((incount = fixiosbld()) == 0) {
            return (FALSE);
        }
        dt->in_end = &dt->in_buff[incount];
        return (TRUE);
    }
    else {
        /*
         * Check whether anything is in the
         * system type-ahead buffer.
         */
        errorcode = qios(SF_GMC, dt->unit, 0, 0, 0,
            &dt->ioab, NULL, &dt->parm);
        return (errorcode == CS_SUC && gncbuf[1] > 0);
    }
}

```

```

static int
fixiosb(di)
register DECTALK *dt; /* DECTalk device */
/*
 * This routine returns the correct input count.
 * The code is unusual.
 */
/* fixiosb() returns the true byte count.
 */
{
    extern int  _ffern;

    if (dt->iosb.terminator != NUL) {
        /*
         * Append the terminator to the buffer.
         */
        dt->iosb.buf[dt->iosb.count] = dt->iosb.terminator;
        dt->iosb.count++;
    }
    if (dt->abort
        || dt->iosb.status == IS_ABORT
        || dt->iosb.count == 0) {
        return (0); /* Read aborted */
    }
    else if (dt->iosb.status != IS_EOF
        || dt->iosb.status != IS_TMO) {
        _ffern = dt->iosb.status;
        return (0); /* I/O error */
    }
    return (dt->iosb.count);
}
#endif

```

DTPESC.C

This routine compiles an appropriate escape sequence from the parameter buffer.

```
/* LIBRARY
```

```
*/
```

```
#ifdef DOCUMENTATION
```

```
title    dt_pesc           Transmit Escape Sequence
index    Transmit escape sequence
```

synopsis

```

#include    <stdio.h>
#include    "dectlk.h"

dt_pesc(dt, seq)
DECTALK    *dt;    /* Device descriptor */
SEQUENCE    *seq;    /* What to transmit */

```

description

Compile an appropriate escape sequence from the parameter buffer. This is similar to butcher() except when seq->state is ESC, CSI, or DCS. In these cases, the function generates an appropriate sequence from the passed data structure. dt_pesc() calls the user-supplied dt_put() to output each character.

Of control sequences are sent in their eight-bit form if _FLAG_EIGHTBIT is set in dt->flag. If this bit is off, they are sent in their <ESC>X form. If the application program sets _FLAG_EIGHTBIT it must also ensure that the operating system transmits eight data bits, and that DECTalk was setup as HOST FORMAT EIGHT.

No value is returned.

```
#endif
```

```

#include <stdio.h>
#include "dectlk.h"

dl_pseq(dl, seq)
register DECTALK *dt; /* Dectalk device */
register SF00[16] *seq; /* Sequence buffer */
/*
 * Output the character (in seq->state) and maybe a sequence, too.
 */
{
    register unsigned i; /* Index into inter[]; param[]; */
    unsigned max; /* Max for inter[] and param[]; */

#ifdef DT_DEBUG
    if (dt->debug) {
        printf("put: (%d);",
            (i < 0 ? seq->state : seq[i]));
        fflush(stdout);
    }
#endif
    i = seq->state;
    if ((dt->flag & _FLAG_EIGHTBIT) == 0
        && i >= 0x80 && i <= 0xFF) {
        /*
         * Output is in 7-bit mode and the character is
         * a C1 control character. Convert it.
         */
        dt_put(dl, ESC);
        dt_put(dl, i - 0x80);
    }
    else {
        /*
         * Not the special case; output the character.
         */
        dt_put(dl, i);
    }
    switch (i) {
    case ESC:
    case CSI:
    case DCS:
        /*
         * Here is a sequence. Output all of its components.
         *
         * First, the parameters.
         * i counts the parameters.
         * max stores the parameter max.
         * val working copy of parameter value.
         */
        if (seq->private != 0)
            dl_put(dl, seq->private);
        max = seq->param[0];
        if (max > SEQ_PARMAX)
            max = SEQ_PARMAX; /* Too many, use limit. */
        for (i = 1; i <= max; i++) {
            if (i > 1)
                dl_put(dl, ",");
            if (seq->param[i] != 0)
                intout(dl, seq->param[i]);
        }
    }
}

```

```

/*
 * Output intermediates.
 * i counts intermediates.
 * max stores the number to output.
 */
max = seq->inter[0];
if (max > SEQ_INTMAX)
    max = SEQ_INTMAX; /* Too many, use limit */
for (i = 1; i <= max; i)
    di_putidt, seq->inter[i++]);
di_putidt, seq->final); /* Output the final */
break;

default:
    break;
}
#endif DT_DEBUG
if (dt_debug)
    printf("\n\n");
#endif
}
#endif INT_32
#endif vax
#define INT_32
#endif

#ifdef M68000
#define INT_32
#endif

static unsigned power10[] =
{ /*
 * Powers of 10 for input
 */
#ifdef INT_32
    10000000,
    1000000,
    100000,
    10000,
    1000,
    100,
    10,
    1,
};

#define NPONERS ((sizeof power10) / (sizeof (unsigned)))

static
input(dt, value)
    DECTALK /* DECtalk device */
    register unsigned value; /* Value to convert */
/*
 * Convert an unsigned number to ASCII and call di_putidt on
 * each character. Note, as implemented here, a zero value
 * does not output anything.
 */

```

```

{
    register unsigned    *power;
    int                  out_char;
    int                  nonzero;

    power = power10;      /* Pointer to power table */
    nonzero = FALSE;      /* Don't output leading zeros */
    do {
        /*
         * Loop until all places except digits place
         * have been done.
         */
        for (out_char = 0; value >= *power; out_char++)
            value -= *power;      /* Subtract a power */
        if (nonzero || out_char > 0) {
            nonzero = TRUE;      /* Not leading zero */
            d_outputd, out_char + '0';
        }
    } while (++power < &power10[POWERS]);
}

```

DTPHON.C

This routine sends a DECTalk phone message.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_phone      Send a Phone Message
index              Send a phone message
```

```
synopsis
```

```

#include      <stdio.h>
#include      "dectalk.h"

int
dt_phone(dt, p3, p4)
DECTALK      *dt;      /* Device descriptor */
int          p3;      /* P3_P4_xxxx parameter */
int          p4;      /* timeout or rings */

```

```
description
```

This routine (which may be implemented as a macro) sends a DECTalk phone message (i.e., the p2 parameter is P2_PHONE).

p3 and p4 should be given as -1 if no parameter is to be sent.

It then reads the status reply and returns TRUE if the r1 and r2 parameters are R1_DECTALK and R2_PHONE respectively. The application program should then test for offhook/onhook as appropriate.

Returns TRUE if successful. If FALSE, something is funny.

```
#endif
```

```
#include      <stdio.h>
#include      "dectalk.h"
```

```
#ifdef dt_phone
#undef dt_phone
#endif
```

```

int
dt_phonedt, p3, p4)
register DECTALK      *dt;      /* Device descriptor */
int          p3;
int          p4;
/*
 * Send a phone message.
 */
{
    return (dt_msgdt, P2_PHONE, p3, p4, R2_PHONE, -1);
}

```

DPTES.C

This routine tests a phone reply.

```
/*)LIBRARY
```

```
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_ptest      Test Phone Reply
index              Test phone reply
```

```
synopsis
```

```

#include    <tdic.h>
#include    "dectlk.h"

int
dt_ptest(dt, r3)
DECTALK    *dt;    /* Device descriptor */
int        r3;     /* R3.PH.... parameter */

```

```
description
```

```

This routine (which may be implemented as a macro)
is used to test the result of a dt_phone() message.
The parameter is a R3.PH.... reply value.
It returns TRUE if the current reply is a DECTalk
phone reply with the specified R3 parameter.

```

```
#endif
```

```

#include    <tdio.h>
#include    "dectlk.h"

```

```

#ifdef dt_ptest
#undef dt_ptest
#endif

```

```

int
dt_ptest(dt, r3)
register DECTALK    *dt;    /* Device descriptor */
int                r3;
/*
 * Test a phone message.
 */
{
    return (dt_test(dt, R3_PHONE, r3));
}

```

DTPUT.C

This routine sends one character to the DECtalk terminal line. No value is returned.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dtput      Write one Character to DECtalk
index            Write one character to DECtalk
```

```
synopsis
```

```
    #include      <stdio.h>
    #include      "dectlk.h"

    dtput(dt, c)
    DECTALK      *dt;    /* Device descriptor */
    int          c;      /* Character to write */
```

```
description
```

One character is written to the DECtalk terminal line. No value is returned.

If DT_DEBUG is #defined when the library is compiled and the global dt_debug is set nonzero (by the application program), the character written is logged to the standard output device.

```
#endif
```

```
#include      <stdio.h>
#include      "dectlk.h"
```

```
#ifdef dtput
#undef dtput
#endif
```

```
dtput(dt, c)
register DECTALK *dt;    /* Device descriptor */
register int      c;      /* Character to write */
{
    extern int      dt_debug;
```

```
    dt_tput(dt, c);
    #ifdef DT_DEBUG
        if ((dt_debug != 0)
            dt_putchar(c, stdout);
```

```
#endif
}
```

DTREAD.C

This routine reads a sequence or character.

```
/*1.LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_read      Read Sequence or Character
index              Read sequence or character
```

synopsis

```
#include <stdio.h>
#include "dectalk.h"

int
dt_read(dt, sec)
DECTALK dt; /* Device descriptor */
char sec; /* O.S. timeout value */
```

description

Read an escape sequence or typed character. Ignore any characters between the DECTALK file and the string terminator. Return the character read or the sequence introducer.

```
#endif
```

```
#include <stdio.h>
#include "dectalk.h"
```

```
int
dt_read(dt, sec)
register DECTALK dt; /* Dectalk device */
int sec; /* Operating system timeout */
{
    register int code;
    register int i;

    /*
     * Read another sequence (or continue reading this one).
     * Copy the sequence read into the working "reply" buffer.
     * Note, this code is not quite general enough for all
     * escape sequence parsing. Specifically, it cannot
     * properly deal with CC control characters embedded
     * inside of escape sequences (as is necessary if the
     * operating system cannot process XJFF/XON controls).
     */
```

```

again: dt->seq.state = 0;
dt->reply.state = code + dt->seq(dt, seq);
switch (code) {
case GRM:
case SUB:
    goto again;

case SSC:
case OSI:
case DCS:
    dt->reply.final = dt->seq.final;
    dt->reply.private = dt->seq.private;
    for (i = 0; i <= dt->seq.inter[0]; ++i)
        dt->reply.inter[i] = dt->seq.inter[i];
    for (i = 0; i <= dt->seq.param[0]; ++i)
        dt->reply.param[i] = dt->seq.param[i];
    break;

default:
    dt->reply.final = dt->reply.private =
    dt->reply.inter[0] = dt->reply.param[0] = 0;
    break;
}
if (dt->reply.state == DCS) {
    /*
     * Ignore text between DCS final and ST
     */
    dt->seq.state = 0;
    do {
        code = dt->seq(dt, seq);
    } while (code > 0 && code < 0x80);
}
return (dt->reply.state);

```

DTRERE.C

This routine sends a soft-reset escape sequence.

```

/* */ LIBRARY
*/

#ifdef DOCUMENTATION
title    dt_reset      DECtalk Soft Reset
index    DECtalk soft reset

synopsis

#include    <stdio.h>
#include    "dectlk.h"

dt_reset(dt)
DECTALK    *dt;    /* Device descriptor */

description

Send a "soft reset" escape sequence.
No errors are possible.

#endif

#include    <stdio.h>
#include    "dectlk.h"

static SEQUENCE soft_reset = {
    CSI, 'P', 0, 0, 0 }, 1, 1, 'P' }
};

dt_reset(dt)
register DECTALK    *dt;
/*
 * dt_reset() sends a soft-reset escape sequence.
 */
{
    dt_putchar(dt, soft_reset);
    dt->flag |= _FLAG_SPEAK;    /* Speaking now */
    dt->timeout = 0;    /* No timeout now */
}

```

DTSAVE.C

This routine saves user type-ahead characters.

```
/* _LIBRARY
 */
```

```
#ifdef DOCUMENTATION
```

```
title dt_save      Save User Type-ahead
index             Save user type-ahead
```

Synopsis

```
#include <stdio.h>
#include "dectlk.h"

int
dt_save(dt, c)
DECTALK *dt; /* Device descriptor */
char c; /* Character to save */
```

Description

If c is a keypad character, save it in the type-ahead buffer and return TRUE; else return FALSE.

If the current reply is a timeout and nothing is stored in the type-ahead buffer, save 'T' and clear the timeout flag. This is necessary as a timeout sequence may be returned in the middle of a message/reply sequence.

This routine should not be called by application programs.

```
#endif
```

```
#include <stdio.h>
#include "dectlk.h"
```

```

int
dt_timeout(d, c)
register DECTALK *dt; /* DecTalk device */
int c /* Character to test */
{
    register int timeout; /* Current value */

    if (!dt_valid(c)) { /* Not a keypadd button? */
        if (!dt_timeout(d)) /* If it isn't timeout, */
            return (FALSE); /* It's not for us. */
        else { /* Timeout is funny. */
            /* Ignore timeout if timer is set to zero or
             * something is already in the typeahead buffer.
             */
            timeout = dt_timeout; /* Get old value */
            dt_timeout = 0; /* Clear timer */
            if (timeout == 0 || dt_key(d))
                return (TRUE); /* Toss it away */
            c = 'T'; /* Save it in typeahead */
        }
    }
    if (dt_send_fp < PEND_SIZE) { /* Save it if there's */
        dt_send_fp++; /* enough room, else */
        dt_send[dt_send_fp] = c; /* throw it away. */
        if (++dt_send_fp >= PEND_SIZE)
            dt_send_fp = 0;
    }
    return (TRUE);
}

```

DTSPLICE.C

This routine lets you control a terminal connected to DECTalk's local port.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dtsplice      Manage Local Terminal
index              Manage Local Terminal
```

```
synopsis
```

```
    #include      <stdio.h>
    #include      "dectlk.h"

    dtsplice(dt, flag)
    DECTALK      *dt;    /* Device descriptor */
    int          flag;    /* Required state */
```

```
description
```

dtsplice() allows control over a terminal connected to DECTalk's local port. Note that the terminal must correctly process ANSI escape sequences. Specifically, it must ignore any escape sequence that it doesn't understand.

The flag parameter may have the following (bit-encoded) values.

SPLICE_SPEAK	Speak subsequent text, if set. Do not speak text if not set. Initially zero.
SPLICE_LOG	Text sent to DECTalk is sent (in raw mode) to the local terminal if set. Initially not set.
SPLICE_TERM	Text typed on the local terminal is sent to DECTalk if set. Initially not set.

The bits would normally be set and cleared in combination. For example:

```
dtsplice(dt, SPLICE_SPEAK);
```

Speak text, don't log it, ignore text typed on the host.

```
dtsplice(dt, SPLICE_LOG | SPLICE_TERM);
```

Stop speaking text, transmit text from/to the attached terminal.

```

#endif

#include <stdio.h>
#include "dectic.h"

dt_splice(dt, flag)
register DECTALK *dt;
register int flag;
/*
 * Manage line-splice modes.
 */
{
    splice(dt, flag & SPLICE_SPEAK, _FLAG_SPEAK,
        FE_SPEAK, 1);
    splice(dt, flag & SPLICE_LDS, _FLAG_LDS,
        FE_LDS, LDS_RAWDS);
    splice(dt, flag & SPLICE_TERM, _FLAG_TERM,
        P2_TERMINAL, TERM_HOST);
}

static
splice(dt, flag, bit, a2, p3)
register DECTALK *dt;
int flag; /* TRUE to set bit */
int bit; /* dt->flag bit to do */
int p2, p3; /* for DCS */
/*
 * Do the dt_splice() work. If dt->flag doesn't agree with flag,
 * send the appropriate dcs().
 */
{
    if ((dt->flag & bit) != 0) != (flag != 0) {
        if (flag != 0) {
            /* Turn mode on, */
            dt->flag |= bit; /* Set flag bit and */
            dcs(dt, a2, p3, -1); /* Sends the p2/p3 */
        }
        else {
            /* Turn mode off, */
            dt->flag &= ~bit; /* Clear flag bit and */
            dcs(dt, p3, 0, -1); /* Send "mode off" */
        }
    }
}

```

DTST.C

This routine sends a string terminator to DECTalk. This string terminates phonemic text or telephone dial commands.

```

/*LIBRARY
*/

#include DOCUMENTATION

title dt_st      Send String Terminator
index            Send String Terminator

synopsis

        #include <stdio.h>
        #include "dectalk.h"

        int
        dt_st(dt)
        DECTALK      *dt;    /* Device descriptor */

description

        This routine sends a string terminator to DECTalk.
        This is needed to terminate phonemic text or telephone
        dial commands.

        A phonemic text sequence would be sent as follows.

                dl_end(dt, p2, p3);
                dt_talk(dt, "hh'ehlow.");
                dt_st(dt);

#endif

#include <stdio.h>
#include "dectalk.h"

static SEQUENCE string_terminator = {
    ST
};

dt_st(dt)
DECTALK      *dt;    /* Device descriptor */
/*
 * Send a string terminator
 */
{
    dt_puts(dt, &string_terminator);
}

```

DTSYNC.C

This routine synchronizes the application with DECTalk.

```

/*DLIBRARY
*/

#ifdef DOCUMENTATION

title    dt_sync      Synchronize with DECTalk
index    Synchronize with DECTalk

synopsis

#include    <stdio.h>
#include    "dectlk.h"

int
dt_sync(int)
DECTALK    *dt;    /* Device descriptor    */

description

The program delays until all text sent to DECTalk
has been spoken.

Returns TRUE if successful.  If FALSE, something is funny.

#endif

#include    <stdio.h>
#include    "dectlk.h"

int
dt_sync(int)
register DECTALK    *dt;    /* Device descriptor    */
/*
 * Synchronize DECTalk and the application.
 */
{
    dt->sdtdt, P2_SYNC, -1, -1);    /* Synchronize    */
    dt->flag |= _FLAG_SPEAK;    /* Now speaking    */
    return (dt->msg(dt, P2_IX_QUERY, -1, -1, R2_IX_QUERY, -1));
}

```

DTTALK.C

This routine speaks one line of text.

```

/*LIBRARY
*/

#ifdef DOCUMENTATION

title    dttalk      Speak One Line of Text
index    dttalk      Speak one line of text
:
synopsis

        #include      <stdio.h>
        #include      "dectalk.h"

        dt_talk(dt, text)
        DECTALK      *dt;    /* Device descriptor */
        char          *text;  /* What to say */

description

        This function sends a line of text to DECTalk.

        dt_talk(dt, NULL) flushes DECTalk by sending
        a vertical-tab sequence.

#endif

#include      <stdio.h>
#include      "dectalk.h"

static const  vlline[] = { VT, 0 };

dt_talk(dt, text)
register DECTALK      *dt;    /* Device descriptor */
register char          *text;  /* Text pointer */
{
    if (text == NULL)
        text = vlline;
    while (*text != 0)
        dt_put(dt, *text++);
    dt_eol(dt);
}

```

DTTEST.C

This routine tests a DECTalk reply.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_test      Test a DECTalk Reply
index             Test a DECTalk reply
```

synopsis

```
#include <stdio.h>
#include "dectlk.h"

int
dt_test(dt, r2, r3)
DECTALK *dt; /* Device descriptor */
int r2; /* R2_xxx parameter */
int r3; /* R3_xxx parameter */
```

description

This routine checks the test reply received from DECTalk against the model. r3 is -1 to ignore it. It returns TRUE if the reply is a properly parsed DECTalk reply sequence, or FALSE on any failure.

```
#endif
```

```
#include <stdio.h>
#include "dectlk.h"

int
dt_test(dt, r2, r3)
register DECTALK *dt; /* Device descriptor */
int r2;
int r3;
/*
 * Test the current returned sequence for the proper
 * DECTalk reply. r3 is -1 to ignore it.
 */
{
    if (dt->reply.vtalk == DCS
        && dt->reply.final == DCS.F.DECTALK
        && dt->reply.inter[0] == 0
        && dt->reply.private == 0) {
        if (dt->reply.param[1] == R1_DECTALK
            && dt->reply.param[2] == r2
            && (r3 == -1 || dt->reply.param[3] == r3))
            return (TRUE);
    }
    return (FALSE);
}
```

DTTIME.C

This routine enables or disables telephone keypad timeout.

```
/*>LIBRARY
*/
```

```
#ifndef DOCUMENTATION
```

```
title dt_timeout      Enable or Disable Keypad Timeout
index                Enable or disable keypad timeout
```

synopsis

```
    #include    <stdio.h>
    #include    "dectlk.h"

    int
    dt_timeout(dt, sec)
    DECTALK     *dt;    /* Device descriptor */
    int         sec;    /* Timeout in seconds */
```

description

If sec is nonzero, timeouts are being enabled;
if zero, they are being disabled.

Enable keypad timeouts if sec is nonzero and there
is no data in the type-ahead buffer (and timeouts
are not already enabled).

Disable timeouts if they are enabled and sec is zero,
or any data is in the type-ahead buffer (even if
sec is nonzero).

Before enabling timeouts, DECTalk is synchronized.

Returns TRUE if successful. If FALSE, the telephone
may have been hung up.

```
#endif
```

```
    #include    <stdio.h>
    #include    "dectlk.h"

    int
    dt_timeout(dt, sec)
    register DECTALK *dt;    /* Device descriptor */
    register int     sec;    /* Timeout in sec seconds */
```

```

/*
 * Enable or disable timeout. No errors are possible.
 * Note that timeout(dt, 15) looks at the state of the
 * type-ahead buffer before deciding whether to turn
 * timeout on, off, or to do nothing.
 */
{
    if (sec != 0) {
        if (dt->key(dt)) /* If enabling, */
            sec = 0; /* Disable if typeahead */
        if (sec != 0) { /* Still enabling? */
            dt->sync(dt); /* Synchronize and */
            if (dt->key(dt)) /* Check again. */
                sec = 0;
        }
    }
    if (dt->timeout != sec) /* Can't set to the */
        return (TRUE); /* same value */
    dt->phone(dt, P3_PH_TIMEOUT, sec);
    dt->timeout = sec;
    if (dt->onhook(dt) || dt->offhook(dt))
        return (TRUE);
    return (FALSE);
}

```

DTTONE.C

This routine sends the msg test string as a tone dialing sequence.

```
*/
```

```
#ifdef DOCUMENTATION
```

```
title dttone      Send DTMF Tones
index            Send DTMF tones
```

```
synopsis
```

```
    #include      <stdio.h>
    #include      "dectlk.h"

    int
    dttone(int, msg)
    register DECTALK *dl;    /* Device descriptor */
    char *msg;              /* Announcement */
```

```
description
```

This routine sends the msg text string as a tone dialing sequence. If the telephone was on-hook when dttone() was called, it will be returned to the on-hook condition. Note, this routine may not work to your satisfaction in countries which require automatic announcement messages on automatically dialed calls. See your DECTalk programmer's manual for more information.

For message text may contain any valid touch-tone characters ("0123456789*#ABCD") or the characters '?' (for a one second delay) or the '^' for a 250 millisecond switch-hook flash. All other characters are ignored.

Note that the telephone will not be hung up before dialing if it is offhook when the command is issued.

```
#endif
```

```
#include      <stdio.h>
#include      "dectlk.h"

int
dttone(int, message)
register DECTALK *dl;        /* Device descriptor */
char *message;              /* Announcement */
```

```
/*  
 * Send tones.  
 */  
{  
    register int    state;  
    register int    code;  
  
    dt_phonect, -1, -1);  
    state = dt_anhact(d1);  
    dt_snd(d1, P2_PHONE, P3_PHONE);  
    dt_talk(d1, message);  
    dt_snd(d1);  
    do {  
        code = dt_recvct, 30);  
    } while (code == ST || dt_wave(d1, code));  
    if (state)  
        dt_hangup(d1);  
}
```

DTTRAP.C

This routine traps CTRL-C interrupts.

```
/*LIBRARY.
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_trap      Trap <CTRL-C> Interrupts
index              Trap <CTRL-C> Interrupts
```

```
synopsis
```

```
    #include <stdio.h>
    #include "dectlk.h"
```

```
    dt_trap()
```

```
description
```

Set the global dt_abort flag if the user types <CTRL-C> at the command terminal. (On UNIX, this is interpreted as catching the INTERRUPT signal, which is not necessarily <CTRL-C>, and which may be generated by running the "kill" system program.

When the interrupt is received, pending I/O is cancelled (on those operating systems where this makes sense).

If dt_abort is set TRUE when the interrupt is received, the program aborts.

No error is returned.

```
#endif
```

```
#include <stdio.h>
#include "dectlk.h"
```

```
#ifdef UNIX
#include <signal.h>
```

```
static
catch()
```

```
{
    if (dt_abort)
        _exit(2);
    dt_abort = TRUE;
}
```

```
dt_trap()
```

```

/*
 * Trap CTRL-C interrupts.
 */
{
    signal(SIGINT, catch);
    signal(SIGTERM, catch);
}
#endif

#ifdef vms
#include <ssdef.h>
#include <signal.h>

static
catch()
{
    register DECTALK *dt;

    if (dt_abort)
        _exit(55+ABORT);
    dt_abort = TRUE;
    for (dt = dt_head; dt != NULL; dt = dt->link)
        sys$unuse(dt->unit);
}

dt_trap()
/*
 * Trap CTRL-C interrupts.
 */
{
    signal(SIGINT, catch);
}
#endif

#ifdef rxx
#include <cx.h>
#include <qiofun.h>
#include <qioreg.h>
#include <qiofid.h>
#define QIO_EFN 1

static
catch()
{
    register DECTALK *dt;

    astsat(); /* AST entry */
    if (dt_abort)
        _exit(55);
    dt_abort = TRUE;
    /*
     * Kill all pending DECTalk I/O
     */
    for (dt = dt_head; dt != NULL; dt = dt->link) {
        qio((IO_KIL, dt->unit, QIO_EFN,
            dt->ioarg, NULL, dt->parm));
    }
    _exit(1); /* AST exit */
}

```

```

static DISPARM newparm = { NULL, 0, catch };

di_trap()
/*
 * Trap CTRL-C interrupts.
 */
{
    qraw(10LATA, fileno(stdin), Q10LCA,
        NULL, NULL, &newparm);
}
#endif
#endif /* !t11 */

/*else
catch()
/*
 * Executed by the operating system if an interrupt is
 * denied.
 */
{
    if (&di_abort)
        **fail();
    di_abort = TRUE;
}

di_trap()
/*
 * Trap CTRL-C interrupts.
 */
{
    seten(catch);
}
#endif

```

DTVISLC

This routine generates a visible ASCII representation of a character stored in the work buffer.

```
/*LIBRARY
*/
```

```
#ifdef DOCUMENTATION
```

```
title dt_visible      Generate Visible Representation
index      Generate Visible Representation
```

synopsis

```
char      work120; /* Output buffer      */

char *
dt_visiblec, work)
int      c; /* Character to dump      */
char      work1; /* Work buffer      */
```

description

A visible ASCII representation of the character is stored in the work buffer. A pointer to the end of the output string is returned.

Note that this routine is independent of DEClibc definitions (except that it knows about the DT_ERROR and DT_TIMEOUT error codes).

```
#endif
```

```
#include <stdio.h>
#include "declib.h"
```

```
char *
dt_visiblec, buffer)
register int      c; /* Character to convert      */
register char *buffer; /* Where to store conversion */
```

```

/*
 * Make a character "visible" ASCII.
 * Return a pointer to the trailing EOS.
 */
{
    register int    flag;

    switch (c) {
    case NUL:
        strcpy(buffer, "<NUL>");
        break;

    case DT_ERROR:
        strcpy(buffer, "<ERROR>");
        break;

    case DT_TIMEOUT:
        strcpy(buffer, "<TIMEOUT>");
        break;

    case ESC:
        strcpy(buffer, "<ESC>");
        break;

    case DCS:
        strcpy(buffer, "<DCS>");
        break;

    case CSI:
        strcpy(buffer, "<CSI>");
        break;

    case ST:
        strcpy(buffer, "<ST>");
        break;

    default:
        flag = (c >= 0x7F)
            ? ((c < ' ' && c != '\n' && c != '\r'))
            : 0;
        if (flag)
            *buffer++ = '^';
        if ((c & 0xFF) >= 0x80) {
            c -= 0x80;
            *buffer++ = '~';
        }
        if (flag && c < ' ') {
            *buffer++ = '^';
            *buffer++ = c + 64;
        }
        else if (flag || c == '\n' || c == '\r')
            *buffer++ = c;
        if (!flag)
            *buffer++ = ' ';
        *buffer = EOS;
        return (buffer);
    }
    return (buffer + strlen(buffer));
}

```

HELLO.C

This is a very simple test program, to show that DECtalk is operating correctly.

```

/*BUILD
#include <decctl.h>
#include <dtlib/decctl.h>
#include <dtlib/lib/errno.h>
*/

#include <stdio.h>
#include "decctl.h"
#ifdef vms
extern int      errno;
#define IO_ERROR      errno
#else
#define IO_ERROR      0
#endif

DECTALK *dt;

main(argc, argv)
int      argc;
char     *argv[];
{
    char     *dev;

    dev = "tty7:";
    if (argc > 1)
        dev = argv[1];
    if ((dt = dt_open(dev)) == NULL) {
        perror(dev);
        printf("Can't open DECTalk\n");
        exit(IO_ERROR);
    }
    dt_debug = TRUE; /* log text */
    dt_trap(); /* CTRL-C trap enabled */
    printf("calling init\n");
    if (dt_init(dt))
        printf("Can't initiate DECTalk\n");
    else {
        printf("initialized\n");
        dt_devfdt, P2.NODE, NODE_SQUARE, -1);
        dt_talk(dt, "Hello world.");
        dt_sync(dt);
        dt_dump("after sync", &dt_reply);
        dt_close(dt);
        printf("Success.\n");
    }
}

```

BASIC-PLUS PROGRAM EXAMPLE

7

This chapter provides the source listings of a simple DECTalk telephone answering program, written in BASIC-PLUS for RSTS/E. You can copy and use this program; however, the program is only a model, and cannot cover all possible DECTalk applications.

RSTS/E SYSTEMS

On some RSTS/E systems, you may need system manager privileges to run this program. Please refer to the appropriate RSTS/E manuals for more information.

```
10      EXTEND
20      !*
      !* DECTalk function library and a sample application.
      !* The function library generally duplicates the C
      !* library, with some minor simplifications.
      !*
      !* The sample program reads a string of numbers from
      !* the keypad and speaks them as a number, and as a
      !* string of digits. The '*' key functions as a dollar
      !* sign, and the '#' key functions as a decimal point.
      !* The program also illustrates how an application
      !* might manage keypad timeouts.
      !*
100     !*
      !* Defaults
      !*
      DEF.LB4 = "KR2:"           ! DECTalk device
      \ DEF.LOG4 = "yes"        ! Assume log?
```

```

1000  !*                                     4
      !* Main program                                     4
      !*                                     4
      ! Initialize DECTalk and start the DEMO             4
      ! Channel 1      Console keyboard for parameters  4
      ! Channel 2      Log file                           4

1010  open "kb:" for input as file 1%             4
      \ kb% = FNprompt("DECTalk terminating", DEF.kb%)  4
      \ DT.log% = (FNyesno("Enable logging", DEF.log%))  4
      \ debug% = (FNyesno("Enable debug printouts", "yes")) 4
      \ retries%, ncall% = 0%                       4 ! Clear counters
      \ error.count% = 0%                             4 ! No errors yet
      \ if (debug% or DT.log%) then                   4 ! Need a log file.
          logfile% = FNprompt("Debug log file", "kb:")  4
          \ open logfile% for output as file 2%         4

1100  while (FNinit%(kb%))                         4 ! Initialize DECTalk
      \ q% = FNlog%("Initialization")                4
      \ retries% = retries% + 1%                     4 ! Count initializations
      \ while (FNanswer%)                             4 ! Answer the phone
          \ if (FNprocess%) then                      4 ! Do this call
              ncall% = ncall% + 1%                   4 ! Got a call
              \ retries% = 0%                         4 ! Clear retry

1200  goto 1800 if (debug% and error.count% > 0%)    4
      \ if (retries% > 2%) then                       4 ! Trouble?
          q% = FNlog%("Too many retries")            4
          \ goto 1800                                4 ! Fatal.

1300  next%                                         4 ! For all calls
      \ next%                                         4 ! For all retries

1000  q% = FNlog%("finished after " + num$(ncall%))  4
      \ close 2% if DT.log%                          4

1900  goto 32767                                   4 ! All done

2000  def+ FNprocess%                               4
      !                                     4
      !      F N p r o c e s s %                   4
      !                                     4
      ! User process. Read a number from the keypad and 4
      ! speak it out. Return when phone is to be hung up. 4
      ! Return TRUE% if ok, FALSE% on error.           4
      !                                     4

2010  FNprocess% = FALSE%                           4 ! Assume failure
      \ nkeys% = 0%                                  4 ! Count button presses
      \ q% = FNlog%("answered")                      4
      \ q% = FNspee%("Imp :ra 100) Welcome to DECTalk.") 4
      \ q% = FNspee%("It is now " + time$(0%))       4
          + " on " + date$(0%) + ",")                4
      \ q% = FNspee%("Enter a number, the star key means") 4
      \ q% = FNspee%("dollar sign, while the number-sign") 4
      \ q% = FNspee%("key means decimal point.")     4
      \ if (not (FNphone%("20"))) then                4 ! turn the keypad on
          q% = FNlog%("error assembling keypad")      4
          \ goto 2080                                4 ! Error exit

```

```

2020  if (not FNtestX(R3.FH.DFFHDKX)) then          &
      q% = FNlogX("enable keypad, state: " + num1(R3X)) &
      \ goto 2080                                ! Error exit &
2030  while TRUEX                                  ! For all numbers &
      \ timer% = 10X                              ! For first character &
      \ work% = ""                                ! Input buffer &
      \ while TRUEX                                ! Get the number &
          \ c% = FNkeyX(timer%)                   ! Read a character &
          \ c% = chr$(c%)                          ! Get both flavors &
          \ goto 2080 if c% = "H"                  ! Hangup &
          \ goto 2080 if c% = "E"                  ! Error from RST5/E &
          \ goto 2080 if c% = "X"                  ! Escape sequence error &
          \ goto 2050 if c% = "T"                  ! Timeout &
          \ c% = "0" if c% = "."                  ! Fix Funny &
          \ c% = "1" if c% = "2"                  ! Buttons &
          \ work% = work% + c%                     ! Stuff it &
          \ timer% = 2X                            ! Short prompt now &
      \ next                                       ! Read a number loop &
2050  goto 2060 if (work% = "")                  ! Did we read anything? &
      \ q% = FhspeakX("You entered " + work% + ",") &
      \ q% = FhspeakX("that is" + FNexpand$(work%) + ",") &
      \ next                                       ! Read all numbers &
2060  FNprocess% = TRUEX                          ! Normal completion &
2080  q% = FNphoneX("21")                         ! Turn off keypad &
      \ q% = FNhangupX                             ! And hang up the phone &
      \ q% = FNlogX("process exit after " + num1(RInkeyX)) &
2090  fpend                                         &
3000  !*
      !*           f h e x p a n d $( t e x t %)
      !*
      !* Expand a number string into its component bytes.
      !* Note that this would be useful in a "bank by phone"
      !* application to speak a number, digit by digit, so
      !* the caller could copy it down. If the input is
      !* "12.34", the output will be "1 2 point 34". Note
      !* the leading blank.
      !*
      def FNexpand$(text%)
      \ q% = ""                                     ! Output work &
      \ for q% = 1% to len(text%)                 ! For each byte &
          \ q1% = mid$(text%, q%, 1%)             ! Locate it &
          \ q1% = "point" if q1% = "."             ! Fix the &
          \ q1% = "minus" if q1% = "-"             ! special &
          \ q1% = "dollar sign" if q1% = "$"       !       case &
          \ q% = q% + " " + q1%                    ! and stuff it &
      \ next q%                                    ! Do 'em all &
      \ FNexpand% = q%                             ! That's it &
3090  fpend                                         &

```

```

10000  !*                                     &
!* Basic-Plus Support functions for DEDtalk &
!* Note that the code is not particularly fast and some &
!* of the error conditions that are handled by the C &
!* version of the Escape Sequence parser are ignored. &
!&
!*&
! Note: the following channels are used: &
!      0      DEDtalk input &
!      9      DEDtalk output &
!      2      Log file &
!             If DT.log% is TRUE, a log file is open &
!             on channel 2 &
!&
!*&
!* Application programs call the following routines &
!*&
! FInit%(ihs)      Initialize DEDtalk on ihs: &
! FAnswer%        Finish last call, answer next &
! FHangup%         Hangup the call &
! FNew%(timeout%) Read a character with timeout &
!                 Returns the character, or &
!                 E      Error (from RSTS) &
!                 H      Phone hung up &
!                 I      Timeout &
!                 X      Bad Escape sequence &
! FTimeout%(sec%)  Set specified timeout, 0 = none &
! FMiss%(R2%, R3%) Test current reply, true if ok &
!                 R3% is -1 to ignore it. &
!                 FTest%( ) checks character, &
!                 intermediates, and finals. &
! FReply%(R3%)     Test phone reply (R2% checked) &
! FSend%(text%)    Send text to DEDtalk. &
! FReply%(text%)   Send text followed by <CR><LF> &
! FLog%(text%)     Log text message &
! FVisible%(char%) Make character printable for &
!                 logging and debugging msg. &
! FMessage%(text%, R2%, R3%) &
!                 Send DCS seq. test reply. &
!                 text is "P2;P3...", &
!                 return TRUE if ok. &
!                 Note: FMessage%( ) ignores &
!                 R3.PH.TIMEOUT replies. &
! FPhone%(text%)   Send DCS sequence, test reply &
!                 text is "P3;P4...", &
!                 R2% must be R2.PHON% &
!                 R3% not tested &
!                 FNew% called if error &
!                 returns as FMessage%( ) &
! FFunny%(text%)   Print bad sequence on the log &
! FDump%(text%)    Dump the current reply &

```

```

10010 1*
10011 1* The application program generally doesn't call the
10012 1* following routines.
10013 1*
10014 1* FNsaveIf(char)      Save type-ahead character,
10015 1*                      return TRUE if saved.
10016 1* FNsendsIf(text)     Send DECtalk DCS message,
10017 1*                      text is "FS;FS;...",
10018 1* FNsendsIf(text)     Send DECtalk CSI message,
10019 1*                      text has parm, inter, finis.
10020 1* FNfromdecTalk(text) Read key or escape sequence.
10021 1* FNgetseq(text)      Read key or escape sequence.
10022 1* FNget(text,timeout) Read one character,
10023 1*                      parity is stripped,
10024 1*                      <NUL> and <DEL> are ignored.
10025 1*                      Return 0X on timeout.
10026 1*                      Other errors are fatal.
10027 1* NOTE: do not use fngotX() to
10028 1* read from the telephone keypad.
10029 1* FNread2(timeout)    Read a record from DECtalk
10030 1*
10031 1*
10032 1* Globals:
10033 1*
10034 1* R1%, R2%, R3% current reply parameters
10035 1* set by FNgetsequenceX()
10036 1* DT.timeoutX     TRUE if keypad timeouts are
10037 1*                  currently enabled.
10038 1* error.countX    incremented on serious errors
10039 1* ESCX           ESC character (parity bit cleared)
10040 1* CANX           CTRL-U character (cancel sequence)
10041 1* SUBX           CTRL-Z character
10042 1* CSIX           CSI character
10043 1* DCSX           DCS character
10044 1* STX           ST character
10045 1* ESC%           An escape to send chr$(155X)
10046 1* CRLF%          Carriage-return, Line-feed
10047 1* VT%           Vertical Tab (DECtalk flush)
10048 1* R2.PHONEX      R2% phone reply
10049 1* R3.PH.ONH00X%  R3% (phone hung up)
10050 1* R3.PH.OFFH00X% R3% (phone is alive)
10051 1* R3.PH.TIMEOUTX R3% (keypad timeout)
10052 1*
10053 1* DT.anything     reserved for local buffers
10054 1* SEQ.anything    reserved for sequence parser
10055 1* qf.anything:    general temporaries
10056 1*

```

```

10100 def FNinitX(hb*)
10101 !
10102 ! F N i n i t X ( h b * )
10103 !
10104 ! Initialize the DECTalk device
10105 ! Return TRUEX if ok, FALSEX if error
10106 !
10107
10110 /*
10111 /* Open the terminal in "binary" mode.
10112 /* Then initialize all constants.
10113 /*
10114 open kb$ for input as file B$, mode 32X+16X+4X+1X
10115 \ open kb$ for input as file B$, mode 32X+16X+4X+1X
10116 \ DT.incountX, DT.inwendX = 0X ! Clear input buffer
10117 \ SEQ.stateX = 0X ! Clear input state
10118 \ DIM DT.pX(3), SEQ.pX(3) ! 3 parameters
10119 \ DIM qX(256) ! For debugging
10120 \ TRUEX = (1X = 1X) ! TRUE
10121 \ FALSEX = not TRUEX ! FALSE
10122 \ ESCX = 27X ! Escape
10123 \ ESC$ = chr$(ESCX + 128X) ! Define escape char
10124 \ VT$ = chr$(ascii('K') - 64X) ! DECTalk flush char
10125 \ CRLF$ = chr$(13X) + chr$(10X) ! <CR><LF> string
10126 \ CANX = ascii('U') - 64X ! CANCEL (CTRL-U)
10127 \ SUBX = ascii('Z') - 64X ! SUBstitute (CTRL-Z)
10128 \ CSI$ = ascii('[') - 64X + 128X ! Define
10129 \ DCS$ = ascii('P') - 64X + 128X ! C1 control
10130 \ STX = ascii('\') - 64X + 128X ! characters
10131 \ R2.PHONES = 70X
10132 \ R3.PH.CMH00X = 0X
10133 \ R3.PH.OFFH00X = 1X
10134 \ R3.PH.TIME00X = 2X
10135
10120 qX = FNsendX(chr$(ascii('G') - 64X + 128X)) ! CTRL-G
10121 \ qX = FNgetX(2X) while (qX > 0X) ! Drain text
10122 \ qX = FNdecX("B2") ! No local>host
10123 \ qX = FNdecX("c") ! "Who are you"
10124 \ qX = FNfromdectalkX(5X) ! Read escape sequence
10125 \ if (DT.charX < 55X ! Cheat
10126 or DT.finalX < 's' ! for
10127 or DT.privateX < '?' ! DECTalk
10128 or R1X < 18X) then ! reply
10129 qX = FNtunnyX("initialization")
10130 \ FNinitX = FALSEX ! Return failure
10131 \ goto 10190 ! from FNinitX()
10132
10130 qX = FNsendX(ESC$ + "lp") ! Soft Terminal Reset
10131 \ qX = FNdecX("B01") ! Set MODE SQUARE
10132 \ DT.timeoutX = 0X ! No timeouts now
10133 \ FNinitX = TRUEX ! Return TRUE
10134
10190 friend

```

```

10200 def* FNanswer%
!
!       F N a n s w e r %
!
! Finish off any current call (hanging up the phone)
! Then setup and answer the next call.
! Return TRUE% if the call was answered.
! Return FALSE% if there's serious problems.
!
!
10210 FNanswer% = FALSE%           ! Assume error
\ q% = FNget$(%) while (q% > 0%) ! Obtain text
\ goto 10290 if (not FNphone$( "" )) ! poll status
\ if (R3% = R3.PH.OFFHOOK%) then ! If alive,
\ goto 10290 if (not FNhangup%) ! hangup phone

10220 if (R3% <> R3.PH.ONHOOK%) then ! still alive?
\ q% = FNfunny$( "hangup/poll" ) ! Ugh.
\ goto 10290 ! exit this

10230 goto 10290 if (not FNphone$( "01" )) ! answer 1 ring
\ if (R3% <> R3.PH.ONHOOK%) then ! ok?
\ q% = FNfunny$( "enable answer" ) ! Jrk.
\ goto 10290 ! exit this

10240 q% = FNtruncdecfloat$(0%) ! wait for ring
\ if (q% <> 0%) then ! ok?
\ q% = FNfunny$( "waiting for ring" ) ! oops.
\ goto 10290 ! exit this

10250 if (not FNplay$(R3.PH.OFFHOOK%)) then
\ q% = FNfunny$( "expecting offhook" )
\ goto 10290

10260 DT.timeout% = 0%           ! No timeouts now
\ DT.pending% = ""              ! Nothing pending now
\ FNanswer% = TRUE%             ! ok.

10290 fnext

10300 def* FNtimeout$(seconds%)
!
!       F N t i m e o u t $( s e c o n d s %)
!
! Enable or disable keypad timeout. Note that
! FNtimeout$(non-zero%) will examine the state of the
! type-ahead buffer before actually enabling timeouts
!
!
10310 if (seconds% > 0%) then
\ seconds% = 0% if (len(DT.pending%) > 0%)
\ if (seconds% > 0%) then
\ q% = FNsyntax% ! make sure all heard
\ seconds% = 0% if (len(DT.pending%) > 0%)
! If the program requests that timeouts be turned
! on, perform some special checks that the user
! hasn't already entered any text (which would be
! stored in one of the type-ahead buffers. If
! something is pending, turn timeouts off. This is
! needed because RSTS allows a program to run even
! if all output has not been sent to the device.

```

```

10320 goto 10390 if (seconds% = DT.timeout%) ! Don't resend &
! print #2, "timeout wait "; seconds% := (DT.log2) &
! q% = FNphone%("30;" + num%(seconds%)) &

10330 DT.timeout% = seconds% ! save timeout state &
! if (not FNtest%(R3.PH.OFFHOOK%)) then &
! q% = FNtunny%("timeout") &

10390 fwend &

10400 def% Fhsync% &
! &
! F h s y n c % &
! &
! Synchronize with DECTalk. This function returns &
! when all text sent to DECTalk has been spoken. &
! Warning: if you have sent much text to DECTalk and &
! the moon is in the wrong phase, there is a very &
! slight chance that this code could get an operating &
! system timeout, even though there are no errors. &
! &

10410 q% = Fhsend%(vts) ! Flush speech &
! q% = Fhds%("1") ! Send sync &
! if (not FNmessage%("32", 92, -1)) then &
! q% = Fhfunny%("sync") &

10490 fwend &

10500 def% Fhangup% &
! &
! F h a n g u p % &
! &
! Hangup the telephone. Returns when the phone is &
! properly on-hook (TRUE%) or an error is detected. &
! &

10510 Fhangup% = FALSE% ! Assume problems &
! goto 10590 if (not FNphone%("11")) ! send hangup &
! while (R3% = R3.PH.OFFHOOK%) ! wait until &
! ! sleep 5% ! it's hung up &
! ! goto 10590 if (not FNphone%("")) &
! next ! loop forever &
! Fhangup% = TRUE% ! OK now. &

10590 fwend &

10600 def% FNphone%(text%) &
! &
! F N p h o n e % ( t e x t % ) &
! &
! Send a phone message, return the FNmessage% code. &
! You should then call FNtest% to see just what the &
! phone state actually is. &
! &

10610 if (text% <> "") ! if extra parameters &
! then text% = "50;" + text% ! tack them on, else &
! else text% = "50" ! just do status report &

```

```

10620 FNphone% = FNsave%$(text$, R2.PHONE%, -1%) 5
10690 friend 5
10700 def% FNsave$(char%) 5
! 5
! FNsave$(char%) 5
! 5
! if the char% came from a user data entry, save it in 5
! the DT.pending% buffer and return TRUE%, otherwise, 5
! return FALSE%. Note that FNsave%() watches for 5
! asynchronous typed timeouts. 5
! 5
! Note that unreasonable amounts of type-ahead may 5
! cause the program to overflow memory. 5
! 5

10710 FNsave% = TRUE% 5
! if FNplest$(R3.PH.TIMEOUT%) then ! Timeout? 5
! goto 10790 if (DT.timeout% = 0%) ! Disabled? 5
! DT.timeout% = 0% ! None now 5
! goto 10790 if (len(DT.pending%) > 0%) 5
! char% = asc$(chr$(DT.pending%)) ! Save 'T' 5

10720 if (instr(0%, "0123456789*#ABCDT", chr$(char%)) = 0%) 4
! then FNsave% = FALSE% 4
! else DT.pending% = DT.pending% + chr$(char%) 4

10790 friend 4

10800 def% FNkey%(timeout%) 4
! 4
! FNkey%(timeout%) 4
! 4
! Read a typed character (in there is one in the 4
! type-ahead buffer, or read a character or escape 4
! sequence from DECtalk. The timeout% parameter is 4
! non-zero to enable timeouts. 4
! 4
! Note that the timeout parameter, if non-zero, will be 4
! extended to compensate for RSTS/E output buffering. 4
! 4
! FNkey% ignores user timeout if timeout was disabled. 4
! 4

10810 q% = FNtimeout$(timeout%) ! Set/clear timeouts 4
! if (len(DT.pending%) > 0%) then 4
! FNkey% = asc$(DT.pending%) 4
! DT.pending% = right$(DT.pending%, 2%) 4
! goto 10890 4

10820 timeout% = (timeout% * 4%) + 60% if timeout% > 0% 5
! q% = FNreaddecalk$(timeout%) 5
! c% = asc$(chr$(q%)) if FNplest$(R3.PH.TIMEOUT%) 5
! DT.timeout% = 0% if (q% = asc$(chr$(q%))) 5
! c% = asc$(chr$(q%)) if FNplest$(R3.PH.DHDDOK%) 5
! q% = asc$(chr$(q%)) if (q% <= 0%) ! D.S. error 5
! FNkey% = q% 5

10890 friend 5

```

```

12000 def* FNmessage%(text$, t2%, t3%)
!
! F N m e s s a g e % ( t e x t $ , t 2 % , t 3 %)
!
! Send a DECtalk DCS sequence to DECtalk and wait
! for a reply. Make sure the reply mentions the t2t
! and t3t parameters. Return TRUE% if ok, else FALSE%.
!
! A keyed timeout (escape sequence) may be read when
! we are expecting some other reply. In this case,
! the timeout is ignored, the timeout status flag is
! set FALSE and we read another sequence.
!

12010 q% = FNdec%(text$)      ! Send the sequence
\ FNmessage% = TRUE%      ! Assume success

12020 q% = FNfrondecalk%(t2%) ! get something
\ goto 12020 if (q% = ST%) ! ignore string term.
\ goto 12020 if (t%aveX(q%)) ! save type-ahead
\ if not (FNtest%(t2%, t3%)) then ! Check seq.
    q% = FNfunny%("message test error")
    \ FNmessage% = FALSE%

12090 f%end

12100 def* FNfrondecalk%(timeout%)
!
! F N f r o n d e c a l k % ( t i m e o u t %)
!
! Read an escape sequence or keyed character. Dump
! junk between DCS final and string terminator.
!

12110 if (SEQ.state% <> 0% and SEQ.state% <> ST%) then
    gosub 12200      ! Grab the sequence
    \ goto 12160      ! And return char value

12120 SEQ.state% = 0%      ! Nothing pending now
\ q% = FNgetsequence%(timeout%) ! Get something
\ gosub 12200      ! Make it current
\ q% = FNtoss% if (q% = DCS%) ! Toss junk until ST

12180 FNfrondecalk% = DI.char% ! Return character

12190 f%end

12200 !
! Subroutine called from FNfrondecalk% to copy the
! last escape sequence read into the "current sequence"
! buffer. This is needed to skip over junk between
! the DCS final and the string terminator.
!

```

```

12210 DT.char% = SEQ.char%      ! Sequence type          4
! DT.final% = SEQ.final%      ! Sequence terminator  4
! DT.private% = SEQ.private%  ! private characters  4
! DT.inter% = SEQ.inter%      ! Intermediates      4
! DT.parm% = SEQ.parm%        ! Parameter count     4
! R1%, DT.p%(1) = SEQ.p%(1)   ! Param'n           4
! R2%, DT.p%(2) = SEQ.p%(2)   !                     4
! R3%, DT.p%(3) = SEQ.p%(3)   !                     4
! \ print "R1%, dt.parm%: "parm%: "R1%: R2%: R3%  4

12220 return

12300 def* FNtoss%               4
!                                     4
!       F N t o s s %          4
!                                     4
! Called after reading a DCS, this function reads  4
! text to the terminating string terminator.      4
!                                     4

12310 SEQ.state% = 0%           4

12320 q% = FNgetsequence%(5%)    4
! if (q% <= 0% or (q% >= 128% and q% <= 159%))  4
! then FNtoss% = q%             4
! else goto 12320               4

12330 friend                    4

12340 def* FNgetsequence%(timeout) 4
!                                     4
!       F N g e t s e q u e n c e % ( t i m e o u t % ) 4
!                                     4
! Read the next character on the next ANSI standard 4
! Escape Sequence.                                     4
!                                     4
! Initialize by setting SEQ.state% to zero. Returns: 4
! SEQ.state%      sequence final character           4
!                                     4
! Note the following goto's:                          4
! goto 12310 to read the next character in a sequence. 4
! goto 12320 to continue processing (needed when escape 4
!           followed by a second character turns      4
!           into a C1 control character).             4
! goto 12320 to exit an ESC sequence                  4
! goto 12330 to exit after reading a DCS/CSI sequence. 4
! goto 12340 to exit a C0 control within a sequence.  4
!                                     4
! The following is set by this module:                4
! SEQ.char%      the character or sequence type       4
! SEQ.final%     the sequence final for CSI/DCS/ESC  4
! SEQ.state%     zero when sequence ends.             4
! SEQ.parm%      number of parameters                4
! SEQ.p%(i)      each parameter as read              4
! SEQ.inter%     intermediates                       4
! SEQ.private%   private introducer, 'X' if error seen 4
!                                     4

```

```

13010  DT.c% = fgetc(stdin);      ! Get a character      *
13020  if (DT.c% = ESC%           ! If the character    *
    or DT.c% = CR%              ! introduces a new    *
    or DT.c% = DC%)) then       ! sequence, initialize *
    SEQ.state% = DT.c%          ! all work areas.    *
    ! \ print %2X, "seq start: "; fvisible%(dt.c%) *
    ! \ SEQ.inters% = ""         *
    ! \ SEQ.private% = ""       *
    ! \ SEQ.param% = 0%         *
    ! \ SEQ.p%(1%), SEQ.p%(2%), SEQ.p%(3%) = 0% *
    ! goto 13010                ! go read another byte *

13030  goto 13140 if (SEQ.state% = 0%) ! done if no sequence *
    ! Continue processing the current sequence *
    ! *
    ! if (DT.c% >= 128% and DT.c% < 160%) ! C1 control *
    or (DT.c% = CAN%)                ! or CTRL-U *
    or (DT.c% = SUB%) then           ! or CTRL-Z *
    SEQ.state% = 0%                  ! force sequence exit *
    ! \ print %2X, "c0 control: "; fvisible%(dt.c%) *
    ! goto 13140                    ! and return C0 control *

13040  goto 13140 if (DT.c% < 32%)    ! Exit if C0 control *
    ! *
    ! Process C1 introducers, intermediates, parameters, *
    ! sequence terminators and other strange stuff *
    ! *
    ! if (DT.c% < 48%) then           ! Intermediate *
    SEQ.inters% = SEQ.inters% + chr(DT.c%) *
    ! \ print %2X, "intermediate: "; fvisible%(dt.c%) *
    ! goto 13010                    ! Go get another *

13050  if (SEQ.state% = ESC%) then    ! <ESC> -> C1 control? *
    q% = DT.c% and 63%               ! Mask out lower 6 bits *
    ! goto 13130 if (SEQ.inters% < "" or c% >= 32%) *
    ! DT.c% = q% + 128%              ! Make it a C1 control *
    ! \ print %2X, "c0 -> c1: "; fvisible%(dt.c%) *
    ! goto 13020                    ! Process C1 control *

13060  goto 13120 if (DT.c% >= 64%)   ! Sequence terminator *
    ! \ print %2X, "not terminator: "; fvisible%(dt.c%) *
    ! goto 13080 if (DT.c% < 60%)    ! private introducer? *
    ! \ print %2X, "private introducer: "; fvisible%(dt.c%) *
    ! if (SEQ.param% > 0%)           ! maybe, but illegal *
    then SEQ.private% = "X"          ! after first param. *
    else SEQ.private% = chr(DT.c%)   *
    ! \ SEQ.param% = 1%              ! Mark "param" *

13070  goto 13010                    ! Read another char. *

```

```

13080 !                                     &
! We know the character is in the range '0'..'9' or &
! ':' (separator) or '?' (illegal separator) &
!                                     &
SEQ.parm% = 1% if (SEQ.parm% = 0%) &
! \ print #2%, "param or sep: "; invisible$(dt.c%) &
\ if (SEQ.inte% <= 99) then ! No param's after &
    SEQ.inte% = "" ! Internediales. &
    \ SEQ.privat% = "X" ! Mark it invalid. &
    ! \ print #2%, "parm or separator after inter" &

13090 if (DT.c% <= ascll("0")) then ! Parameter digit &
    SEQ.pt(SEQ.parm%) = ! Note it's a number &
    (SEQ.p%(SEQ.parm%) * 10%) + (DT.c% - ascll("0")) &
    ! \ print #2%, "digit, param :="; seq.p%(SEQ.parm%) &
    \ goto 13010 ! Go read another byte &

13100 if (DT.c% = ascll(":")) then ! parameter separator &
    SEQ.parm% = SEQ.parm% + 1% &
    \ goto 13010 ! and read another byte &

13110 SEQ.privat% = "X" ! '?' isn't a separator &
! \ print #2%, "bad separator "; invisible$(dt.c%) &
\ goto 13010 ! read another byte &

13120 !                                     &
! Character is a sequence terminator. If no parameters &
! were read, return a single zero-valued parameter. &
!                                     &
SEQ.parm% = 1% if (SEQ.parm% = 0%) &
! \ print #2%, "terminator: "; invisible$(dt.c%) &

13130 !                                     &
! Jump here at the end of the sequence. &
!                                     &
SEQ.final% = chr$(DT.c%) ! Set the final &
\ DT.c% = SEQ.stat% ! Get return value &
\ SEQ.stat% = 0% ! Not in a sequence &

13140 SEQ.char% = DT.c% ! Character code &

13180 FMgetsequence% = SEQ.char% ! Return value &

13190 fnext ! That's all, folks &

14100 def* [send$(text)] &
!                                     &
! FM s e n d $( t e x t ) &
!                                     &
! Send a string of text to DECtalk. Note, the text &
! length must be less than the DECtalk terminal buffer &
! size. &
!                                     &

```

```

14110  (field #9%, len(text%)) as q%          4
      \ let q% = text%                      4
      \ put #9%, record 4096%, count len(text%) 4
      \ if (debug% and DT.log%) then        4
          print #2%, using 'sent: $$$ ', len(text%); 4
          \ change text% to q%              4
          \ print #2%, FNvisible(q%(q%));    4
          for q% = 1% to q%(q%)             4
              \ print #2%, ""               4
14190  fnend                                  5
14200  def* FNesc%(text%) = FNend%(ESC% + "L" + text%) 5
      !                                     5
      !      F N e s c % ( t e x t % )      5
      !                                     5
      ! Send a Control Sequence to DECTalk.  5
      !                                     5
14300  def* FNdec%(text%) =                    5
      FNend%(ESC% + "PD;" + text% + ";" + ESC% + "%") 5
      !                                     5
      !      F N d e c % ( t e x t % )      5
      !                                     5
      ! Send a DECTalk Device Control Sequence. 4
      ! Note that the DECTalk P1 parameter, final, and 3
      ! string terminator are automatically included. 4
      !                                     5
14400  def* FNspeak%(text%) = FNend%(text% + CRLF%) 5
      !                                     4
      !      F N s p e a k % ( t e x t % )  4
      !                                     4
      ! Send a line of text to DECTalk, followed by <CR><LF> 5
      !                                     5
15000  def* FNget%(timeout%)                   5
      !                                     5
      !      F N g e t % ( t i m e o u t % ) 5
      !                                     5
      ! Read the next character from DECTalk. 5
      ! timeout% = 0% means none             5
      ! timeout% > 0% wait timeout% seconds 5
      ! timeout% = -1% return immediately if none 5
      ! return 0% on timeout, fatal exit on other errors 4
      ! The character is forced into the range 000 to 127 5
      ! and <shu> (000) and <DEL> (127) are ignored 4
      !                                     5
15010  while (DT.incount% > DT.inend%)      ! None saved? 5
      \ goto 15000 if (not FNread%(timeout%)) 5
15020  next1                                  5

```

```

15090 field #0%, DT.incount% as q$, 1% as q1 : get char      1
      \ DT.incount% = DT.incount% + 1% : step index      2
      \ q% = ascii(q%) and 127% : drop parity      3
      \ goto 15110 if (q% = 0% or q% = 127%) : ignore nulls 4
      \ FNgetc% = q% : return char      5
      \ goto 15090 : exit      6

15080 FNgetc% = 0% : got timeout      1

15090 fncnd      1

15100 def FN-read%(timeout%) :      1
      :      FN-read%(timeout%)      2
      :      :      3
      :      Read a record from DECTalk.      4
      :      timeout% = 0% means none      5
      :      timeout% > 0% wait (timeout% seconds)      6
      :      timeout% = -1% return immediately if none      7
      :      return FALSE% on timeout, fatal exit on other errors      8
      :      return TRUE% on success.      9
      :      :      10

15110 goto 15120 if DT.incount% < DT.inend% : Still stuff      1
      \ on error goto 15150 : grab error      2
      \ q% = syschr$(31) + chr$(9%) : no echo      3
      \ + syschr$(4%) + chr$(9%) : add mode      4
      \ wait timeout% if timeout% > 0% : timeout      5
      \ get #0% if timeout% >= 0% : read buffer      6
      \ get #0%, record 8192% if timeout% < 0% :      7
      \ DT.inend% = rcount : got it      8
      \ wait 0% : no timeout      9
      \ DT.incount% = 0% : clear index      10
      \ on error goto 15000 : common exit      11
      \ if (debug% and DT.log%) then      12
      : print #2%, using "read: %d", DT.inend% :      13
      : \ field #0%, DT.inend% as q% :      14
      : \ change q% to q1 :      15
      : \ print #2%, FNvisible$(q%); :      16
      : for q% = 1% to q%(0%) :      17
      : \ print #2%, " " :      18

15120 FNread% = TRUE%      1
      \ goto 15190      2

15150 resume 15180      1
      if (err% = 1% and timeout% > 0%) :      2
      or (err% = 1% and timeout% < 0%) :      3
      \ goto 15000 :      4

15180 FNread% = FALSE%      1

15190 fncnd      1

```

```

16050 def* FNtestX(t2X, t3X) =
    (DT.charX = DGSX)      ! Date
    and (DT.fineX = '2')   ! sure
    and (len(DT.intenX) = 6X) ! 11's
    and (len(DT.privateX) < 6X) ! from
    and (R1X = 6X)         ! DECTalk
    and (t2X = R2X)        ! Check R2X
    and (t3X = R3X or t3X = -1X) ! maybe check R3X
    !
    ! FNtestX(t2X, t3X)
    !
    ! Return TRUEX if the current reply is a properly-
    ! formed DECTalk reply sequence whose R2X and R3X
    ! parameters match t2X and t3X. t3X is ignored if
    ! it is -1X.
    !
    !
16100 def* FNptestX(t3X) =      ! Test phone reply
    FNtestX(R2.PHONEFX, t3X)
    !
    ! FNptestX(t3X)
    !
    ! Return TRUEX if the current reply R2X parameter
    ! is R2.PHONEFX and the t3X matches R3X
    !
    !
17000 def* FNFunnyX(textX)
    !
    ! FNFunnyX(textX)
    !
    ! Log an error message and dump the current reply.
    !
    !
17010 errorCountX = errorCountX + 1X
    \ if (DT.logX) then
        print #2X if (errorCountX < 6X)
        \ print #2X, "Illegal reply at " & textX & ". "
        \ FNFunnyX = FNDumpX("")
    !
    !
17100 found
    !
    !
17110 def* FNDumpX(textX)
    !
    ! FNDumpX(textX)
    !
    ! Dump the current reply.
    !
    !

```

```

17110 IF (DT.log%) then
    print #2%, "Last sequence read"
    \ print #2%, " at "; text%: if (text% <> "")
    \ print #2%, " ";
    \ if (DT.char% = 0%)
        then print #2%, "<[MEOUT>"
        else print #2%, FNvisible$(DT.char%);
        \ print #2%, DT-private%: DT-inter%;
        \ for q% = 1% to DT.para%
            \ print #2%, num$(DT.p%(q%));
            \ if (DT.p%(q%) <> 0%)
                \ print #2%, " ";
            \ if ((q% + 1%) < DT.para%)
                \ next q%
        \ print #2%, DT-fine%:
        \ print #2%, "<ST>"; if (DT.char% = DCS%)
        \ print #2%
17180 fnext
17200 def% FNvisible$(c%)
    !
    ! FN v i s i b l e $( c %)
    !
    ! Return "datascope" version of c%
    !
17210 if (c% = ESC%) then FNvisible% = "<ESC>"
    else if (c% = DCS%) then FNvisible% = "<DCS>"
    else if (c% = CSI%) then FNvisible% = "<CSI>"
    else if (c% = ST%) then FNvisible% = "<ST>"
    else if (c% = CR%) then FNvisible% = CRLF%
    else if (c% = VT%) then FNvisible% = "<VT>"
    else if (c% = 13%) then FNvisible% = ""
    else q.via% = (c% >= 127% or c% < 32%)
        \ q% = ""
        \ q% = "<~" if (c% >= 128%)
        \ q% = "<~" if (c% < 32%)
        \ c% = c% and 127%
        \ q% = q% + "~" + chr$(c% + 64%) if (c% < 32%)
        \ q% = q% + chr$(c%) if (c% >= 128%)
        \ q% = q% + "~" if q.via%
        \ FNvisible% = q%
17280 fnext
17300 def% FNlog$(text%)
    !
    ! FN l o g $( t e x t %)
    !
    ! log a text message
    !
17310 if (DT.log%) then
    print #2%, date$(DS%); " "; time$(DT%); " "; text%

```

```

17390      friend
17400      def* FNyesno$(prompt$, default$)
17410      !
17420      ! FNyesno$(prompt$, default$)
17430      !
17440      ! Prompt and get a yes/no answer
17450      !
17460      q% = 0%
17470      \ until (q% = 1% or q% = 5%)
17480      \ q% = FNprompt$(prompt$ + "{Yes/No}", default$)
17490      \ q% = instr(1%, "YES NO", cut$(q%, -1%))
17500      \ next
17510      \ fnyesno$ = {q% = 1%}
17520      friend
17530      def* FNprompt$(prompt$, default$)
17540      !
17550      ! FNprompt$(prompt$, default$)
17560      !
17570      ! Prompt and get a response
17580      !
17590      print #1%, prompt$: " <"; default$: ">? ";
17600      \ input line #1%, q%
17610      \ FNprompt$, q% = cut$(q%, 30%)
17620      \ FNprompt$ = cut$(default$, 30%) if len(q%) = 0%
17630      friend
17640      !
17650      ! Fatal Error Trap
17660      !
17670      error% = err                                ! save error number
17680      \ error.line% = erl                          ! and error line
17690      \ resume 19100                             ! and take fatal exit
17700      !
17710      print                                         ! force new line
17720      \ print "Fatal Error ";                     ! print error message
17730      cut$(right(sys$(chr$(62) + chr$(9%))
17740      + chr$(error%)), 3%), 4%);
17750      " at line"; error.line%                     ! and line number
17760      !
17770      stop
17780      goto 32767
17790      end

```

DECtalk ESCAPE SEQUENCES A

This appendix summarizes the escape sequences (and their parameters) described in this manual. The following tables list escape sequence mnemonics and their ASCII representations.

You can verify each ASCII character by checking the decimal value that appears below the character.

Table A-1 Escape Commands

Mnemonic	Escape Sequence Decimal Value
DA Primary	ESC [0 c 027 091 048 099 Request DECtalk to identify itself. See Table A-2 for reply.
DECAC1	ESC SP 7 027 032 055 Select 8-bit C1 control character reception (accept the high-order bit).
DECSTR	ESC [1 p 027 091 083 112 Reset to power-up state.
DEQTC1	ESC SP 8 027 032 054 Select 7-bit C1 control character reception (truncate the high-order bit).
DECTST	ESC [5 ; Pn y 027 091 083 059 ; ; 121 Initiate local self-tests. See Table A-6 for Pn parameters.
DSR Brief	ESC [5 n 027 091 063 110 Give a brief status report. See Table A-2 for replies.
DSR Extended	ESC [n 027 091 110 Give an extended device status report. See Table A-2 for replies.
DT_DICT	ESC @ 0 ; 4 0 ; z name sub ESC \ 027 080 048 058 052 048 122 ; ; 027 092 Load user dictionary. See Table A-2 for replies.

Table A-1 Escape Commands (Cont)

Mnemonic	Escape Sequence Decimal Value
DT_INDEX	ESC P 0 : 2 0 : P2 z ESC \ 027 080 048 050 050 048 059 ~ 122 027 092 Insert index flag in text. P2 range is 0 to 32767 (sent as ASCII characters).
DT_INDEX_QUERY	ESC P 0 : 2 1 z ESC \ 027 080 048 050 050 050 122 027 092 Request DECTalk to return last index marker spoken. See Table A-2 for reply.
DT_INDEX_REPLY	ESC P 0 : 2 1 : P3 z ESC \ 027 080 048 050 050 048 059 ~ 122 027 092 Insert index flag in text and inform host. P3 range is same as for DT_INDEX. See Table A-2 for reply.
DT_LOG	ESC P 0 : 3 1 : P3 z ESC \ 027 080 048 050 050 048 059 ~ 122 027 092 Set trace and debugging log functions. See Table A-7 for P3 parameters.
DT_MASK	ESC P 0 : 3 3 : P3 z ESC \ 027 080 048 050 050 081 059 ~ 122 027 092 Controls how DECTalk sends escape sequences and keyboard characters to the host. See Table A-8 for P3 parameters.
DT_MODE	ESC P 0 : 0 0 : P3 z ESC \ 027 080 048 050 050 048 059 ~ 122 027 092 Set DECTalk mode. See Table A-3 for P3 parameters.
DT_PHONE	ESC P 0 : 5 0 : Pn : Pn z text ESC \ 027 080 048 050 054 048 059 ~ 255 ~ 122 ~ 027 092 Control attached telephone and telephone keypad interface. See Table A-5 for Pn parameters.

Table A-1 Escape Commands (Cont)

Memorico	Escape Sequence Decimal Value
DT_PHOTEXT	ESC P 0 : 0 z text ESC \ 027 080 048 059 048 122 ^ 027 092 Speak phonetic text.
DT_SPEAK	ESC P 0 : 1 2 : P3 z ESC \ 027 080 048 059 048 050 059 ^ 122 027 092 Enable (P3=1) or disable (P3=0) speaking.
DT_STOP	ESC P 0 : 1 0 z ESC \ 027 080 048 059 048 048 122 027 092 Stop speaking and dump any pending unspoken text.
DT_SYNC	ESC P 0 : 1 1 z ESC \ 027 080 048 059 048 048 122 027 092 Finish speaking current text before processing next command.
DT_TERMINAL	ESC P 0 : 8 2 : P3 z ESC \ 027 080 048 059 055 050 059 ^ 122 027 092 Set local terminal mode. See Table A-4 for P3 parameters.
DECID	ESC Z 027 090 Old identify terminal request. Not recommended.
RIS	ESC p 027 099 Reset to power-up state.
7-CIT	ESC SP P 027 040 070 Select 7-bit CJ control character transmission.

Table A-1. Escape Commands (Cont.)

Mnemonic	Escape Sequence Decimal Value
SBCIT	ESC 5P 0 027 040 074
	Gets a SBCIT control character transmission.

Table A-2. DECtalk Status Replies

Mnemonic	Escape Sequence Decimal Value
D1-DICT Reply	ESC P 0 0 0 0 P3 z ESC \ 027 040 040 050 052 040 050 102 027 102
	P3 parameters are as follows:
	0 Word entered correctly. 040
	1 No room in dictionary. 048
	2 Entry too long. 050
DA Priority Reply	ESC 1 2 3 9 c 027 001 063 040 067 089
	Reply from DECtalk to DA priority sequence.
D57-BCEI Replies	ESC 1 0 n 027 001 040 170
	No restrictions.
	ESC 1 3 n 027 001 051 170
	Restrictions applied.

Table A-2 DECtalk Status Replies (Cont)

Synonymic	Escape Sequence Decimal Value
DSR-Extended Replies	ESC [0 n ESC [? 2 1 n 027 091 048 110 027 091 063 050 049 110
	No malfunctions, first reply.
	ESC [0 n ESC [? 2 0 n 027 091 048 110 027 091 063 050 048 110
	No malfunctions, second or later reply.
	ESC [3 n ESC [? Pn ... Ph n 027 091 051 110 027 091 063 ... 059 ... 110
	Malfunction occurred. Pn parameter values are as follows:
	2 2 Communication failure 050 050
	2 3 Input buffer overflow. 050 051
	2 4 Last NVF operation failed. 050 052
	2 5 Error in program transcription. 050 053
	2 6 Error in DECtalk private control sequence. 050 054
	2 7 Last DECTST failed. 050 056
DT INDEX QUERY Reply	ESC [P 0 ... 2 2 1 P3 ... 2 ESC \ 027 090 048 050 051 066 062 ... 128 027 090
	P3 is the ASCII value of the last index spoken.
DT INDEX REPLY Reply	ESC [a 0 ... 3 1 1 P3 ... 2 ESC \ 027 090 048 050 051 049 050 ... 128 027 092
	Reply sent by DECtalk after speaking index of text. P3 is the ASCII value of the last index spoken.

Table A-3 DT MODE Parameters

Mnemonic	Value	Function
MODE_SQUARE	1	Set MODE_SQUARE on.
MODE_8KEY	2	Use the single-character shorthand syntax.
MODE_MINUTE	4	Speak hyphen as "minus".

Table A-4 DT TERMINAL Parameters

Mnemonic	Value	Function
TERM_HDST	1	Send all local terminal characters to dict 104.
TERM_SPEAK	2	Speak all characters typed on local terminal.
TERM_EDITED	4	Line edit all local terminal input.
TERM_HARD	8	Do local terminal editing to hardcopy format.
TERM_SETUP	16	Speak all characters when terminal is in set-up mode.
TERM_FILTER	32	Do not send DECtalk-specific escape sequences to the terminal.

Table A-5 DT_PHONE Parameters

Mnemonic	ASCII Code Decimal Value		Function
PH_STATUS	0 048		Send a telephone status report.
PH_ANSWER	1 049	0 048	Enable telephone autoanswer.
PH_HANGUP	1 049	1 049	Hang up the telephone and disable the keypad.
PH_KEYPAD	2 050	0 048	Enable the telephone keypad.
PH_NOKEYPAD	2 050	1 049	Disable the telephone keypad.
PH_TIMEOUT	3 051	0 048	Send telephone status message after n seconds (Chapter 4).
PH_TONE_DIAL	4 052	0 048	Dial the telephone by using Touch-Tone dialing.
PH_PULSE_DIAL	4 052	1 049	Dial the telephone by using pulse dialing.

Table A-6 DECTalk Parameters

Mnemonic	ASCII Code Decimal Value	Function
TEST_POWER	1 0x01	Return power-on tests.
TEST_HDATA	2 0x02	Run host port data loopback test.
TEST_HCONTROL	3 0x03	Run host port control loopback test.
TEST_LDATA	4 0x04	Run local port data loopback test.
TEST_SPEAK	5 0x05	Speak a built-in message.

Table A-7 DECTalk LOG Parameters

Mnemonic	Value	Function
LOG_TEXT	1	Speak all ASCII text.
LOG_PHONEME	2	Log all spoken text in phonemic format.
LOG_RAWHOST	4	Log all text read from the host on the local terminal.
LOG_INHOST	8	Log all text read from the host on the local terminal.
LOG_OUTHOST	16	Log all text sent to the host on the local terminal.
LOG_ERROR	32	Log all error messages on the terminal.
LOG_TRACE	64	Log all escape sequences as readable text on the local terminal.
LOG_DEBUG	128	Reserved for DECTalk internal use.

Table A-8 OT_MASK Parameters

Value	Bit	Character
1	0	0
2	1	1
4	2	2
8	3	3
16	4	4
32	5	5
64	6	6
128	7	7
256	8	8
512	9	8
1024	10	-
2048	11	#
4096	12	A
8192	13	X
16384	14	C
32768	15	U

PHONEMIC ALPHABET **B**

This appendix summarizes the phonemic symbols that DECtalk uses. DECtalk recognizes all 17 vowel phonemes and 24 consonant phonemes in the English language (Table B-1).

DECtalk uses two-character symbols for each English phoneme. DECtalk also recognizes a one-character system of representing phonemes. Use of the one-character system is discouraged, as it is not in wide use and may not be supported on future releases of DECtalk. However, DECtalk can be set to the one-character system. Refer to Chapter 4 of the *DECtalk DTC01 Owner's Manual*.

Table B-2 lists emphasis characters, for adding stress and suggesting proper phrasing (syntax).

Table B-1 Phonemic Inventory

2-Char. Symbol	1-Char. Symbol	Example	2-Char. Symbol	1-Char. Symbol	Example
Vowels					
ay	e	bake	ah	ʌ	but
aa	a	bat	aw	W	bow
iy	i	best	ya	Y	cube
eh	E	bet	rr	R	bed
ay	A	baa	ao	ɔ	bought
ih	I	bit	ae	æ	bat
oy	O	boy	oh	U	hook
aw	o	boat	ix	I	kisses
aw	u	boat	ax	x	about
ir		beer	er		beer
er		bar	or		born
ur		poor			
Consonants					
p	p	pet	b	b	bet
t	t	test	d	d	deb
k	k	ken	g	g	guess
f	f	fin	j	j	jest
th	T	thin	dh	D	whis
s	s	sit	z	z	zoo
sh	S	shin	zh	Z	azure
ch	C	chin	ph	J	gin
w	w	wet	th	m	met
yx	y	yet	n	n	net
nx	h	head	rx	G	sing
r	r	ret	en	N	burton
l	l	red			science
el	L	bottle			
em	M	kenshin			

Allophones (Override DECtalk internal values.)

rx	r	quadrant	postvocalic r
lx	l	electric	postvocalic l
q	q	we are	glottal stop [w'iy or tyt]
dx	d	rider	flapped d
tx	t	Latin	glottalized t

Table B-2 Phonemic Emphasis Markers

2-Character Symbol	1-Character Symbol	Meaning
<i>Stress and Syntax Phonemic Symbols</i>		
		Primary lexical stress
		Secondary lexical stress
		Emphatic stress
/	/	Pitch rise
\	\	Pitch fall
/\	/\	Pitch rise/fall
<i>Syntactic Structure Symbols</i>		
		Syllable boundary (dash)
		Morpheme boundary
#	#	Compound noun boundary
		Word boundary (space)
(	(	Beginning of relative clause
)	)	End relative clause, begin with phrase
		End of clause
		End of sentence
?	?	End of question
!	!	End of exclamation
~	~	Paragraph introducer

1. The first step is to identify the problem or question that needs to be addressed. This involves understanding the context and the specific requirements of the task.

DOCUMENTATION C

RELATED DOCUMENTATION

You can order the following DECtalk documents from Digital:

Title	Description
DECtalk DTC01 Owner's Manual (EK-DTC01-OM)	This manual gives an overview of DECtalk operations and a detailed description of DECtalk off-line (local) operations, phonemic codes, and spoken text conventions.
DECtalk DTC01 Programmer Reference Manual (EK-DTC01-RM)	This manual describes DECtalk-computer connections, DECtalk escape sequences, and programming methods for interfacing DECtalk with a host computer and telephone.
DECtalk DTC01 Programmer Reference Card (EK-DTC01-RC)	This card summarizes DECtalk phonemic codes, commands, and escape sequences.
DECtalk DTC01 Installation Manual (EK-DTC01-IN)	This manual explains how to install and operate DECtalk.

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